# Introduction to Supersymmetry $\left({ }^{1}\right)$ 

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## 1 Supersymmetry in Quantum Mechanics

### 1.1 The Supersymmetric Oscillator

As we will see later the "hermitian supercharges" $Q_{\alpha}^{i}$, in the $N$ extended SuperPoincaré Lie Algebra obey the anticommutation relations:

$$
\begin{equation*}
\left\{Q_{\alpha}^{i}, Q_{\beta}^{j}\right\}=2\left(\gamma^{m} C\right)_{\alpha \beta} \delta^{i j} P_{m} \tag{1.1}
\end{equation*}
$$

where $\alpha, \beta$ are "spinor" indices, $i, j \in\{1, \cdots, N\}$ "internal" indices and $\left(\gamma^{m} C\right)_{\alpha \beta}$ a bilinear form in the spinor indices $\alpha, \beta$.

When specialized to 0-space dimensions ( $(1+0)$-spacetime), then since $P_{0}=H$, relations (1.1) take the form (with a little change in notations):

$$
\begin{equation*}
\left\{Q_{i}, Q_{j}\right\}=2 \delta_{i j} H \tag{1.2}
\end{equation*}
$$

with $N$ "Hermitian charges" $Q_{i}, i=1, \cdots, N$. Let us see some imediate consequences of relations (1.2:

- The supercharges $Q_{i}$ are constants of motion. In fact:

$$
\begin{equation*}
[H, Q]=\left[Q^{2}, Q\right]=0 \tag{1.3}
\end{equation*}
$$

where $Q$ is any of the $Q_{i}$.

- The Hamiltonian $H$ is an hermitian positive operator, and so the energy spectrum is always positive definite. In fact:

$$
\begin{equation*}
H=Q_{1}^{2}=\cdots=Q_{N}^{2} \tag{1.4}
\end{equation*}
$$

So, $\forall|\psi\rangle \in \mathcal{H}$ we have:

$$
\langle\psi| H|\psi\rangle=\langle\psi| Q^{2}|\psi\rangle=\langle\psi| Q^{\dagger} Q|\psi\rangle=\| Q|\psi\rangle \|^{2} \geq 0
$$

where $Q$ is any of the $Q_{i}$. This also proves that:

$$
\begin{equation*}
\operatorname{ker} H=\cap_{i} \operatorname{ker} Q_{i} \tag{1.5}
\end{equation*}
$$

Since the Hamiltonian $H$ is a positive operator, any eigenstate $\mid \psi_{0}>$ of $H$ with zero eigenvalue is a "ground state", and for such a ground state we have that $Q_{i} \mid \psi_{0}>=\mathbf{0}, \forall i$. We then say that the "supersymmetry is unbroken". When there is no eigenstate with zero eigenvalue, then the ground state $\left|\psi_{0}\right\rangle$ has energy $E_{\psi_{0}}>0$. This implies that $Q\left|\psi_{0}\right\rangle \neq \mathbf{0}$ and we then say that we have "spontaneous susy breaking".

Now we focus our attention in the $N=2$ model, which we call the:

## "Supersymmetric Oscillator"

In this case let us define the following two "nonhermitian supercharges", adjoint of each other:

$$
\begin{array}{r}
S \\
\stackrel{\text { def }}{=}  \tag{1.6}\\
\bar{S}=S^{\dagger}= \\
\stackrel{1}{2}\left(Q_{1}+i Q_{2}\right) \\
\frac{\text { def }}{2}\left(Q_{1}-i Q_{2}\right)
\end{array}
$$

Then we have the following "representation" for the above ( $N=2$ )-Susy algebra:

$$
\begin{align*}
H=Q_{1}^{2}=Q_{2}^{2} & =\{S, \bar{S}\} \\
S^{2} & =\bar{S}^{2}=0 \tag{1.7}
\end{align*}
$$

We also have $[H, Q]=0$, where $Q$ is any of the $Q_{i}, S$ or $\bar{S}$.

Consider the Hilbert space $\mathcal{H}$ with basis:

$$
\begin{equation*}
\left|n_{B}, n_{F}\right\rangle \quad n_{B}=0,1,2, \cdots, \infty \quad n_{F}=0,1 \tag{1.8}
\end{equation*}
$$

where $n_{B}$ and $n_{F}$ are "boson" and "fermion occupation numbers" respectivelly, and let $a, a^{\dagger}$ "anihilation-creation" bosonic operators, and $f, f^{\dagger}$ "anihilation-creation" fermionic operators, acting on $\mathcal{H}$ in the standard way. They satisfy the following commutation and anticommutation relations:

$$
\begin{align*}
& {\left[a, a^{\dagger}\right]=1} \\
& \left\{f, f^{\dagger}\right\}=1 \\
& {[a, f]=0} \tag{1.9}
\end{align*} \quad f^{2}=\left(f^{\dagger}\right)^{2}=0
$$

Then if we put:

$$
\begin{array}{llll}
S & \stackrel{\text { def }}{ } & k a f^{\dagger} & \text { "destroy a boson } \otimes \text { create a fermion" } \\
\bar{S} & \stackrel{\text { def }}{=} & k a^{\dagger} f & \text { "create a boson } \otimes \text { destroy a fermion" } \tag{1.10}
\end{array}
$$

where $k$ is a constant so that $S$ and $\bar{S}$ are adjoints of each other ( $\bar{S}=S^{\dagger}$ ), we see that:

$$
\begin{align*}
& \left.S\left|n_{B}, n_{F}\right\rangle=k a f^{\dagger}\left|n_{B}, n_{F}>\propto\right| n_{B}-1, n_{F}+1\right\rangle \\
& \left.\bar{S}\left|n_{B}, n_{F}\right\rangle=k a^{\dagger} f\left|n_{B}, n_{F}>\propto\right| n_{B}+1, n_{F}-1\right\rangle \tag{1.11}
\end{align*}
$$

so that these operators convert a boson into a fermion and vice-versa. Moreover we can verify properties (1.7), using (1.9).

Now what about the Hamiltonian? We compute:

$$
\begin{align*}
H & =\{S, \bar{S}\} \\
& =k^{2}\left(a f^{\dagger} a^{\dagger} f+a^{\dagger} f a f^{\dagger}\right) \\
& =k^{2}\left(a^{\dagger} a+\frac{1}{2}\right)+k^{2}\left(f^{\dagger} f-\frac{1}{2}\right) \\
& \stackrel{\text { def }}{ } H_{B}+H_{F} \tag{1.12}
\end{align*}
$$

So the $H$ is the sum of two non-interacting terms: the Hamiltonian of the bosonic oscillator $H_{B}$ with energy spectrum $E_{B}$, and the Hamiltonian of the fermionic oscillator $H_{F}$ with energy spectrum $E_{F}$ given respectivelly by:

$$
\begin{array}{lll}
H_{B}=k^{2}\left(a^{\dagger} a+\frac{1}{2}\right) & E_{B}=k^{2}\left(n_{B}+\frac{1}{2}\right) & n_{B}=0,1,2,3, \cdots \\
H_{F}=k^{2}\left(f^{\dagger} f-\frac{1}{2}\right) & E_{F}=k^{2}\left(n_{F}-\frac{1}{2}\right) & n_{B}=0,1 \tag{1.13}
\end{array}
$$

Note that:

$$
n_{F}^{2}=f^{\dagger} f f^{\dagger} f=f^{\dagger}\left\{f, f^{\dagger}\right\} f=f^{\dagger} f=n_{F}
$$

and so in fact the eigenvalues of $n_{F}$ are 0,1 which is the "Pauli exclusion principle". Note also that the frequencies $\omega=k^{2}$ of these two oscillators are the same.

### 1.2 Witten Index

For the above $(N=2)$-Susy QM model, we can define an operator:

$$
(-1)^{F} \quad \stackrel{\text { def }}{=}(-1)^{n_{F}} \mathbb{1}
$$

such that:

$$
\begin{equation*}
\left\{(-1)^{F}, Q_{i}\right\}=0 \quad\left((-1)^{F}\right)^{2}=\mathbb{1} \quad\left((-1)^{F}\right)^{\dagger}=(-1)^{F} \tag{1.14}
\end{equation*}
$$

Converselly, given an Hilbert space $\mathcal{H}$ and hermitian operators $H, Q,(-1)^{F}$ such that $(-1)^{F}$ is bounded and:

$$
\begin{equation*}
H=Q^{2} \quad\left((-1)^{F}\right)^{2}=\mathbb{1} \quad\left\{Q,(-1)^{F}\right\}=0 \tag{1.15}
\end{equation*}
$$

we can define a ( $N=2$ )-Susy QM model by putting:

$$
Q_{1}=Q \quad \text { and } \quad Q_{2}=i(-1)^{F} Q
$$

We explore now the abstract data given by an Hilbert space $\mathcal{H}$ and hermitian operators $H, Q,(-1)^{F}$, with $(-1)^{F}$ bounded, and verifying conditions (1.15).

Here follows some properties of this "abstract Susy model", $\left\{H, Q,(-1)^{F}\right\}$, which are imediate consequences of conditions (1.15):

I •

$$
\begin{align*}
{\left[(-1)^{F}, H\right] } & =\left[(-1)^{F}, Q^{2}\right] \\
& =\left\{(-1)^{F}, Q\right\} Q-Q\left\{Q,(-1)^{F}\right\}=0 \tag{1.16}
\end{align*}
$$

II • We have a decomposition of $\mathcal{H}$ in eigenspaces of $(-1)^{F}$ corresponding to the eigenvalues $\pm$ :

$$
\mathcal{H}=\mathcal{H}_{b} \oplus \mathcal{H}_{f}
$$

with:

$$
\begin{align*}
\mathcal{H}_{b} & =\left\{\psi \in \mathcal{H}:(-1)^{F} \psi=+\psi\right\} \\
\mathcal{H}_{f} & =\left\{\psi \in \mathcal{H}:(-1)^{F} \psi=-\psi\right\} \tag{1.17}
\end{align*}
$$

so that $(-1)^{F}$ acts on $\mathcal{H}$ as:

$$
(-1)^{F}=\left[\begin{array}{cc}
\mathbb{1}_{b} & 0 \\
0 & -\mathbb{1}_{f}
\end{array}\right]
$$

III - The involution $(-1)^{F}$ induces also a decomposition on the algebra of operators acting on $\mathcal{H}$. If:

$$
K=\left[\begin{array}{ll}
A & B \\
C & D
\end{array}\right]
$$

acts on $\mathcal{H}=\mathcal{H}_{b} \oplus \mathcal{H}_{f}$, then:

- K is "bosonic" or "even" iff $\quad\left[(-1)^{F}, K\right]=0 \quad$ iff $\quad K=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$
- K is "fermionic" or "odd" iff $\quad\left\{(-1)^{F}, K\right\}=0 \quad$ iff $\quad K=\left[\begin{array}{cc}0 & B \\ C & 0\end{array}\right]$

IV - In particular, since $Q$ is hermitian and anticommutes with $(-1)^{F}$, we have that $Q$ is odd and:

$$
Q=\left[\begin{array}{cc}
0 & A^{\dagger}  \tag{1.18}\\
A & 0
\end{array}\right]
$$

So, applying $Q$ to a vector $\psi=\psi_{b} \oplus \psi_{f} \in \mathcal{H}$, we have:

$$
Q \psi=\left[\begin{array}{cc}
0 & A^{\dagger} \\
A & 0
\end{array}\right]\left[\begin{array}{l}
\psi_{b} \\
\psi_{f}
\end{array}\right]=\left[\begin{array}{c}
A^{\dagger} \psi_{f} \\
A \psi_{b}
\end{array}\right]
$$

and since this belongs to $\mathcal{H}_{b} \oplus \mathcal{H}_{f}$ we must have:

$$
\begin{array}{r}
Q\left\lfloor\mathcal{H}_{b}=A: \mathcal{H}_{b} \longrightarrow \mathcal{H}_{f}\right. \\
Q\left\lfloor\mathcal{H}_{f}=A^{\dagger}: \mathcal{H}_{f} \longrightarrow \mathcal{H}_{b}\right. \tag{1.19}
\end{array}
$$

Note also that:

$$
H=\left[\begin{array}{cc}
A^{\dagger} A & 0  \tag{1.20}\\
0 & A A^{\dagger}
\end{array}\right]
$$

V - Now we turn to the fundamental property of this Susy model. Let $\psi$ be an eigenvalue of $H$ with positive energy $E>0$ :

$$
H \psi=E \psi \quad E>0
$$

Then, as $[H, Q]=0$ we have:

$$
H(Q \psi)=Q(H \psi)=E(Q \psi)
$$

which means that $Q \psi$ is again an eigenvalue of $H$ with the same positive energy $E>0$. Note that if $E=0$ we can not apply this reasoning, since $H \psi=0$ implies that:

$$
0=\langle\psi| H|\psi\rangle=\langle\psi| Q^{2}|\psi\rangle=\langle\psi| Q^{\dagger} Q|\psi\rangle=\|Q \psi\|^{2}
$$

and so $Q \psi=\mathbf{0}$ which is not an eigenvector.
As we have seen, if $\psi \in \mathcal{H}_{b}$ (resp., $\mathcal{H}_{f}$ ) then $Q \psi \in \mathcal{H}_{f}$ (resp., $\mathcal{H}_{b}$ ) (we call $Q \psi$ the "superpartner" of $\psi$ ), and so we conclude that "all eigenstates with energy $E>0$ are paired":

$$
\begin{equation*}
\operatorname{dim} \operatorname{ker}\left[(H-E)\left\lfloor\mathcal{H}_{b}\right)\right]=\operatorname{dim} \operatorname{ker}\left[(H-E)\left\lfloor\mathcal{H}_{f}\right)\right] \quad \forall E>0 \tag{1.21}
\end{equation*}
$$



Here we have put:

$$
\begin{align*}
& N_{b}=\operatorname{dim} \operatorname{ker}\left(H\left\lfloor\mathcal{H}_{b}\right)\right. \\
& N_{f}=\operatorname{dim} \operatorname{ker}\left(H\left\lfloor\mathcal{H}_{f}\right)\right. \tag{1.22}
\end{align*}
$$

If either $N_{b}$ or $N_{f}$ are nonzero, then there exists a state of zero energy (a ground sate) and supersymmetry is unbroken. So if we can compute $N_{b}$ or $N_{f}$ we can decide about Susy breaking. In general this is a difficult problem, and the only thing available is the difference $N_{b}-N_{f}$.

Thus we define the "Witten index" as:

$$
\begin{equation*}
\Delta_{W}=N_{b}-N_{f} \tag{1.23}
\end{equation*}
$$

This has remarkable stability properties. In fact "small perturbations" of the system don't affect $\Delta_{W}$, since the states of non-zero energy move always in Bose-Fermi pairs.

Since $Q$ has the form (1.18), i.e., $Q=\left[\begin{array}{cc}0 & A^{\dagger} \\ A & 0\end{array}\right]$, with $A$ an elliptic operator, then by (1.19), we have that:

$$
\begin{align*}
\Delta_{W} & =N_{b}-N_{f} \\
& =\operatorname{dim} \operatorname{ker} A-\operatorname{dim} \operatorname{ker} A^{\dagger} \\
& =\operatorname{index}(A) \tag{1.24}
\end{align*}
$$

### 1.3 A fundamental example: The Laplacian on forms

Assume that $M$ is a compact oriented closed smooth $n$-dimensional Riemannian manifold, and let $\Omega^{k}(M)$ be the Hilbert space obtained by completion of the space of smooth $k$-forms, with respect to the usual inner product:

$$
<\alpha, \beta>=\int_{M} \alpha \wedge * \beta
$$

Now we construct an "abstract Susy model" $\left\{H, Q,(-1)^{F}\right\}$, on the Hilbert space:

$$
\begin{equation*}
\mathcal{H} \stackrel{\text { def }}{=} \oplus_{k=0}^{n} \Omega^{k}(M) \tag{1.25}
\end{equation*}
$$

by defining:

- $H=\Delta=d d^{*}+d^{*} d$, the operator closure of the usual laplacian on smooth forms.
- $(-1)^{F}\left\lfloor\Omega^{k}(M)=(-1)^{k} \mathbb{1}\right.$. Thus the bosonic-fermionic sectors of $\mathcal{H}$ are:

$$
\begin{align*}
& \mathcal{H}_{b}=\bigoplus_{k} \bigoplus_{k \text { even }} \Omega^{k}(M) \\
& \mathcal{H}_{f}=\bigoplus_{\text {odd }} \Omega^{k}(M) \tag{1.26}
\end{align*}
$$

- $Q=d+d^{*}$, where $d: \Omega^{k}(M) \rightarrow \Omega^{k+1}(M)$ is the operator closure of the usual differential on forms, and $d^{*}: \Omega^{k+1}(M) \rightarrow \Omega^{k}(M)$ its adjoint (codifferential).
So, with respect to the bosonic-fermionic grading of $\mathcal{H}, Q=\left[\begin{array}{cc}0 & d^{*} \\ d & 0\end{array}\right]$.
It's easy to see that conditions (1.15) hold, namelly:

$$
Q^{2}=\left(d+d^{*}\right)^{2}=\Delta \quad\left\{(-1)^{F}, Q\right\}=0 \quad\left((-1)^{F}\right)^{2}=\mathbb{1}
$$

Thus in particular, property (1.21) takes, in this case, the following form:

$$
\begin{equation*}
\left.\sum_{\{k} \text { even }\right\} \operatorname{dim} \operatorname{ker}\left((\Delta-E)\left\lfloor\Omega^{k}(M)\right)=\sum_{\{k} \text { odd }\right\} \operatorname{dim} \operatorname{ker}\left((\Delta-E)\left\lfloor\Omega^{k}(M)\right)\right. \tag{1.27}
\end{equation*}
$$

or equivallently:

$$
\begin{equation*}
\sum_{k=0}^{n} \operatorname{dim} \operatorname{ker}\left((\Delta-E)\left\lfloor\Omega^{k}(M)\right)=0\right. \tag{1.28}
\end{equation*}
$$

On the other hand, by Hodge theory, we know that:

$$
\begin{align*}
\operatorname{dim} \operatorname{ker}\left(\Delta\left\lfloor\Omega^{k}(M)\right)\right. & =\operatorname{dim} H^{k}(M) \\
& =b_{k}(M) \quad \text { the } k \text {-Betti number of } M \tag{1.29}
\end{align*}
$$

Recall also that the Euler characteristic of $M$ is:

$$
\chi(M)=\sum_{k=0}^{n}(-1)^{k} b_{k}(M)
$$

and that Poincaré duality asserts that:

$$
b_{k}(M)=b_{n-k}(M) \quad \forall k=0, \cdots, n
$$

### 1.4 Witten's proof of Morse Inequalities

Recall that a smooth function $f: M \rightarrow \mathbf{R}$ is called a "Morse function" if it has finitely many critical points and each critical point is nondegenerate. Then we can prove that around each critical point $p \in M$ it's possible to choose local coordinates $\left\{x_{i}: i=1, \cdots, n\right\}$, such that $f$ has the local expression:

$$
\begin{equation*}
f\left(x_{1}, \cdots, x_{n}\right)=f(p)-\underbrace{x_{1}^{2}-\cdots-x_{\mathbb{k}_{p}}^{2}}_{\mathbb{k}_{p} \text { terms }}+\underbrace{x_{\mathbb{k}_{p}+1}^{2}+\cdots+x_{n}^{2}}_{n-\mathbb{k}_{p} \text { terms }} \tag{1.30}
\end{equation*}
$$

where $\mathbb{k}_{p}$ is the index of the critical point $p$.
For a Morse function $f: M \rightarrow \mathbf{R}$, and for each integer $\mathbb{k}_{\mathbf{k}}=0,1, \cdots, n$, let:

$$
m_{\mathbb{k}}(f) \quad \stackrel{\text { def }}{=} \quad \text { number of critical points of } f \text { of index } \mathbb{k}
$$

Then we have the following theorem:

## Morse Theorem...

Let $M$ is a compact oriented closed smooth $n$-dimensional manifold, and $f: M \rightarrow \mathbf{R} a$ Morse function on $M$. Then we have:
(i). for each integer $\mathbb{k}=0,1, \cdots, n$, the "weak Morse inequalities":

$$
m_{\mathrm{lk}}(f) \geq b_{\mathrm{lk}}(M)
$$

(ii). for each integer $l=0,1, \cdots, n$, the "strong Morse inequalities":

Figure 1: Examples of critical points

$$
\sum_{\mathbb{k}=0}^{l}(-1)^{l-\mathbb{k}} m_{\mathrm{k}}(f) \geq \sum_{\mathrm{k}=0}^{l}(-1)^{l-\mathbb{l}_{k}} b_{\mathrm{l}_{\mathrm{k}}}(M)
$$

(iii). the "Morse index Theorem":

$$
\sum_{\mathbb{k}=0}^{n}(-1)^{\mathbb{k}} m_{\mathbb{k}}(f)=\sum_{\mathbb{k}=0}^{n}(-1)^{\mathbb{k}} b_{\mathbb{k}}(M)=\chi(M)
$$

Our aim now it's to explain the main ideas of Witten's proof of this theorem.

- The first thing it's to "deform" the abstract Susy model of the previous section: $\left\{H=\Delta, Q=d+d^{+},(-1)^{F}\right\}$, on the Hilbert space $\mathcal{H}=\oplus_{k=0}^{n} \Omega^{k}(M)$, by defining the $t$-dependent $(t \in \mathbf{R})$ abstract Susy model:

$$
\left\{H_{t}, Q_{t}=d_{t}+d_{t}^{*},(-1)^{F}\right\}
$$

again on the same $\mathcal{H}$, where:

$$
\begin{align*}
d_{t} & =e^{-t f} d e^{t f} \\
d_{t}^{*} & =e^{t f} d^{*} e^{-t f} \\
H_{t} & =d_{t} d_{t}^{*}+d_{t}^{*} d_{t} \tag{1.31}
\end{align*}
$$

and the same involution.
As $d_{t}$ is obtained from $d$, by conjugation with $e^{t f}$, the cohomology of $(\Omega(M), d)$ is the same as the cohomology of $\left(\Omega(M), d_{t}\right)$, and so $\operatorname{ker} \Delta \cong \operatorname{ker} H_{t}$, which implies for the Betti numbers that:

$$
b_{k}(M)=\operatorname{dim} \operatorname{ker}\left(H _ { t } \left\lfloor\Omega^{k}(M)\right.\right.
$$

- Now recall that on $\mathcal{H}=\Omega(M)$ we have, for each 1-form $\alpha \in \Omega^{1}(M)$, a pair of fermionic creation-anihilation (0-order) operators, given respectivelly by exterior multiplication:

$$
\varepsilon_{\alpha}: \omega \rightarrow \varepsilon_{\alpha}(\omega)=\alpha \wedge \omega \quad \omega \in \Omega(M)
$$

and interior multiplication (or contraction with $g(\cdot, \alpha)$ ):

$$
\iota_{\alpha}: \omega \rightarrow \iota_{\alpha}(\omega)=(-1)^{n k+n+1} *(\alpha \wedge * \omega) \quad \omega \in \Omega^{k}(M)
$$

We can prove that these operators are adjoint of each other, and that:

$$
\left\{\varepsilon_{\alpha}, \iota_{\beta}\right\}=g(\alpha, \beta)
$$

Now we have $\forall \omega \in \mathcal{H}$ :

$$
\begin{align*}
& d_{t} \omega=e^{-t f} d\left(e^{t f} \omega\right)=d \omega+t d f \wedge \omega=\left(d+t \varepsilon_{d f}\right)(\omega) \\
& d_{t}^{*} \omega=e^{t f} d^{*}\left(e^{-t f} \omega\right)=\left(d^{*}-t \iota_{d f}\right)(\omega) \tag{1.32}
\end{align*}
$$

and so:

$$
Q_{t}=d_{t}+d_{t}^{*}=d+d^{*}+t\left(\varepsilon_{d f}-\iota_{d f}\right)=Q+t B_{f}
$$

where $B_{f}$ is the endomorphism of the exterior bundle (i.e., a 0 -order operator) given by $\varepsilon_{d f}-\iota_{d f}$.

Now it's easy to see that $B_{f}^{2}$ is given by multiplication by $\|d f\|^{2}$, and that $\left\{Q, B_{f}\right\}$ is also a 0 -order operator, say $A_{f}$. Putting all this together we have that:

$$
\begin{equation*}
H_{t}=\Delta+t^{2}\|d f\|^{2}+t A_{f} \tag{1.33}
\end{equation*}
$$

In local orthonormal flat coordinates $x_{i}$ we have:

$$
\begin{align*}
H_{t} & =\Delta+t^{2}\left(\delta^{i j} \frac{\partial f}{\partial x_{i}} \frac{\partial f}{\partial x_{j}}\right)+t \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}\left[a_{i}^{*}, a_{j}\right]  \tag{1.34}\\
& \stackrel{\text { def }}{=} \Delta+V_{f}
\end{align*}
$$

where $a_{i}^{*}=\varepsilon_{d x_{i}}$ and $a_{i}=\iota_{d x_{i}}$.

- The above computation shows that $H_{t}$ is a Schrödinger type operator with potential $V_{f}$, which for large $t$ is dominated by the $t^{2}\|d f\|^{2}$ term. When $t \rightarrow \infty$ this potential is enormeous, except at the critical points of $f$ (where $d f$ vanishes), and so it looks like finitely many harmonic oscilators wells centered at each one of the critical points of $f$, and separated by large barriers.

Thus, assume that $p_{1}, \cdots, p_{s}$ are the critical points of $f$, each with index $p_{a}=\mathbb{k}_{a}, a=$ $1, \cdots, s$. Then locally, around each $p_{a}$, we can choose Morse coordinates $\left\{x_{i}\right\}$ where $f$ has the local expression (1.30). By stipulating that $d x_{1}, \cdots, d x_{n}$ are orthonormal we obtain a metric in some neighborhood of $p_{a}$, and the local expression of $H_{t}$ is, by (1.34):

$$
\begin{align*}
H_{t}^{(a)} & =-\Delta+4 t^{2}\left(\sum_{i=1}^{n} x_{i}^{2}\right)-2 t \sum_{i=1}^{\mathbb{k}_{a}}\left[a_{i}^{*}, a_{i}\right]+2 t \sum_{i=\mathbb{k}_{a}+1}^{n}\left[a_{i}^{*}, a_{i}\right] \\
& =-\Delta+4 t^{2} \mathbf{x}^{2}+2 t \sum_{i=1}^{n} \lambda_{i}\left[a_{i}^{*}, a_{i}\right] \tag{1.35}
\end{align*}
$$

$\left(\lambda_{i}=-1\right.$, if $i=1, \cdots, \mathbb{k}_{a}$, and $\lambda_{i}=+1$, if $\left.i=\mathbb{k}_{a}+1, \cdots, n\right)$, and where $\Delta$ acts on $k$-forms as follows:

$$
\Delta\left(h d x_{i_{1}} \wedge \cdots \wedge d x_{i_{k}}\right)=\sum_{i=1}^{n} \frac{\partial^{2} h}{\partial x_{i}^{2}} d x_{i_{1}} \wedge \cdots \wedge d x_{i_{k}}
$$

Since the critical points $p_{a}$ of $f$ are isolated, we can patch together such local metrics using a partition of unity, to obtain a metric on all $M$.

- Now we write (1.35), in the form:

$$
\begin{equation*}
H_{t}^{(a)}=\sum_{i=1}^{n}\left(-\frac{\partial^{2}}{\partial x_{i}^{2}}+4 t^{2} x_{i}^{2}+\lambda_{i}\left[a_{i}^{*}, a_{i}\right]\right) \tag{1.36}
\end{equation*}
$$

We see that each $-\frac{\partial^{2}}{\partial x_{i}^{2}}+4 t^{2} x_{i}^{2}$ is an harmonic oscillator of frequency $w=2 t$, which commutes with the 0 -order operator $\left[a_{i}^{*}, a_{i}\right]$, and so can be simultaneously diagonalized.

Therefore, the eigenvalues of $\sum_{i=1}^{n}\left(-\frac{\partial^{2}}{\partial x_{i}^{2}}+4 t^{2} x_{i}^{2}\right)$ are:

$$
2 t \sum_{i=1}^{n}\left(1+2 \mu_{i}\right) \quad \mu_{1}, \mu_{2}, \cdots, \mu_{n}=0,1,2, \cdots
$$

Each eigenform, is of type:

$$
\psi d x_{i_{1}} \wedge \cdots \wedge d x_{i_{k}} \quad 1 \leq i_{1}<i_{2}<\cdots<i_{n} \leq n
$$

where $\psi$ is an harmonic oscillator eigenfunction, and each of this eigenforms is also an eigenform of the 0 -order operator $\left[a_{i}^{*}, a_{i}\right]$, with eigenvalue +1 (if $i \in\left\{i_{1}, i_{2}, \cdots, i_{k}\right\}$ ) or -1 (if $\left.i \notin\left\{i_{1}, i_{2}, \cdots, i_{k}\right\}\right)$. So the spectrum of $H_{t}^{(a)}$ is:

$$
\begin{equation*}
\text { spect } H_{t}^{(a)}=\left\{2 t \sum_{i=1}^{n}\left(\left(1+2 \mu_{i}\right)+\lambda_{i} \epsilon_{i}\right): \quad \mu_{1}, \mu_{2}, \cdots, \mu_{n}=0,1,2, \cdots \quad \text { and } \quad \epsilon_{i}= \pm 1\right\} \tag{1.37}
\end{equation*}
$$

and when acting on $k$-forms the spectrum of $H_{t}^{(a)}$ is as above but with the additional restriction that exactly $k$ of the $\epsilon_{i}$ are equal to +1 .

- Now we want to make contact with Betti numbers, and so we will look for the multiplicity of the zero eigenvalue, of the restriction of $H_{t}^{(a)}$ to $k$-forms. By the above considerations we see that (since $\sum_{i=1}^{n} \lambda_{i} \epsilon_{i} \geq-n$ ) we will have zero eigenvalue iff $\mu_{i}=0, \forall i$ (and the corresponding eigenspace is the 1-dimensional ground state of the oscillator) and $\epsilon_{i}=-\operatorname{signal} \lambda_{i}$. Thus we must have exactly $\mathbb{k}_{a}=\operatorname{index} p_{a}$ of the $\epsilon_{i}$ equal to +1 , and so $\operatorname{dim} \operatorname{ker}\left(H_{t}^{(a)}\left\lfloor\Omega^{k}\right)=1\right.$ iff $k=\mathbb{k}_{a}=$ index $p_{a}$, which implies that:

$$
\operatorname{dim} \operatorname{ker}\left(\oplus_{a} H_{t}^{(a)}\left\lfloor\Omega^{k} M\right)=m_{k}\right.
$$

the number of critical points of index $k$.
But remember that we are working with an approximation! If this approximation was exact then we will have that $b_{k}=m_{k}$. Taking into account the approximation means that
some of the zero eigen- $k$-forms may disappear in an exact computation, and so we will have the weak Morse inequalities:

$$
b_{k}(M) \leq m_{k}(f)
$$

Of course this deserves a more rigourous argument!... (see [1], for this and also for the proof of the strong Morse inequalities and Morse index theorem).

## References

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## 2 Supergeometry and Supersymmetry

### 2.1 Field Theory. A quick review

- Actions. Euler equations

Fields $\varphi$ in a field theory are sections of a bundle $E \rightarrow M$, with fiber $F$, over a smooth manifold $M$. We call $F$ the target manifold and:

$$
\Phi=\{\text { space of fields, or "histories" }\}
$$

For example, In a scalar field theory $F$ is a linear space, in a spinor field theory $E \rightarrow M$ is a spin bundle, while in Yang-Mills with gauge group $G, E$ is an affine bundle whose sections are connections in some principal $G$-bundle over $M . M$ will be flat Minkowski spacetime, Euclidean space, a Riemann surface, etc....

The dynamics of fields is determined by an action functional $S: \Phi \rightarrow \mathbf{C}$ which in general is "local", i.e., is given by:

$$
\begin{equation*}
S[\varphi]=\int_{M} L[\varphi(x)] \quad x \in M \quad \varphi \in F \tag{2.1}
\end{equation*}
$$

where the Lagrangian density $L$ is a function of $\varphi(x)$ and a finite number of its derivatives.

## Example ... Scalar field theory or nonlinear $\sigma$-model theory

We take the trivial bundle $E=M \times F$, where $M$ is $D$-dimensional flat Minkowski spacetime or Euclidean space $\mathbf{R}^{D}$, with cartesian coordinates $x^{a}, a=1, \cdots, D$, and the target is a Riemannian manifold $\mathcal{M}$ with metric $G$ and local coordinates $\varphi^{I}$. The space of fields $\Phi$ is the space of smooth maps $\varphi=\left(\varphi^{1}, \cdots, \varphi^{d}\right): M \rightarrow F$ for which the action:

$$
\begin{align*}
S[\varphi] & =-\frac{1}{2} \int_{M} d^{D}(\mathbf{x})\|d \varphi\|^{2} \\
& =-\frac{1}{2} \int_{M} d^{D} \mathbf{x} G_{I J}(\varphi) \partial^{a} \varphi^{I} \partial_{a} \varphi^{J} \quad \partial_{a}=\frac{\partial}{\partial x^{a}}, \quad a=1, \cdots, D \tag{2.2}
\end{align*}
$$

is finite.
Of particular importance will be $\sigma$-models on complex manifolds $\mathcal{M}$ of real dimension $d=2 n$, with local real coordinates $\varphi^{I}, I=1, \cdots, 2 n$. Choose local complex coordinates $w^{i}, i=1, \cdots, n$, such that:

$$
\varphi^{i}=\operatorname{Re} w^{i}=\frac{1}{2}\left(w^{i}+\bar{w}^{i}\right) \quad \quad \varphi^{i+n}=\operatorname{Im} w^{i}=\frac{1}{2 i}\left(w^{i}-\bar{w}^{i}\right)
$$

If the metric $G$ is Hermitian, then:

$$
G=2 G_{i \bar{j}} d w^{i} d \bar{w}^{j} \quad G_{j \bar{i}}=\left(G_{i \bar{j}}\right)^{*}
$$

and the action (2.2) is rewritten in the form:

$$
\begin{equation*}
S[w, \bar{w}]=-\int_{M} d^{D} \mathbf{x} \quad G_{i \bar{j}}(w, \bar{w}) \partial^{a} \bar{w}^{j} \partial_{a} w^{i} \tag{2.3}
\end{equation*}
$$

## Example ... Bosonic string theory

Here $M=\Sigma_{h}$ a Riemann surface of genus $h$ with local smooth coordinates $\sigma^{a}, a=1,2$. The space of fields $\Phi$ is the space:

$$
\Phi=\operatorname{Emb}\left(\Sigma_{h}, \mathbf{R}^{d}\right) \times \operatorname{Met}\left(\Sigma_{h}\right)
$$

where $\operatorname{Emb}\left(\Sigma_{h}, \mathbf{R}^{d}\right)$ is the space of smooth embeddings $\varphi: \Sigma_{h} \rightarrow \mathbf{R}^{d}$, of $\Sigma_{h}$ into $d$-dimensional flat Minkowski spacetime $\mathbf{R}^{d}$, with cartesian coordinates $X^{i}, i=1, \cdots, d, \operatorname{Met}\left(\Sigma_{h}\right)$ is the space of Riemannin metrics $g$ on $\Sigma_{h}$, and the action is the Polyakov action:

$$
\begin{align*}
S[\varphi, g] & =\int_{\Sigma_{h}} d \mu_{g}\|d \varphi\|^{2} \\
& =\int_{\Sigma_{h}} d^{2} \sigma \sqrt{g} g_{a b}(\sigma) \partial^{a} \varphi^{i} \partial^{b} \varphi_{i} \quad \partial_{a}=\frac{\partial}{\partial \sigma^{a}}, \quad a=1,2 \tag{2.4}
\end{align*}
$$

with $\varphi^{i}=X^{i} \circ \varphi$.

The action functional (2.1) determines the dynamical field equations or Euler equations:

$$
\begin{equation*}
\frac{\delta S[\varphi]}{\delta \varphi^{i}(x)}=0 \tag{2.5}
\end{equation*}
$$

where the functional derivatives are defined by:

$$
\delta S[\varphi]=S[\varphi+\delta \varphi]-S[\varphi]=\int_{M} \delta \varphi^{i}(x) \frac{\delta S[\varphi]}{\delta \varphi^{i}(x)}
$$

with $\delta \varphi^{i}(x) \in T_{\varphi} \Phi$ are arbitrary field variations.
Every solution of Euler equations is called a dynamical field history, and the set of all those solutions forms a subset $\Phi_{o} \subseteq \Phi$ called the dynamical subspace or "mass shell surface":

$$
\Phi_{o}=\left\{\varphi \in \Phi: \frac{\delta S[\varphi]}{\delta \varphi^{i}(x)}=0\right\}
$$

## Example ... Scalar field theory or nonlinear $\sigma$-model theory

The Euler equations corresponding to the action (2.2) are:

$$
\begin{equation*}
\frac{\delta S[\varphi]}{\delta \varphi^{i}}=\partial^{a} \partial_{a} \varphi^{i}+\Gamma_{j k}^{i} \partial^{a} \varphi^{j} \partial_{a} \varphi^{k}=0 \quad i=1, \cdots, d \tag{2.6}
\end{equation*}
$$

where $\Gamma_{j k}^{i}$ is the Levi-Civita connection of the metric $G$ on $F=\mathbf{R}^{d}$. Solutions $\varphi$ of (2.6) are called harmonic maps because they satisfy a generalized Laplace equation.

## Example ... Bosonic string theory

The Euler equations corresponding to the action (2.4) are:

$$
\begin{align*}
\frac{\delta S[\varphi]}{\delta g_{a b}} & \equiv T^{a b}=0 \\
\frac{\delta S[\varphi]}{\delta \varphi^{i}} & =0 \quad i=1, \cdots, d \tag{2.7}
\end{align*}
$$

We can combine the above two models in a "string $\sigma$-model", by considering the following generalized harmonic map problem. We take a Riemannian manifold ( $M, G$ ) (the target space), a sympletic form $B$ on $M$ (the $B$-field), and the action:

$$
\begin{equation*}
S[\varphi, g]=\int_{\Sigma}\left(d \mu_{g}\|d \varphi\|^{2}+\varphi^{*} B\right)+\frac{1}{8 \pi} \int_{\Sigma} \Psi \cdot s_{g} \tag{2.8}
\end{equation*}
$$

where $g$ is an arbitrary riemannian metric on a Riemann surface $\Sigma$ (the worlsheet), $s_{g}$ is the scalar curvature of $g$, and $\Psi$ is a scalar field (the "dilaton") on $\Sigma$.

- Symmetries

In general one considers action functionals that are invariant under some symmetry group. More preciselly we have an action of a (Lie) group $G$ on the space of fields $\Phi$ :

$$
(g, \varphi) \mapsto g \cdot \varphi
$$

and we have that:

$$
S[\varphi]=S[g \cdot \varphi] \quad \forall g \in G
$$

Traditionally we consider the infinitesimal (derived) action of the Lie algebra $\mathfrak{g}$ on $\Phi$, given through the differential of the "orbital map" $\eta_{\varphi}: G \rightarrow \Phi\left(\right.$ defined by $\left.\eta_{\varphi}(g)=g \cdot \varphi\right)$ :

$$
d \eta_{\varphi}: \mathfrak{g} \longrightarrow T_{\varphi} \Phi
$$

with:

$$
d \eta_{\varphi}(\xi)=\left.\frac{d}{d t}\right|_{t=0} e^{t \xi} \cdot \varphi \equiv \delta_{\xi \varphi} \in T_{\varphi} \Phi
$$

## Example ... Relativistic field theory

In the case of a field theory in Minkowski space, the Poincaré group $\mathcal{P}=\operatorname{ISO}(1,3)$ is assumed to act on the space of fields $\Phi$, by means of spacetime symmetries, i.e., a symmetry of the base space $M$, represented in $\Phi$ by:

$$
(g, \varphi) \mapsto g \cdot \varphi(\mathbf{x}) \equiv \varphi\left(g^{-1} \mathbf{x}\right)
$$

For example, translations in a flat spacetime can be written as:

$$
\delta_{\xi} \varphi=-\xi^{a} \partial_{a} \varphi \in T_{\varphi} \Phi
$$

When the "mass shell surface" $\Phi_{o} \subseteq \Phi$ is $\mathcal{P}$-invariant:

$$
\frac{\delta S[\varphi]}{\delta \varphi^{i}(x)}=0 \Longrightarrow \frac{\delta S[g \cdot \varphi]}{\delta \varphi^{i}(x)}=0 \quad \forall g \in \mathcal{P}
$$

then we say that we have a relativistic field theory. This will be the case if for example the action functional is a scalar with respect to $\mathcal{P}: S[\varphi]=S[g \cdot \varphi]$.

In contrast to the above spacetime symmetries, we have the internal symmetries which act on $\varphi \in \Phi$ at each point of $M$, i.e., acts without spacetime derivatives. For example a $U(1)$-algebra acts on a complex field $\varphi$ as:

$$
\delta_{\lambda} \varphi=i \lambda \varphi
$$

When the transformation prameters are constant over $M$, like the above $\xi^{a}$ or $\lambda$, we say that the symmetry is global or rigid. When they are functions over $M, \lambda=\lambda(\mathbf{x})$, then the symmetry is called local, like for example, gauge transformations on Yang-Mills fields. Sometimes it is possible to promote a global symmetry to a local one. The prescription to do this is called gauging the symmetry.

The commutator of two infinitesimal symmetries is a symmetry and so they form a Lie algebra in general infinite dimensional. Sometimes an infinite dimensional symmetry algebra acts as a finite dimensional algebra on the dynamical fields $\varphi \in \Phi_{o}$. In this case we say that we have an on shell representation of that algebra.

## Example ... Nonlinear $\sigma$-model

The symmetries of the action (2.2) are of two types: The spacetime ones are the isometries of flat Minkowski spacetime $M$, i.e., the Poincaré group $\mathcal{P}$. The internal symmetries are the isometries of the target $(F, G)$. These are global symmetries generated by Killing vector fields of $F$ :

$$
\left(\delta_{X} \varphi\right)(\mathbf{x})=\left(X^{A} K_{A}\right)(\varphi(\mathbf{x}))
$$

where $K_{A}=k_{A}^{i} \partial_{i}$ is a basis for the Lie algebra of the isometry group of $F$.

## Example ... String theory

The symmetries of the Polyakov action (2.4) are:

- translations in $\mathbf{R}^{d}$ :

$$
S\left[\varphi^{i}+c^{i}, g\right]=S[\varphi, g] \quad \forall c^{i} \in \mathbf{R}^{d}
$$

- the group of (orientation preserving) diffeomorphisms: $\operatorname{Diff} f^{+}\left(\Sigma_{h}\right)$ :

$$
S\left[f^{*} \varphi, f^{*} g\right]=S[\varphi, g] \quad \forall f \in \operatorname{Diff}^{+}\left(\Sigma_{h}\right)
$$

- the group of conformal (pointwise) rescallings of the metric: $C^{\infty}\left(\Sigma_{h}, \mathbf{R}\right)$ :

$$
S\left[\varphi, e^{\lambda} g\right]=S[\varphi, g] \quad \forall \lambda \in C^{\infty}\left(\Sigma_{h}, \mathbf{R}\right)
$$

So if we quotient these symmetries, we see that the action functional is defined in the so called moduli space $\mathcal{M}$ :

$$
\mathcal{M}=\frac{\operatorname{Emb}\left(\Sigma_{h}, \mathbf{R}^{d}\right) \times \operatorname{Met}\left(\Sigma_{h}\right)}{\mathbf{R}^{d} \times \operatorname{Diff} f^{+}\left(\Sigma_{h}\right) \times C^{\infty}\left(\Sigma_{h}, \mathbf{R}\right)}
$$

### 2.2 SuperEuclidean Space

Consider the ( $\mathbf{Z}_{2}$-graded) supercommutative, associative, with unit element $\mathbb{1}$, complex "Grassmann algebra" $\Lambda=\Lambda_{L}=\wedge \mathbf{C}^{L}$ :

$$
\Lambda=\Lambda_{L}=\Lambda_{0} \oplus \Lambda_{1}
$$

with a finite number (sufficiently large, eventually $L=\infty, \ldots$ ) of generators $\left\{\mathbb{1}, \zeta_{k}: k=\right.$ $1,2, \cdots, L\}$, and with a normed topology (such that $\Lambda \cong \mathbf{C}^{2 L}$ ). We have for homogeneous elements:

$$
\alpha \beta=(-1)^{|\alpha||\beta|} \beta \alpha \quad \alpha, \beta \in \Lambda
$$

where the notation $|\alpha|$ means "grassmann parity", equal to 0 if $\alpha \in \Lambda_{0}$ and equal to 1 if $\alpha \in \Lambda_{1}$. In particular, elements in $\Lambda_{0}$ commute ( $\Lambda_{0}$ is a commutative subalgebra of $\Lambda$ ) and elements in $\Lambda_{1}$ anticommute. Thus we call the elements in $\Lambda_{0}$, "c-numbers" and the elements in $\Lambda_{1}$ "a-numbers", and we put:

$$
\mathbf{C}_{c}=\Lambda_{0} \quad \mathbf{C}_{a}=\Lambda_{1}
$$

Every element $\mathbf{z} \in \Lambda$ splits as:

$$
\mathbf{z}=z_{b}+\mathbf{z}_{s} \in \mathbf{C} \oplus \Lambda_{s}
$$

where $z_{b} \in \mathbf{C}$ is the "body" and $\mathbf{z}_{s}=\mathbf{z}-z_{b} \in \Lambda_{s}$ is the "soul" of $\mathbf{z}$ (its nilpotent part, because $\mathbf{z}_{s}^{N}=0$ if $N>L$ ).

We define the "SuperEuclidean space" $\mathbf{C}^{m \mid n}$ of "even dimension" $m$ and "odd dimension" $n$, by:

$$
\begin{equation*}
\mathbf{C}^{m \mid n}=\left(\mathbf{C}_{c}\right)^{m} \times\left(\mathbf{C}_{a}\right)^{n} \tag{2.9}
\end{equation*}
$$

with a normed topology (so that $\mathbf{C}^{m \mid n} \cong \mathbf{C}^{(m+n) 2^{L-1}}$ ), and denote an element of $\mathbf{C}^{m \mid n}$ by $(\mathrm{x} ; \Theta)$, with:

$$
\begin{array}{ll}
\mathbf{x}=\left(\mathbf{x}^{i}\right)=\left(\mathbf{x}^{1}, \cdots, \mathbf{x}^{m}\right) & \mathbf{x}^{i} \in \mathbf{C}_{a} \quad i=1, \cdots, m \\
\Theta=\left(\theta^{\alpha}\right)=\left(\theta^{1}, \cdots, \theta^{n}\right) & \theta^{\alpha} \in \mathbf{C}_{a} \quad \alpha=1, \cdots, n \tag{2.10}
\end{array}
$$

$\left(\mathbf{x}^{1}, \cdots, \mathbf{x}^{m}\right)$ are called "bosonic coordinates" and $\left(\theta^{1}, \cdots, \theta^{n}\right)$ "fermionic coordinates". The "body" of $(\mathbf{x} ; \Theta) \in \mathbf{R}^{m \mid n}$ is by definition $\mathbf{x}_{b}=\left(x_{b}^{1}, \cdots, x_{b}^{m}\right) \in \mathbf{C}^{m}$, and this defines the "body projection":

$$
b: \mathbf{C}^{m \mid n} \longrightarrow \mathbf{C}^{m}
$$

which is a continuous open surjective map.

### 2.3 Reality Conditions

We define an involution * on $\Lambda$, which we call "complex conjugation", as follows:

$$
\begin{align*}
\zeta_{k}^{*} & =\zeta_{k} \quad k=1, \cdots, L \\
(\alpha \mathbf{z})^{*} & =\bar{\alpha} \mathbf{z}^{*} \quad \forall \alpha \in \mathbf{C} \quad \forall \mathbf{z} \in \Lambda \\
(\mathbf{z}+\mathbf{w})^{*} & =\mathbf{z}^{*}+\mathbf{w}^{*} \quad \forall \mathbf{z}, \mathbf{w} \in \Lambda \\
(\mathbf{z w})^{*} & =\mathbf{w}^{*} \mathbf{z}^{*} \quad \forall \mathbf{z}, \mathbf{w} \in \Lambda \tag{2.11}
\end{align*}
$$

An element $\mathbf{z} \in \Lambda$ is called "real" if $\mathbf{z}^{*}=\mathbf{z}$, and "imaginary" if $\mathbf{z}^{*}=-\mathbf{z}$. The set of real elements in $\mathbf{C}_{c}$ (the real c-numbers), form a real commutative subalgebra in $\Lambda$, which is denoted by $\mathbf{R}_{c}$. The set of real elements in $\mathbf{C}_{a}$ (the real $a$-numbers) is denoted by $\mathbf{R}_{a}$. Note that the product of a real $c$-number and a real $a$-number is a real $a$-number, and finally the product of two real $a$-numbers is a bodiless imaginary $c$-number:

$$
\mathbf{R}_{c} \cdot \mathbf{R}_{c} \subseteq \mathbf{R}_{c} \quad \mathbf{R}_{c} \cdot \mathbf{R}_{a} \subseteq \mathbf{R}_{a} \quad \mathbf{R}_{a} \cdot \mathbf{R}_{a} \subseteq i \mathbf{R}_{a}
$$

The "real SuperEuclidean space" $\mathbf{R}^{m \mid n}$ of "even dimension" $m$ and"odd dimension" $n$, is defined by:

$$
\begin{equation*}
\mathbf{R}^{m \mid n}=\left(\mathbf{R}_{c}\right)^{m} \times\left(\mathbf{R}_{a}\right)^{n} \tag{2.12}
\end{equation*}
$$

### 2.4 Supersmooth functions

Given a smooth $\left(C^{\infty}\right) \Lambda$-valued function $f$ in an open set of $U \subseteq \mathbf{R}^{m}$ :

$$
f: U \subseteq \mathbf{R}^{m} \longrightarrow \Lambda
$$

we define its "Grassmann analytic continuation":

$$
Z f: b^{-1}(U) \cap \mathbf{R}_{c}^{m} \longrightarrow \Lambda
$$

by the following (finite) Taylor expansion:

$$
\begin{align*}
Z f\left(\mathbf{x}^{1}, \cdots, \mathbf{x}^{m}\right) & =Z f\left(x_{b}^{1}+\mathbf{x}_{s}^{1}, \cdots, x_{b}^{m}+\mathbf{x}_{s}^{m}\right) \\
& =\sum_{j_{1}, \cdots, j_{k}} \frac{1}{j_{1}!\cdots j_{k}!} \frac{\partial^{j_{1}+\cdots+j_{k}} f}{\partial x_{b}^{j_{1}} \cdots \partial x_{b}^{j_{k}}}\left(x_{b}^{1}, \cdots, x_{b}^{m}\right)\left(\mathbf{x}_{s}^{1}\right)^{j_{1}} \cdots\left(\mathbf{x}_{s}^{m}\right)^{j_{k}} \\
& =\sum_{J} \frac{1}{J!} \frac{\partial^{|J|} f}{\partial x_{b}^{J}}\left(\mathbf{x}_{b}\right) \mathbf{x}_{s}^{J} \tag{2.13}
\end{align*}
$$

where in the last line we have used multiindice notation: $J=\left(j_{1}, \cdots, j_{k}\right), J!=j_{1}!\cdots j_{k}$ !, $\mathbf{x}_{b}=\left(x_{b}^{1}, \cdots, x_{b}^{m}\right),|J|=j_{1}+\cdots+j_{k}$, and $\mathbf{x}_{s}^{J}=\left(\mathbf{x}_{s}^{1}\right)^{j_{1}} \cdots\left(\mathbf{x}_{s}^{m}\right)^{j_{k}}$.

Now we define a $\left(H^{\infty}\right)$, or "supersmooth function" $\Phi$ in (an open set of) $\mathbf{R}^{m \mid n}$ as a $\Lambda$-valued function of the form:

$$
\begin{align*}
\Phi(\mathbf{x} ; \Theta) & =\Phi\left(\mathbf{x}^{1}, \cdots, \mathbf{x}^{m} ; \theta^{1}, \cdots, \theta^{n}\right) \\
& =\sum_{\alpha} \phi_{\alpha}(\mathbf{x}) \Theta^{\alpha} \\
& \stackrel{\text { def }}{=} \sum_{\alpha=\left\{\alpha_{1}<\cdots<\alpha_{k}\right\}} Z f_{\alpha}(\mathbf{x}) \Theta^{\alpha} \\
& =\sum_{\alpha} Z f_{\alpha_{1}, \cdots, \alpha_{k}}\left(\mathbf{x}^{1}, \cdots, \mathbf{x}^{m}\right) \theta^{\alpha_{1}} \cdots \theta^{\alpha_{k}} \tag{2.14}
\end{align*}
$$

where each"component function" $\phi_{\alpha}=Z f_{\alpha}$ is a $\Lambda$-valued function of the form (2.13), which depends only on the bosonic coordinates $\mathbf{x} \in\left(\mathbf{R}_{c}\right)^{m} \cong \mathbf{R}^{m \mid 0}$. Note that the above expansion (2.14) contains only a finite number of terms.

We denote by $\mathcal{S F}\left(\mathbf{R}^{m \mid n}\right)$ the algebra of supersmooth functions on $\mathbf{R}^{m \mid n}$. This is a $\mathbf{Z}_{2^{-}}$ graded supercommutative algebra: $\mathcal{S F}=\mathcal{S F}^{+} \oplus \mathcal{S F}^{-}$, where $\mathcal{S F}^{+}$are the $\mathbf{C}_{c}$-valued, or "even supersmooth functions", and $\mathcal{S F}^{-}$the $\mathbf{C}_{a}$-valued, or "odd supersmooth functions".

## Examples ...

(i). An even supersmooth function on $\mathbf{R}^{1 \mid 1}$ is of the form:

$$
\Phi(\mathbf{t}, \theta)=\phi(\mathbf{t})+\psi(\mathbf{t}) \theta \quad \mathbf{t} \in \mathbf{R}_{c} \quad \theta \in \mathbf{R}_{a}
$$

with $\phi: \mathbf{R}^{1 \mid 0} \cong \mathbf{R}_{c} \rightarrow \mathbf{R}_{c}$ and $\psi: \mathbf{R}^{1 \mid 0} \cong \mathbf{R}_{c} \rightarrow \mathbf{R}_{a}$ obtained by $Z$-extension: $\phi=Z f$ and $\psi=Z g$.
(ii). In $\mathbf{R}^{2 \mid 2}$, which we can think as the superspace extension of 2-dimensional Minkowski space-time $\mathbf{R}_{(1,1)}$, we consider the coordinates ( $\mathbf{x}^{1}, \mathbf{x}^{2} ; \theta^{1}, \theta^{2}$ ). In supersymmetric field theories we must think of $\theta^{1}, \theta^{2}$ as coordinates with respect to a basis $\left\{\mathbf{Q}_{1}, \mathbf{Q}_{2}\right\}$ of the space $\mathcal{S}$ of (Majorana) $\operatorname{Spin}(1)$-spinors, in such a way that the pair $\left(\theta^{1}, \theta^{2}\right)$ describes a spinor of $\mathbf{R}_{(1,1)}$, with (real) $a$ number coefficients.

An "even superfield" is an even supersmooth function of the form:

$$
\Phi\left(\mathbf{x}^{1}, \mathbf{x}^{2} ; \theta^{1}, \theta^{2}\right)=\phi_{o}\left(\mathbf{x}^{1}, \mathbf{x}^{2}\right)+\phi_{1}\left(\mathbf{x}^{1}, \mathbf{x}^{2}\right) \theta^{1}+\phi_{2}\left(\mathbf{x}^{1}, \mathbf{x}^{2}\right) \theta^{2}+\phi_{12}\left(\mathbf{x}^{1}, \mathbf{x}^{2}\right) \theta^{1} \theta^{2}
$$

where $\phi_{o}=Z f_{o}$ is an even function, called the "bosonic component" of $\Phi, \phi_{1}=Z f_{1}, \phi_{2}=Z f_{2}$ are odd functions (of spinorial character) called the "fermionic components" of $\Phi$, and $\phi_{12}=Z f_{12}=$ $-\phi_{21}$, is even and must be viewed as a section of $\wedge^{2} S$.

Consider two superfields $\Phi=\sum_{\alpha} \phi_{\alpha}(\mathbf{x}) \Theta^{\alpha} \in \mathcal{S} \mathcal{F}, \Psi=\sum_{\alpha} \psi_{\beta}(\mathbf{x}) \Theta^{\beta} \in \mathcal{S} \mathcal{F}$ and assume that $\phi_{\alpha}=Z f_{\alpha}, \psi_{\beta}=Z g_{\beta}$.

We define for each $i=1, \cdots, m$ :

$$
\begin{align*}
\frac{\partial \Phi}{\partial \mathbf{x}^{i}}(\mathbf{x} ; \Theta) & =\sum_{\alpha} \frac{\partial \phi_{\alpha}}{\partial \mathbf{x}^{i}}(\mathbf{x}) \Theta^{\alpha} \\
& =\sum_{\alpha} \frac{\partial\left(Z f_{\alpha}\right)}{\partial \mathbf{x}^{i}}(\mathbf{x}) \Theta^{\alpha} \\
& =\sum_{\alpha} Z\left(\frac{\partial f_{\alpha}}{\partial x_{b}^{i}}\right)(\mathbf{x}) \Theta^{\alpha} \tag{2.15}
\end{align*}
$$

where $\frac{\partial \phi_{\alpha}}{\partial \mathbf{x}^{i}}(\mathbf{x})$ is the Grassmann analytic continuation of $\frac{\partial f_{\alpha}}{\partial x_{b}^{i}}\left(x_{b}^{i}\right.$ is the body of $\left.\mathbf{x}^{i}\right)$. Then $\frac{\partial}{\partial \mathbf{x}^{i}}$ is an "even derivation" on $\mathcal{S F}$ :

$$
\begin{align*}
\frac{\partial(\Phi+\Psi)}{\partial \mathbf{x}^{i}} & =\frac{\partial \Phi}{\partial \mathbf{x}^{i}}+\frac{\partial \Psi}{\partial \mathbf{x}^{i}} \\
\frac{\partial(\lambda \Phi)}{\partial \mathbf{x}^{i}} & =\lambda \frac{\partial \Phi}{\partial \mathbf{x}^{i}} \quad \forall \lambda \in \mathbf{R} \\
\frac{\partial(\Phi \Psi)}{\partial \mathbf{x}^{i}} & =\frac{\partial \Phi}{\partial \mathbf{x}^{i}} \Psi+\Phi \frac{\partial \Psi}{\partial \mathbf{x}^{i}} \tag{2.16}
\end{align*}
$$

Now, for each $\alpha=1, \cdots, n$, we define $\frac{\partial}{\partial \theta^{\alpha}}$, by putting:

$$
\frac{\partial}{\partial \theta^{\alpha}} \theta^{\beta}=\delta_{\alpha}^{\beta}
$$

and extending this to all $\mathcal{S F}$ as an odd derivation, so that:

$$
\begin{align*}
\frac{\partial(\Phi+\Psi)}{\partial \theta^{\alpha}} & =\frac{\partial \Phi}{\partial \theta^{\alpha}}+\frac{\partial \Psi}{\partial \theta^{\alpha}} \\
\frac{\partial(\lambda \Phi)}{\partial \theta^{\alpha}} & =\lambda \frac{\partial \Phi}{\partial \theta^{\alpha}} \quad \forall \lambda \in \mathbf{R} \\
\frac{\partial(\Phi \Psi)}{\partial \theta^{\alpha}} & =\frac{\partial \Phi}{\partial \theta^{\alpha}} \Psi+(-1)^{\Phi} \Phi \frac{\partial \Psi}{\partial \theta^{\alpha}} \tag{2.17}
\end{align*}
$$

for homogeneous $\Phi$. We can prove that:

$$
\begin{align*}
{\left[\frac{\partial}{\partial \mathbf{x}^{i}}, \frac{\partial}{\partial \mathbf{x}^{j}}\right] } & =0 \\
{\left[\frac{\partial}{\partial \mathbf{x}^{i}}, \frac{\partial}{\partial \theta^{\alpha}}\right] } & =0 \\
\left\{\frac{\partial}{\partial \theta^{\alpha}}, \frac{\partial}{\partial \theta^{\beta}}\right\} & =0 \quad \alpha \neq \beta \tag{2.18}
\end{align*}
$$

Consider the graded vector space:

$$
\begin{equation*}
\mathbf{R}\left\{\frac{\partial}{\partial \mathbf{x}^{i}}\right\} \oplus \mathbf{R}\left\{\frac{\partial}{\partial \theta^{\alpha}}\right\} \tag{2.19}
\end{equation*}
$$

and let us tensor it with the graded module $\mathcal{S F}^{+} \oplus \mathcal{S F}^{-}$. Then we obtain the graded module of "supervector fields" on $\mathbf{R}^{m \mid n}$ :

$$
\mathfrak{X}\left(\mathbf{R}^{m \mid n}\right)=\mathfrak{X}^{+}\left(\mathbf{R}^{m \mid n}\right) \oplus \mathfrak{X}^{-}\left(\mathbf{R}^{m \mid n}\right)
$$

where:

$$
\begin{equation*}
\mathfrak{X}^{+}\left(\mathbf{R}^{m \mid n}\right)=\mathcal{S} \mathcal{F}^{+}\left\{\frac{\partial}{\partial \mathbf{x}^{i}}\right\} \oplus \mathcal{S} \mathcal{F}^{-}\left\{\frac{\partial}{\partial \theta^{\alpha}}\right\} \tag{2.20}
\end{equation*}
$$

consists of the "even supervector fields", and:

$$
\begin{equation*}
\mathfrak{X}^{-}\left(\mathbf{R}^{m \mid n}\right)=\mathcal{S F} \mathcal{F}^{-}\left\{\frac{\partial}{\partial \mathbf{x}^{i}}\right\} \oplus \mathcal{S F} \mathcal{F}^{+}\left\{\frac{\partial}{\partial \theta^{\alpha}}\right\} \tag{2.21}
\end{equation*}
$$

consists of the "odd supervector fields".

## Example ...

In $\mathbf{R}^{1 \mid 1}$ the supervector field $\mathbf{D}=\frac{\partial}{\partial \theta}-\theta \frac{\partial}{\partial \mathrm{t}}$ is odd, and satisfy $\mathbf{D}^{2}=-\frac{\partial}{\partial \mathrm{t}}$.

### 2.5 Supermanifolds

A $\left(H^{\infty}\right)$ "Supermanifold $\mathcal{M}^{m \mid n}$, of dimension $(m \mid n)$ ", is an Hausdorff, paracompact topological space $\mathcal{M}$, locally modelled on $\mathbf{R}^{(m \mid n)}$, with supersmooth transition functions.

Note that every ordinary $m$-dimensional manifold $M$, can be extended to a (bosonic) supermanifold $\mathcal{M}^{m \mid 0}=Z M^{m \mid 0}$, by replacing each open set of $M$ homeomorphic to an open set $U \subset \mathbf{R}^{m}$, by the open set $b^{-1}(U) \subset \mathbf{R}_{c}^{m} \cong \mathbf{R}^{m \mid 0}$, and taking as transition functions between two such open sets the $Z$-expansion (2.13), of the transition functions of the corresponding open sets in $\mathbf{R}^{m}$.

### 2.6 Lie Superalgebras

A "Lie Superalgebra" is a $\mathbf{Z}_{2}$-graded (real or complex) vector space:

$$
\mathfrak{G}=\mathfrak{g}_{0} \oplus \mathfrak{g}_{1}
$$

where:
(i). $\mathfrak{g}_{0}$ is a Lie algebra.
(ii). $\mathfrak{g}_{1}$ is a $\mathfrak{g}_{0}$-module, i.e., the carrier space of a representation of the Lie algebra $\mathfrak{g}_{0}$.
(iii). $\mathfrak{G}$ is endowed with a graded Lie bracket defined by the following conditions:

- This graded Lie bracket when restricted to $\mathfrak{g}_{0}$, is the same as the Lie bracket defined in the Lie algebra $\mathfrak{g}_{0}$. Thus, $\forall X, Y, Z \in \mathfrak{g}_{0}$ :

$$
\begin{gather*}
{[X, Y]=-[Y, X]}  \tag{2.22}\\
{[X,[Y, Z]]=[[X, Y], Z]+[Y,[X, Z]]} \tag{2.23}
\end{gather*}
$$

(i.e., $[X, \cdot]=a d_{X}$ is an even derivation on $\mathfrak{g}_{0}$.)

- For an element $X \in \mathfrak{g}_{0}$ and $\psi \in \mathfrak{g}_{1}$ :

$$
\begin{equation*}
[X, \psi] \equiv-[\psi, X]=X \cdot \psi \in \mathfrak{g}_{1} \tag{2.24}
\end{equation*}
$$

is the element of $\mathfrak{g}_{1}$ given by the $\mathfrak{g}_{0}$-action on $\mathfrak{g}_{1}$. Thus, $\forall X, Y \in \mathfrak{g}_{0}, \forall \psi \in \mathfrak{g}_{1}$ :

$$
\begin{equation*}
[[X, Y], \psi]=[X, Y] \cdot \psi=X \cdot(Y \cdot \psi)-Y \cdot(X \cdot \psi)=[X,[Y, \psi]]-[Y,[X, \psi]] \tag{2.25}
\end{equation*}
$$

- The graded Lie bracket when restricted to $\mathfrak{g}_{1}$, is given by a bilinear symmetric mapping:

$$
\{\cdot, \cdot\}: \mathfrak{g}_{1} \times \mathfrak{g}_{1} \longrightarrow \mathfrak{g}_{0}
$$

that behaves like an anticommutator:

$$
\begin{equation*}
[\phi, \psi] \equiv\{\phi, \psi\}=\{\psi, \phi\} \quad \forall \phi, \psi \in \mathfrak{g}_{1} \tag{2.26}
\end{equation*}
$$

Moreover we must have the following Jacobi identities:

$$
\begin{align*}
{[X,\{\phi, \psi\}] } & =\{[X, \phi], \psi\}+\{\phi,[X, \psi]\}  \tag{2.27}\\
{[\{\phi, \psi\}, \eta] } & =\{\phi, \psi\} \cdot \eta \\
& =-\{\phi, \eta\} \cdot \psi-\{\psi, \eta\} \cdot \phi \\
& =[\psi,\{\phi, \eta\}]+[\phi,\{\psi, \eta\}] \tag{2.28}
\end{align*}
$$

$\forall \phi, \psi, \eta \in \mathfrak{g}_{1}, \forall X \in \mathfrak{g}_{0}$.

We can put (2.22),(2.24) and (2.26) in the short form

$$
[A, B]=(-1)^{|A||B|+1}[B, A]
$$

and the Jacobi identities (2.23), (2.25), (2.27) and (2.28) in the form:

$$
(-1)^{|A||C|}[A,[B, C]]+(-1)^{|B||A|}[B,[C, A]]+(-1)^{|C \|||B|}[C,[A, B]]=0
$$

for homogeneous elements $A, B, C \in \mathfrak{G}$.
If $\left\{\mathbf{t}_{a} ; \mathbf{T}_{\alpha}\right\}, a=1, \cdots, m ; \alpha=1, \cdots, n$, is a linear basis for $\mathfrak{G}=\mathfrak{g}_{0} \oplus \mathfrak{g}_{1}$, then the structure constants of $\mathfrak{G}$ are:

- $C_{a b}^{c}$ - the structure constants of the Lie algebra $\mathfrak{g}_{0}$.
- $C_{a \alpha}^{\beta}$ - where $C_{a}=\left(C_{a \alpha}^{\beta}\right),(a=1, \cdots, m)$, are $n \times n$-matrices which satisfy the relations of the Lie algebra $\mathfrak{g}_{0}$ and generates one of its representations.
- $C_{\alpha \beta}^{a}$ are symmetric (in the indices $\alpha, \beta$ ) structure constants, which verifies certain constraints imposed by Jacobi identities.


## Example ...

Given a $\mathbf{Z}_{2}$ graded vector space $\mathcal{V}=\mathcal{V}^{+} \oplus \mathcal{V}^{-}$then $\operatorname{End}(\mathcal{V})$ is a Lie superalgebra, defining the gradation $\operatorname{End}(\mathcal{V})=\operatorname{End}^{+}(\mathcal{V}) \oplus \operatorname{End}^{-}(\mathcal{V})$, by:

$$
\begin{align*}
& \operatorname{End}^{+}(\mathcal{V})=\operatorname{Hom}\left(\mathcal{V}^{+}, \mathcal{V}^{+}\right) \oplus \operatorname{Hom}\left(\mathcal{V}^{-}, \mathcal{V}^{-}\right) \\
& \operatorname{End} d^{+}(\mathcal{V})=\operatorname{Hom}\left(\mathcal{V}^{+}, \mathcal{V}^{-}\right) \oplus \operatorname{Hom}\left(\mathcal{V}^{-}, \mathcal{V}^{+}\right) \tag{2.29}
\end{align*}
$$

and the graded bracket as the "supercommutator":

$$
[A, B]=A B-(-1)^{|A||B|} B A
$$

for homogeneous elements of $\operatorname{End}(\mathcal{V})$. In terms of a graded basis $\left\{\mathbf{e}_{a} ; \mathbf{e}_{\alpha}\right\}, a=1, \cdots, m ; \alpha=$ $1, \cdots, n$, for $\mathcal{V}=\mathcal{V}^{+} \oplus \mathcal{V}^{-}, E n d^{+}(\mathcal{V})$ is represented by "even supermatrices":

$$
\left[\begin{array}{cc}
\mathrm{A} & 0  \tag{2.30}\\
0 & \mathrm{D}
\end{array}\right]
$$

while $\operatorname{End}^{-}(\mathcal{V})$ is represented by "odd supermatrices":

$$
\left[\begin{array}{ll}
0 & B  \tag{2.31}\\
\mathrm{C} & 0
\end{array}\right]
$$

## Example ...

The algebra $\mathcal{M}_{\mathbf{k}}(m ; n)$ of $(\mathbf{k}=\mathbf{R}, \mathbf{C}, \mathbf{H})$ matrices of the form:

$$
\mathbf{M}=\left[\begin{array}{ll}
\mathbf{A} & \mathbf{B}  \tag{2.32}\\
\mathbf{C} & \mathbf{D}
\end{array}\right]
$$

with even part given by even supermatrices of type (2.30), odd part given by odd supermatrices of type (2.31), and graded bracket the corresponding supercommutator.

For a supermatrix M, of type (2.32) we define its "supertrace" str M, by:

$$
\operatorname{str} \mathbf{M}=\operatorname{tr} \mathbf{A}-\operatorname{tr} \mathbf{D}
$$

Then the subset of $\mathcal{M}_{\mathbf{k}}(m ; n)$ of all matrices $\mathbf{M}$ with $\operatorname{str} \mathbf{M}=0$ is a Lie subsuperalgebra, denoted by $\mathfrak{s l}_{\mathbf{k}}(m ; n)$.

## Example ... The Orthosympletic algebras $\mathfrak{o s p}(2 p ; N)$

Consider a $\mathbf{Z}_{2}$ graded real vector space $\mathcal{V}=\mathcal{V}^{+} \oplus \mathcal{V}^{-}$, of dimension $(m=2 p ; N)$, and assume that we give a sympletic linear form $\Omega$ on $\mathcal{V}^{+}$, and a positive definite inner product $G$ on $\mathcal{V}^{-}$. We can always choose a graded basis $\left\{\mathbf{e}_{a} ; \mathbf{e}_{\alpha}\right\}, a=1, \cdots, m=2 p ; \alpha=1, \cdots, N$ such that the matrices of $\Omega$ and $G$ satisfy:

$$
\Omega^{2}=-\mathbb{1} \quad \Omega^{T}=-\Omega \quad \mathbf{G}^{T}=\mathbf{G}
$$

Now we consider the supermatrix:

$$
\mathbf{K}=\left[\begin{array}{ll}
\Omega & \mathbf{0} \\
\mathbf{0} & \mathbf{G}
\end{array}\right]
$$

and the subset of $\mathcal{M}_{\mathbf{R}}(2 p ; N)$ of all supermatrices $\mathbf{M}$ which verify:

$$
\begin{equation*}
\mathbf{M}^{s T} \mathbf{K}+(-1)^{\| M \mid} \mathbf{K M}=\mathbf{0} \tag{2.33}
\end{equation*}
$$

where the "supertranspose" $\mathbf{M}^{s T}$, of $\mathbf{M}$ is defined by:

$$
\mathbf{M}^{s T}=\left[\begin{array}{ll}
\mathbf{A} & \mathbf{B} \\
\mathbf{C} & \mathbf{D}
\end{array}\right]^{s T}=\left[\begin{array}{cc}
\mathbf{A}^{T} & (-1)^{||M|} \mathbf{C}^{T} \\
(-1)^{|\mathbf{M}|+1} \mathbf{B}^{T} & \mathbf{D}^{T}
\end{array}\right]
$$

Working the definitions, we see that if $\mathbf{M}=\left[\begin{array}{cc}\mathbf{A} & \mathbf{0} \\ \mathbf{0} & \mathbf{D}\end{array}\right]$ is even, then (2.33), says that:

$$
\mathbf{A}^{T} \Omega+\Omega \mathbf{A}=\mathbf{0} \quad \mathbf{D}^{T} \mathbf{G}=\mathbf{G D}
$$

i.e., $\mathbf{A}$ is sympletic and $\mathbf{D}$ is orthogonal. Thus the even part of $\mathfrak{o s p}(2 p ; N)$ is the Lie algebra:

$$
\mathfrak{g}_{0}=\mathfrak{s p}(2 p) \oplus \mathfrak{s o}(N)
$$

If $\mathbf{M}=\left[\begin{array}{cc}\mathbf{0} & \mathbf{B} \\ \mathbf{C} & \mathbf{0}\end{array}\right]$ is odd, then (2.33), says that:

$$
\mathbf{B}=\Omega \mathbf{C}^{T} \mathbf{G}
$$

## Example ... $\quad(N=1, D=2)$-Poincaré Lie Superalgebra $\mathcal{S P}(1 ; 2)$

Let us begin with the construction of the " $(N=1, D=2)$-Poincaré Lie Superalgebra". Consider the Poincaré Lie algebra on ( $D=2$ )-dimensional Minkowski spacetime $\mathbf{R}_{(1,1)}$, with metric $\eta_{a b}$ of signature $(-,+)$, and cartesian coordinates $\left(x^{0}=c t, x^{1}\right), c=1$ :

$$
\mathfrak{g}_{0}=\mathfrak{s o}(1,1) \oslash \mathbf{R}^{2}
$$

the semi-direct sum of the Lorentz Lie algebra $\mathfrak{s o}(1,1)$ with its 2 -dimensional vectorial representation space $\mathbf{R}^{2}$. The Lie bracket in $\mathfrak{s o}(1,1) \oslash \mathbf{R}^{2}$ is given by:

$$
\begin{equation*}
\left[\left(\Lambda_{1}, \mathbf{x}_{1}\right),\left(\Lambda_{2}, \mathbf{x}_{2}\right)\right]=\left(\left[\Lambda_{1}, \Lambda_{2}\right], \Lambda_{1} \mathbf{x}_{2}-\Lambda_{2} \mathbf{x}_{1}\right) \tag{2.34}
\end{equation*}
$$

Now we choose for the odd part $\mathfrak{g}_{1}$ of our Lie superalgebra, the carrier space of the spinor representation of $\mathfrak{s o}(1,1)$. Recall how this is constructed.

We begin with the Clifford algebra $\mathcal{F}=C l_{(1,1)}$ of Minkowski spacetime $\mathbf{R}_{(1,1)}$, i.e., the $2^{2}$ dimensional real algebra generated by $\mathbb{1}$ and $\mathbf{R}^{2}$, subject to the relations:

$$
\mathbf{x y}+\mathbf{y x}=-2 \eta(\mathbf{x}, \mathbf{y}) \mathbb{1} \quad \forall \mathbf{x}, \mathbf{y} \in \mathbf{R}^{2}
$$

$\mathcal{F}=C l_{(1,1)}$ has a 2 -dimensional real (Majorana) representation linearly generated by:

$$
\mathbb{1}=\left[\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right] \quad \gamma^{0}=\sigma_{2}=\left[\begin{array}{cc}
0 & -i \\
i & 0
\end{array}\right] \quad \gamma^{1}=i \sigma_{1}=\left[\begin{array}{cc}
0 & i \\
i & 0
\end{array}\right] \quad \mathcal{W}=\gamma^{0} \gamma^{1}=\left[\begin{array}{cc}
+1 & 0 \\
0 & -1
\end{array}\right]
$$

where $\gamma^{m}, m=0,1$, are the "gamma matrices" and $\mathcal{W}=\gamma^{0} \gamma^{1}$ is the "Chiral (or Weyl) operator". Note that $\mathcal{W}^{2}=\mathbb{1}$, and that $\left\{\mathcal{W}, \gamma^{m}\right\}=0$.

Now we know that $\mathfrak{s o}(1,1) \cong \mathcal{F}_{2}=\mathbf{R}\left\{\mathcal{W}=\gamma^{0} \gamma^{1}\right\}$, and so is 1 -dimensional. Denote its generator by $\Lambda_{01}=\frac{1}{2} \gamma^{0} \gamma^{1}$. Since $\left[\mathcal{W}, \Lambda_{01}\right]=0$, we see that this representation is Majorana-Weyl (or Chiral), and the spinor space $\mathfrak{g}_{1}=\mathbf{R}^{2}$ splits into a direct sum:

$$
\mathfrak{g}_{1}=\mathbf{R}^{2}=\mathbf{R}_{l} \oplus \mathbf{R}_{r}
$$

corresponding to the eigenspaces of $\mathcal{W}$ associated to its eigenvalues $\pm 1$, respectivelly. Elements of $\mathbf{R}_{l}$ are called left spinors and elements of $\mathbf{R}_{r}$ right spinors.

Thus, the Chiral representation of $\mathfrak{s o}(1,1)$ reduces to the direct sum of two irreducible 1dimensional representations $\Gamma=\Gamma_{l} \oplus \Gamma_{r}$, whose action on the spinor space is given by:

$$
\left[\begin{array}{c}
\theta^{1} \\
\theta^{2}
\end{array}\right] \xrightarrow{\Gamma} \frac{1}{2}\left[\begin{array}{cc}
+1 & 0 \\
0 & -1
\end{array}\right]\left[\begin{array}{c}
\theta^{1} \\
\theta^{2}
\end{array}\right]=\left[\begin{array}{c}
+\frac{1}{2} \theta^{1} \\
-\frac{1}{2} \theta^{2}
\end{array}\right]
$$

where $\theta^{\alpha}$ are coordinates with respect to a basis $\left\{\mathbf{Q}_{\alpha}\right\}_{\alpha=1,2}$ for $\mathfrak{g}_{1}$.
These $\mathbf{Q}_{\alpha}$ are called "spinor charges", "supercharges", or "supersymmetric generators".
So for the moment we have defined the Lie superbracket on $\mathfrak{g}_{0}=\mathfrak{s o}(1,1) \oslash \mathbf{R}^{2}$ by (2.34), so that, if $\left\{\Lambda_{01}, \mathbf{P}_{0}, \mathbf{P}_{1}\right\}$ is a basis for $\mathfrak{g}_{0}$, then:

$$
\left[\Lambda_{01}, \mathbf{P}_{a}\right]=0=\left[\mathbf{P}_{a}, \mathbf{P}_{b}\right]
$$

Now we define, according to the previous discussion:

$$
\left[\Lambda_{01}, \mathbf{Q}_{1}\right]=+\frac{1}{2} \mathbf{Q}_{1} \quad\left[\Lambda_{01}, \mathbf{Q}_{2}\right]=-\frac{1}{2} \mathbf{Q}_{2} \quad\left[\mathbf{P}_{a}, \mathbf{Q}_{\alpha}\right]=0
$$

Finally we must define the anticommutator $\left\{\mathbf{Q}_{\alpha}, \mathbf{Q}_{\beta}\right\}$ of two spinor charges. General considerations (based on the constraints imposed by Jacobi identities, together with the previous definitions) show that $\left\{\mathbf{Q}_{\alpha}, \mathbf{Q}_{\beta}\right\}$ must be a linear combination only of the linear momentum basis $\mathbf{P}_{a}$. So we must construct a vector with a symmetric combination of two spinors. Usually this is achieved by defining (if possible) a "charge conjugation" matrix C, which in this particular case (where we are using the Majorana-Weyl representation) is given by:

$$
\mathbf{C}=-\sigma_{2}=\left[\begin{array}{cc}
0 & i \\
-i & 0
\end{array}\right]
$$

and verifies:

- $\mathbf{C}$ is antisymmetric.
- The matrices $\gamma^{m} \mathbf{C}$ are real and symmetric. In fact in this case $\gamma^{0} \mathbf{C}=-\mathbb{1}=\left[\begin{array}{cc}-1 & 0 \\ 0 & -1\end{array}\right]$ and $\gamma^{1} \mathbf{C}=\sigma_{3}=\left[\begin{array}{cc}+1 & 0 \\ 0 & -1\end{array}\right]$.

Now we define:

$$
\begin{equation*}
\left\{\mathbf{Q}_{\alpha}, \mathbf{Q}_{\beta}\right\}=-\sum_{m=0}^{1}\left(\gamma^{m} \mathbf{C}\right)_{\alpha \beta} \mathbf{P}_{m} \quad \alpha, \beta=1,2 \tag{2.35}
\end{equation*}
$$

In this case we have:

$$
\left\{\mathbf{Q}_{1}, \mathbf{Q}_{1}\right\}=\mathbf{P}_{0}-\mathbf{P}_{1} \quad\left\{\mathbf{Q}_{2}, \mathbf{Q}_{2}\right\}=\mathbf{P}_{0}+\mathbf{P}_{1} \quad\left\{\mathbf{Q}_{1}, \mathbf{Q}_{2}\right\}=0
$$

Our Lie superalgebra, "the ( $N=1, D=2$ )-Poincaré superalgebra":

$$
\mathcal{S P}(1 ; 2)=\left(\mathfrak{s o}(1,1) \oslash \mathbf{R}^{2}\right) \oplus \mathcal{S}
$$

has real graded dimension (3|2), with basis $\left\{\Lambda_{10}, \mathbf{P}_{0}, \mathbf{P}_{1} ; \mathbf{Q}_{1}, \mathbf{Q}_{2}\right\}$.

## Example … $\quad(N=2, D=2)$-Poincaré Lie Superalgebra $\mathcal{S P}(2 ; 2)$

Here we simply add to the odd part of the Lie superalgebra $\mathcal{S} \mathcal{P}(1 ; 2)$, another spinor space $\mathcal{S}^{\prime}$ with a corresponding basis $\left\{\mathbf{Q}_{1}^{\prime}, \mathbf{Q}_{2}^{\prime}\right\}$ of spinor charges, such that:

$$
\begin{align*}
\left\{\mathbf{Q}_{\alpha}^{\prime}, \mathbf{Q}_{\beta}^{\prime}\right\} & =-\sum_{m=0}^{1}\left(\gamma^{m} \mathbf{C}\right)_{\alpha \beta} \mathbf{P}_{m} \\
\left\{\mathbf{Q}_{\alpha}, \mathbf{Q}_{\beta}^{\prime}\right\} & =0 \quad \alpha, \beta=1,2 \tag{2.36}
\end{align*}
$$

Thus we put:

$$
\mathcal{S P}(2 ; 2)=\left(\mathfrak{s o}(1,1) \oslash \mathbf{R}^{2}\right) \oplus\left(\mathcal{S} \oplus \mathcal{S}^{\prime}\right)
$$

with real graded dimension (3|4) and basis $\left\{\Lambda_{10}, \mathbf{P}_{0}, \mathbf{P}_{1} ; \mathbf{Q}_{1}, \mathbf{Q}_{2}, \mathbf{Q}_{1}^{\prime}, \mathbf{Q}_{2}^{\prime}\right\}$.

### 2.7 Super Lie groups

Given a Lie superalgebra $\mathfrak{G}=\mathfrak{g}_{0} \oplus \mathfrak{g}_{1}$, with linear basis $\left\{\mathbf{t}_{a} ; \mathbf{T}_{\alpha}\right\}, a=1, \cdots, m ; \alpha=1, \cdots, n$, we consider the ordinary $2^{L-1}(m+n)$-dimensional complex Lie algebra, given by the even part of $\Lambda \otimes \mathfrak{G}$, i.e:

$$
\mathfrak{G}_{\Lambda} \stackrel{\text { def }}{=} \mathbf{C}_{c} \otimes \mathfrak{g}_{0} \oplus \mathbf{C}_{a} \otimes \mathfrak{g}_{1}
$$

with Lie brackett:

$$
\begin{align*}
& {\left[\mathbf{x}^{a} \mathbf{t}_{a}+\theta^{\alpha} \mathbf{T}_{\alpha}, \mathbf{y}^{b} \mathbf{t}_{b}+\eta^{\beta} \mathbf{T}_{\beta}\right]=} \\
& \quad \mathbf{x}^{a} \mathbf{y}^{b}\left[\mathbf{t}_{a}, \mathbf{t}_{b}\right]+\mathbf{x}_{a} \eta^{\beta}\left[\mathbf{t}_{a}, \mathbf{T}_{\beta}\right]+\theta^{\alpha} \mathbf{y}^{b}\left[\mathbf{T}_{\alpha}, \mathbf{t}_{b}\right]-\theta^{\alpha} \eta^{\beta}\left\{\mathbf{T}_{\alpha}, \mathbf{T}_{\beta}\right\}= \\
& \quad \mathbf{x}^{a} \mathbf{y}^{b}\left[\mathbf{t}_{a}, \mathbf{t}_{b}\right]+\left(\mathbf{x}_{a} \eta^{\beta}-\mathbf{y}^{a} \theta^{\beta}\right)\left[\mathbf{t}_{a}, \mathbf{T}_{\beta}\right]-\theta^{\alpha} \eta^{\beta}\left\{\mathbf{T}_{\alpha}, \mathbf{T}_{\beta}\right\} \tag{2.37}
\end{align*}
$$

We call $\mathfrak{G}_{\Lambda}$ the "Grassmann shell" of the Lie superalgebra $\mathfrak{G}$. The associated (connected and simply connected) Lie group:

$$
\mathbf{G}=\exp \mathfrak{G}_{\Lambda}
$$

has a natural supermanifold structure and a group structure, obtained via Campbell-Haussdorff formula:

$$
\begin{equation*}
e^{a} e^{b}=e^{\left(a+b+\frac{1}{2}[a, b]+\frac{1}{12}[a,[a, b]]+\frac{1}{12}[b,[b, a]]+\cdots\right)} \tag{2.38}
\end{equation*}
$$

which we call the "Super Lie group" associated with $\mathfrak{G}$. Elements of $\mathbf{G}$ take the form:

$$
\exp \left(\mathbf{x}^{a} \mathbf{t}_{a}+\theta^{\alpha} \mathbf{T}_{\alpha}\right) \quad \mathbf{x}^{a} \in \mathbf{C}_{c}, \theta^{\alpha} \in \mathbf{C}_{a}
$$

## Example ... Super-Poincaré group $\mathbf{S P}(1 ; 2)$

The Grassmann shell of the $(N=1, D=2)$-Poincaré superalgebra $\mathcal{S P}(1 ; 2)=\left(\mathfrak{s o}(1,1) \oslash \mathbf{R}^{2}\right) \oplus$ $\mathcal{S}$, with real graded dimension (3|2), and basis $\left\{\Lambda_{10}, \mathbf{P}_{0}, \mathbf{P}_{1} ; \mathbf{Q}_{1}, \mathbf{Q}_{2}\right\}$, has the form:

$$
\mathcal{S P}(1 ; 2)_{\Lambda}=\left\{\lambda^{01} \Lambda_{01}+\mathbf{x}^{0} \mathbf{P}_{0}+\mathbf{x}^{1} \mathbf{P}_{1}+\theta^{1} \mathbf{Q}_{1}+\theta^{2} \mathbf{Q}_{2}: \quad \lambda^{10}, \mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2} \in\left(\mathbf{R}_{c}\right)^{3} \times\left(\mathbf{R}_{a}\right)^{2}\right\}
$$

endowed with the Lie brackett (2.37).
Note that $\mathcal{S P}(1 ; 2)_{\Lambda}$ is the semi-direct sum of two subalgebras:

$$
\mathfrak{s o}(1,1)_{\Lambda} \stackrel{\text { def }}{=}\left\{\lambda^{01} \Lambda_{01}: \lambda^{01} \in \mathbf{R}_{c}\right\}
$$

and the "supersymmetric algebra":

$$
\mathfrak{m} \stackrel{\text { def }}{=}\left\{\mathbf{x}^{0} \mathbf{P}_{0}+\mathbf{x}^{1} \mathbf{P}_{1}+\theta^{1} \mathbf{Q}_{1}+\theta^{2} \mathbf{Q}_{2}: \quad \mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2} \in\left(\mathbf{R}_{c}\right)^{2} \times\left(\mathbf{R}_{a}\right)^{2}\right\}
$$

i.e.:

$$
\begin{equation*}
\left[\mathfrak{s o}(1,1)_{\Lambda}, \mathfrak{s o}(1,1)_{\Lambda}\right] \subseteq \mathfrak{s o}(1,1)_{\Lambda} \quad[\mathfrak{m}, \mathfrak{m}] \subseteq \mathfrak{m} \quad\left[\mathfrak{s o}(1,1)_{\Lambda}, \mathfrak{m}\right] \subseteq \mathfrak{m} \tag{2.39}
\end{equation*}
$$

By definition, the elements of the Super-Poincaré group:

$$
\mathbf{S P}(1 ; 2) \stackrel{\text { def }}{=} \exp \mathcal{S P}(1 ; 2)_{\Lambda}
$$

are of the form:

$$
\begin{equation*}
\mathbf{g}\left(\lambda^{01}, \mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2}\right)=\exp \left(\lambda^{01} \Lambda_{01}+\mathbf{x}^{0} \mathbf{P}_{0}+\mathbf{x}^{1} \mathbf{P}_{1}+\theta^{1} \mathbf{Q}_{1}+\theta^{2} \mathbf{Q}_{2}\right) \tag{2.40}
\end{equation*}
$$

with $\left(\lambda^{10}, \mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2}\right) \in\left(\mathbf{R}_{c}\right)^{3} \times\left(\mathbf{R}_{a}\right)^{2}=\mathbf{R}^{3 \mid 2}$.

### 2.8 Rigid Superspace

We first recall some geometrical properties of homogeneous spaces. Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$, and $H$ a closed subgroup with Lie algebra $\mathfrak{h}$. $H$ acts on the right on $G$ by right translations, and as we know, $G$ has a structure of $H$-principal fiber bundle over the homogeneous space of $H$-left cosets $G / H$ :

$$
\begin{gathered}
G \\
\pi \downarrow \\
G / H
\end{gathered}
$$

$G$ acts on itself by left translations $L_{g}: k \rightarrow g k$, and this induces a left action on $G / H$ : $l_{g}: k H \rightarrow(g k) H$, since $\pi \circ L_{g}=l_{g} \circ \pi:$


Let $\exp : \mathfrak{g} \rightarrow G$ the exponential map of $G$, and define a map $\mathfrak{g} \rightarrow \mathfrak{X}(G / H)$ by:

$$
\left.\widetilde{X}_{\pi(g)} \stackrel{\text { def }}{=} \frac{d}{d t}\right|_{t=0} \pi(\exp (t X) g) \quad X \in \mathfrak{g}, g \in G
$$

so that $\widetilde{X} \in \mathfrak{X}(G / H)$ is the infinitesimal generator of the $G$-left action on the homogeneous space $G / H$. Consider also the right-invariant vector field $\widehat{X} \in \mathfrak{X}(G)$, determined by $X \in \mathfrak{g}$ :

$$
\widehat{X}_{g} \quad \stackrel{\text { def }}{=}\left(R_{g}\right)_{*}(X)
$$

Then, for all $g \in G$ :

$$
\pi_{*} \widehat{X}_{g}=\pi_{*}\left(R_{g}\right)_{*}(X)=\left.\frac{d}{d t}\right|_{t=0} \pi \circ R_{g} \circ \exp (t X)=\widetilde{X}_{\pi(g)}
$$

and so $\pi_{*} \widehat{X}=\widetilde{X} \circ \pi$, which means that the right-invariant vector field $\widehat{X}$ on $G$ is $\pi$-related to the field $\widetilde{X}$ on $G / H$, determined by the left action of $G$ on $G / H$ :

$$
\begin{array}{ccc}
T G & \xrightarrow{\pi_{*}} & T(G / H) \\
\hat{X} \uparrow & & \uparrow \tilde{x} \\
G & \xrightarrow{\pi} & G / H
\end{array}
$$

Moreover the map $\widehat{X} \mapsto \widetilde{X}$ is a Lie algebra homomorphism from the Lie algebra of right-invariant vector fields on $G$, into $\mathfrak{X}(G / H)$.

On the other hand, if $A d: G \rightarrow G L(\mathfrak{g})$ is the adjoint representation of $G$ on its Lie algebra, then:

$$
l_{g} \widetilde{X}=\widetilde{A \widetilde{d_{g}} X} \circ l_{g}
$$

Assume now that $\mathfrak{m}$ is a direct sum complement to $\mathfrak{h}$ in $\mathfrak{g}$. With respect to an appropriate basis for $\mathfrak{g}=\mathfrak{h} \oplus \mathfrak{m}$, the restriction to $H$ of the adjoint representation $A d: G \rightarrow G L(\mathfrak{g})$ takes the form:

$$
A d_{h}=\left[\begin{array}{cc}
A & B \\
O & C
\end{array}\right] \quad h \in H
$$

since $H$ is a subgroup of $G$. The submatrix $B$ will be $O, \forall h \in H$, iff the adjoint action of $H$ on $\mathfrak{g}$, which is already reducible to an action on the subspace $\mathfrak{h}$ of $\mathfrak{g}$, is also reducible to an action on $\mathfrak{m}$; thus $B=O, \forall h \in H$ iff $A d\lfloor H$ is reducible to the direct sum of representations of $H$ on $\mathfrak{h}$ and $\mathfrak{m}$.

A homogeneous space $G / H$ is called "reducible", if there exists a vector space decomposition $\mathfrak{g}=\mathfrak{h} \oplus \mathfrak{m}$ (called a "reductive decomposition"), such that:

$$
A d_{H}(\mathfrak{m}) \subseteq \mathfrak{m}
$$

If $H$ is connected, $\mathfrak{g}=\mathfrak{h} \oplus \mathfrak{m}$ is a reductive decomposition iff:

$$
[\mathfrak{h}, \mathfrak{m}] \subseteq \mathfrak{m}
$$

Given a reducible homogeneous space $G / H$, with reductive decomposition $\mathfrak{g}=\mathfrak{h} \oplus \mathfrak{m}$, then the $\mathfrak{h}$-component (with respect to the reductive decomposition) of the canonical MaurerCartan 1-form $\Theta$ on $G$, defines a connection on the $H$-principal fiber bundle $G(G / H, H)$,
which is invariant by the left translations $L_{g}$ on $G$. The corresponding horizontal subspace is $\mathfrak{m}$, under the identification $\mathfrak{g} \cong T_{e} G$, and the curvature form $\Omega$ of this canonical invariant connection is:

$$
\Omega(X, Y)=-\frac{1}{2}[X, Y]_{\mathfrak{h}}
$$

where $[X, Y]_{\mathfrak{h}}$ means $\mathfrak{h}$-component, and $X, Y$ are arbitrary left invariant vector fields on $G$, belonging to $\mathfrak{m}$.

Now we apply these results to our supersymmetric situation, starting with the reductive decomposition (2.39) of the Grassmann shell $\mathfrak{g}=\mathcal{S P}(1 ; 2)_{\Lambda}$.

## Example ... The rigid superspace $\mathcal{S}^{2 \mid 2}$

By definition the rigid superspace of graded dimension (2|2) is the homogeneous space:

$$
\mathcal{S}^{2 \mid 2} \quad \stackrel{\text { def }}{=} \quad \frac{\mathbf{S P}(1 ; 2)}{\mathbf{H}}=\frac{\exp \mathcal{S P}(1 ; 2)_{\Lambda}}{\exp \left(\mathfrak{s o}(1,1)_{\Lambda}\right)}
$$

where $\mathbf{H}=\exp \left(\mathfrak{s o}(1,1)_{\Lambda}\right)$. Note that (locally) we can write every element $g \in \mathbf{S P}(1,1)$ in the form:

$$
\begin{equation*}
\left.\mathbf{g}=\mathbf{g}\left(\mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2} ; \lambda^{01}\right) \stackrel{\text { def }}{=} \exp \left(\mathbf{x}^{0} \mathbf{P}_{0}+\mathbf{x}^{1} \mathbf{P}_{1}+\theta^{1} \mathbf{Q}_{1}+\theta^{2} \mathbf{Q}_{2}\right) \exp \left(\lambda^{01} \Lambda_{01}\right)\right) \tag{2.41}
\end{equation*}
$$

with $\left(\mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2}\right) \in\left(\mathbf{R}_{c}\right)^{2} \times\left(\mathbf{R}_{a}\right)^{2}=\mathbf{R}^{2 \mid 2}$ and $\lambda^{10} \in \mathbf{R}_{c}$. So, the homogeneous space $\mathcal{S}^{2 \mid 2}$ can be parametrized by local coordinates $\left(z^{M}\right)=\left(\mathbf{x}^{1}, \mathbf{x}^{2} ; \theta^{1}, \theta^{2}\right) \in \mathbf{R}^{2 \mid 2}$, using the exponential chart (2.41). It is to be considered as a generalization of Minkowski space $\mathbf{R}_{(1,1)}$ and it is expected to have a richer structure, since now the supersymmetric algebra $\mathfrak{m}$ is not abelian.
$\mathcal{S}^{2 \mid 2}$ is a reductive homogeneous space, with reductive decomposition (see (2.39)):

$$
\mathcal{S P}(1 ; 2)_{\Lambda}=\mathfrak{s o}(1,1)_{\Lambda} \oplus \mathfrak{m}
$$

where, as before, $\mathfrak{m}$ is the supersymmetric algebra with generators $\left\{\mathbf{P}_{1}, \mathbf{P}_{2} ; \mathbf{Q}_{1}, \mathbf{Q}_{2}\right\}$.
In fact $\mathcal{S}$ is a very particular reductive homogeneous space, since in this case $\mathfrak{m}$ is a (graded) Lie algebra (recall that $[\mathfrak{m}, \mathfrak{m}] \subseteq \mathfrak{m}$ ). So exponentiation of $\mathfrak{m}$ give us a subgroup:

$$
\mathcal{M} \stackrel{\text { def }}{=} \exp (\mathfrak{m})
$$

of $\mathbf{S P}(1 ; 2)$. Let us see their left action on $\mathbf{S P}(1 ; 2)$, using BACH-formula (2.38), (2.37) and the supercommutation relations in $\mathcal{S P}(1 ; 2)$ :

$$
\begin{aligned}
& \mathbf{g}\left(\mathbf{a}^{0}, \mathbf{a}^{1} ; \eta^{1}, \eta^{2} ; \mathbf{0}\right) \mathbf{g}\left(\mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2} ; \lambda^{01}\right) \\
& \quad=e^{\left(\mathbf{a}^{0} \mathbf{P}_{0}+\mathbf{a}^{1} \mathbf{P}_{1}+\eta^{1} \mathbf{Q}_{1}+\eta^{2} \mathbf{Q}_{2}\right)} e^{\left(\mathbf{x}^{0} \mathbf{P}_{0}+\mathbf{x}^{1} \mathbf{P}_{1}+\theta^{1} \mathbf{Q}_{1}+\theta^{2} \mathbf{Q}_{2}\right)} e^{\left(\lambda^{01} \Lambda_{01}\right)} \\
& =e^{\left(\left(\mathbf{a}^{0}+\mathbf{x}^{0}-\eta^{1} \theta^{1}-\eta^{2} \theta^{2}\right) \mathbf{P}_{0}+\left(\mathbf{a}^{1}+\mathbf{x}^{1}+\eta^{1} \theta^{1}-\eta^{2} \theta^{2}\right) \mathbf{P}_{1}+\left(\eta^{1}+\theta^{1}\right) \mathbf{Q}_{1}+\left(\eta^{2}+\theta^{2}\right) \mathbf{Q}_{2}\right)} e^{\left(\lambda^{01} \Lambda_{01}\right)} \\
& =\mathbf{g ( \mathbf { a } ^ { 0 } + \mathbf { x } ^ { 0 } - \eta ^ { 1 } \theta ^ { 1 } - \eta ^ { 2 } \theta ^ { 2 } , \mathbf { a } ^ { 1 } + \mathbf { x } ^ { 1 } + \eta ^ { 1 } \theta ^ { 1 } - \eta ^ { 2 } \theta ^ { 2 } ; \eta ^ { 1 } + \theta ^ { 1 } , \eta ^ { 2 } + \theta ^ { 2 } )}
\end{aligned}
$$

So the induced $\mathcal{M}$-left action $l_{\mathbf{g}}=l_{\mathbf{g}\left(\mathbf{a}^{0}, \mathbf{a}^{1} ; \eta^{1}, \eta^{2} ; \mathbf{0}\right)}$ on the superspace $\mathcal{S}^{2 \mid 2}$, is given in local coordinates, defined by the exponential chart (2.41), by the so called "rigid supersymmetric translations":

$$
\begin{equation*}
z^{A}=\left(\mathbf{x}^{0}, \mathbf{x}^{1} ; \theta^{1}, \theta^{2}\right) \mapsto z^{\prime A}=\left(\mathbf{x}^{0}+\mathbf{a}^{0}-\eta^{1} \theta^{1}-\eta^{2} \theta^{2}, \mathbf{x}^{1}+\mathbf{a}^{1}+\eta^{1} \theta^{1}-\eta^{2} \theta^{2} ; \theta^{1}+\eta^{1}, \theta^{2}+\eta^{2}\right) \tag{2.42}
\end{equation*}
$$

Note an important point: if we decompose each even coordinate, for example $\mathbf{x}^{0}$, on body and soul: $\mathbf{x}^{0}=x_{b}^{0}+\mathbf{x}_{s}^{0}$, we see that the above supersymmetric translations, with $\mathbf{a}^{0}=\mathbf{0}$ ), change the soul leaving the body invariant, i.e.::

$$
x_{b}^{0} \rightarrow x_{b}^{0} \quad \mathbf{x}_{s}^{0} \rightarrow \mathbf{x}_{s}^{0}-\eta^{1} \theta^{1}-\eta^{2} \theta^{2}
$$

so, even if $\mathbf{x}^{0}$ were soulles before a susy transformation, it acquires some soul afterwords!
The susy transformation (2.42) can be interpreted as infinitesimal coordinate transformations $z^{\prime A}=z^{A}+X^{A}$, generated by the super vector field:

$$
\mathbf{X}=\left(\mathbf{a}^{0}-\eta^{1} \theta^{1}-\eta^{2} \theta^{2}\right) \frac{\partial}{\partial x^{0}}+\left(\mathbf{a}^{1}+\eta^{1} \theta^{1}-\eta^{2} \theta^{2}\right) \frac{\partial}{\partial x^{1}}+\eta^{1} \frac{\partial}{\partial \theta^{1}}+\eta^{2} \frac{\partial}{\partial \theta^{2}}
$$

where:

$$
\frac{\partial}{\partial z^{A}}=\left(\frac{\partial}{\partial x^{0}}, \frac{\partial}{\partial x^{1}}, \frac{\partial}{\partial \theta^{1}}, \frac{\partial}{\partial \theta_{2}}\right)
$$

represents the coordinate basis on super tangent space $T_{z} \mathcal{S}^{2 \mid 2}$.
To determine the basis of $T_{z} \mathcal{S}^{2 \mid 2}$ which is induced by the (left) action of the group element $\mathbf{g}\left(\mathbf{a}^{0}, \mathbf{a}^{1} ; \eta^{1}, \eta^{2} ; \mathbf{0}\right) \in \mathcal{M}$, we rewrite the above super vector field $\mathbf{X}$ in the form:

$$
\widetilde{\mathbf{X}}=\mathbf{a}^{0} \widetilde{\mathbf{P}}_{0}+\mathbf{a}^{1} \widetilde{\mathbf{P}}_{1}+\eta^{1} \widetilde{\mathbf{Q}}_{1}+\eta^{2} \widetilde{\mathbf{Q}}_{2}
$$

with:

$$
\begin{align*}
\widetilde{\mathbf{P}}_{0} & =\frac{\partial}{\partial x^{0}} \quad \widetilde{\mathbf{P}}_{1}=\frac{\partial}{\partial x^{1}} \\
\widetilde{\mathbf{Q}}_{1} & =\frac{\partial}{\partial \theta^{1}}-\theta^{1}\left(\frac{\partial}{\partial x^{0}}-\frac{\partial}{\partial x^{1}}\right) \\
\widetilde{\mathbf{Q}}_{2} & =\frac{\partial}{\partial \theta^{2}}-\theta^{2}\left(\frac{\partial}{\partial x^{0}}+\frac{\partial}{\partial x^{1}}\right) \tag{2.43}
\end{align*}
$$

We can compute that the Lie bracket between the tangent vector fields $\left\{\widetilde{\mathbf{P}}_{0}, \widetilde{\mathbf{P}}_{1}, \widetilde{\mathbf{Q}}_{1}, \widetilde{\mathbf{Q}}_{2}\right\}$ vanish except the (graded) brackets:

$$
\left\{\widetilde{\mathbf{Q}}_{1}, \widetilde{\mathbf{Q}}_{1}\right\}=\widetilde{\mathbf{P}}_{0}-\widetilde{\mathbf{P}}_{1} \quad\left\{\widetilde{\mathbf{Q}}_{2}, \widetilde{\mathbf{Q}}_{2}\right\}=\widetilde{\mathbf{P}}_{0}+\widetilde{\mathbf{P}}_{1}
$$

So, while the $\left\{\frac{\partial}{\partial z^{A}}\right\}$ forms an holonomic frame for $T_{z} \mathcal{S}^{2 \mid 2},\left\{\widetilde{\mathbf{P}}_{0}, \widetilde{\mathbf{P}}_{1}, \widetilde{\mathbf{Q}}_{1}, \widetilde{\mathbf{Q}}_{2}\right\}$ defines an anholonomic frame characterized by the structure constants given by the above brackets.

We call the tangent vector fields $\left\{\mathbf{P}_{0}, \mathbf{P}_{1}, \mathbf{Q}_{\mathbb{1}}, \mathbf{Q}_{2}\right\}$ (we omit the hats), given by (2.43), the supersymmetric generators on superspace.

### 2.9 Covariant Derivatives

For simplicity, we continue to analyse the case of superspace $\mathcal{S}^{2 \mid 2}$, parametrized by local coordinates $\left(\mathbf{x}^{i} ; \theta^{\alpha}\right) \in \mathbf{R}^{2 \mid 2}$, given by the exponential chart (2.41):

Since the rigid supersymmetric transformations are induced by left action on the group $\mathbf{S P}(1 ; 2)$, the natural way to obtain a theory on $\mathcal{S}^{2 \mid 2}$ which is invariant under these transformations is to rely on the fact that left and right translations on a group commute. So one must express all geometric quantities on $\mathcal{S}^{2 \mid 2}$, with respect to the basis $\left\{\mathbf{D}_{A}\right\}=\left\{\partial_{0}, \partial_{1}, \mathbf{D}_{\mathbb{1}}, \mathbf{D}_{2}\right\}$ of $T_{z} \mathcal{S}^{2 \mid 2}$ (or its dual) which is induced by right action of $\mathcal{M}$ on $\mathbf{S P}(1 ; 2)$. Using the same reasoning as before (BACH-formula (2.38), (2.37) and the supercommutation relations in $\mathcal{S P}(1 ; 2)$ ), we deduce that this basis is given by:

$$
\begin{align*}
\partial_{0} & =\frac{\partial}{\partial x^{0}} \quad \partial_{1}=\frac{\partial}{\partial x^{1}} \\
\mathbf{D}_{1} & =\frac{\partial}{\partial \theta^{1}}+\theta^{1}\left(\frac{\partial}{\partial x^{0}}-\frac{\partial}{\partial x^{1}}\right) \\
\mathbf{D}_{2} & =\frac{\partial}{\partial \theta^{2}}+\theta^{2}\left(\frac{\partial}{\partial x^{0}}+\frac{\partial}{\partial x^{1}}\right) \tag{2.44}
\end{align*}
$$

We can compute that the Lie bracket between the tangent vector fields $\mathbf{D}_{A}$ vanish except the (graded) bracket:

$$
\left\{\mathbf{D}_{1}, \mathbf{D}_{1}\right\}=-\mathbf{P}_{0}+\mathbf{P}_{1} \quad\left\{\mathbf{D}_{2}, \mathbf{D}_{2}\right\}=-\mathbf{P}_{0}-\mathbf{P}_{1}
$$

Moreover:

$$
\left[\mathbf{Q}_{\alpha}, \mathbf{D}_{A}\right]=\mathbf{0}
$$

which means that the frame $\left\{\mathbf{D}_{A}\right\}$ is left-invariant, i.e., invariant under rigid supersymmetric transformations on superspace. We call the left-invariant tangent vector fields $\mathbf{D}_{A}$ the:

> "supersymmetric covariant derivatives"
on superspace. In fact, they can be considered as covariant derivatives with respect to the canonical connection on the reductive homogeneous space $\mathcal{S}^{2 \mid 2}$.

## 3 APPENDIX. Clifford Algebras and Spin Groups

### 3.1 Clifford Algebras

Motivation. Clifford maps
"Dirac problem": Consider the Minkowski quadratic form in $\mathbf{R}^{4}$ :

$$
q(\mathbf{x})=-t^{2}+x^{2}+y^{2}+z^{2} \quad \mathbf{x}=(t, x, y, z) \in \mathbf{R}^{4}
$$

and try to find a "linear function":

$$
\varphi(\mathbf{x})=\alpha t+\beta x+\gamma y+\delta z
$$

such that $(\varphi(\mathbf{x}))^{2}=-q(\mathbf{x}), \forall \mathbf{x} \in \mathbf{R}^{4}$, ie.:

$$
(\alpha t+\beta x+\gamma y+\delta z)^{2}=t^{2}-x^{2}-y^{2}-z^{2}
$$

A computation shows that:

$$
\begin{align*}
& \alpha^{2}=-\beta^{2}=-\gamma^{2}=-\delta^{2}=\mathbb{1} \\
& \alpha \beta+\beta \alpha=\alpha \gamma+\gamma \alpha=\cdots=\mathbf{0} \tag{3.1}
\end{align*}
$$

and so if there exists a solution, the coefficients of $\varphi$ must belong to a noncommutative algebra. In fact, up to isomorphism, there exists only one solution which can be obtained with complex $(4 \times 4)$-matrices $\alpha, \beta, \gamma, \delta$ - the Dirac matrices.

Let us generalize the above setup. Let $\mathbb{k}$ denote $\mathbf{R}$ or $\mathbf{C}$, and consider again the following:
"Dirac problem": Let $(\mathcal{V}, q)$ a $\mathbb{k}$-vector space with a non-degenerate quadratic form $q$, and let $\beta$ the associated symmetric bilinear form. Try to find a linear map:

$$
\varphi: \mathcal{V} \rightarrow \mathcal{A}
$$

where $\mathcal{A}$ is an associative $\mathbf{k}$-algebra (with unit $\mathbb{1}=\mathbb{1}_{\mathcal{A}}$ ), such that:

$$
\begin{equation*}
(\varphi(\mathbf{x}))^{2}=-q(\mathbf{x}) \mathbb{1} \quad \forall \mathbf{x} \in \mathcal{V} \tag{3.2}
\end{equation*}
$$

or equivalently, such that:

$$
\begin{equation*}
\varphi(\mathbf{x}) \varphi(\mathbf{y})+\varphi(\mathbf{y}) \varphi(\mathbf{x})=-2 \beta(\mathbf{x}, \mathbf{y}) \mathbb{1} \quad \forall \mathbf{x}, \mathbf{y} \in \mathcal{V} \tag{3.3}
\end{equation*}
$$

We call such a linear map $\varphi: \mathcal{V} \rightarrow \mathcal{A}$, a "Clifford map" from $(\mathcal{V}, q)$ to the algebra $\mathcal{A}$.

$$
\text { Example } \ldots \quad(\mathcal{V}, q)=\left(\mathbf{R}, q(x)=x^{2}\right)
$$

Then if $\mathcal{A}=\mathbf{C}$, considered as a real algebra, the real linear map $\varphi: \mathbf{R} \rightarrow \mathbf{C}$ defined by $\varphi(x)=i x$ is a Clifford map.

$$
\text { Example } \ldots \quad(\mathcal{V}, q)=\left(\mathbf{R}^{3}, q(\mathbf{x})=-\left(x^{2}+y^{2}+z^{2}\right)\right) \text {. }
$$

Then if $\mathcal{A}=\mathbf{C}(2)$ is the algebra of complex $(2 \times 2)$-matrices, considered as a real algebra, the real linear map $\varphi: \mathbf{R}^{3} \rightarrow \mathbf{C}(2)$ defined by:

$$
\varphi(\mathbf{x})=\varphi(x, y, z)=\left[\begin{array}{cc}
z & x-i y \\
x+i y & -z
\end{array}\right]
$$

is a Clifford map.

## Clifford Algebras

Definition $1 \ldots$ Let $(\mathcal{V}, q)$ a $\mathbb{k}$-vector space with a quadratic form $q$. An associative $\mathbb{k}$ algebra (with unit $\mathbb{1}) C l(\mathcal{V}, q)$ is called a Clifford algebra of $(\mathcal{V}, q)$, if there exists a Clifford map:

$$
\begin{equation*}
c: \mathcal{V} \rightarrow C l(\mathcal{V}, q) \tag{3.4}
\end{equation*}
$$

such that:
(i). $C l(\mathcal{V}, q)$ is generated by $\mathbb{1}$ and $c(\mathcal{V})$.
(ii). The following "universal property" holds: for every associative $\mathbb{k}$-algebra $\mathcal{A}$ (with unit), and every Clifford map $\varphi: \mathcal{V} \rightarrow \mathcal{A}$, there exists a $\mathbb{k}_{\mathbf{k}}$-algebra morphism $\Phi: C l(\mathcal{V}, q) \rightarrow$ $\mathcal{A}$, such that the diagram:

$$
\begin{array}{cc}
\mathcal{V} \xrightarrow{c} & C l(\mathcal{V}, q) \\
\varphi & \downarrow \Phi  \tag{3.5}\\
& \mathcal{A}
\end{array}
$$

commutes.

Since we assume $q$ to be a non-degenerate quadratic form, the Clifford map $c: \mathcal{V} \rightarrow$ $C l(\mathcal{V}, q)$ is injective, and so we identify hereater $\mathbf{x} \in \mathcal{V}$ with its image $c(\mathbf{x}) \in C l(\mathcal{V}, q)$. So in $C l(\mathcal{V}, q)$, we have that:

$$
\begin{equation*}
\mathbf{x}^{2}=-q(\mathbf{x}) \mathbb{1} \quad \mathbf{x y}+\mathbf{y x}=-2 \beta(\mathbf{x}, \mathbf{y}) \mathbb{1} \tag{3.6}
\end{equation*}
$$

$\forall \mathbf{x}, \mathbf{y} \in \mathcal{V} \stackrel{c}{\hookrightarrow} C l(\mathcal{V}, q)$. In particular we see that $\mathbf{x}$ and $\mathbf{y}$ are ortoghonal iff they anticommute in $C l(\mathcal{V}, q)$, and that $\mathbf{x}$ is invertible in $C l(\mathcal{V}, q)$ iff $\mathbf{x}$ is nonisotropic $q(\mathbf{x}) \neq 0$. In this case the inverse of $x \in \mathcal{V}$ is:

$$
\begin{equation*}
\mathrm{x}^{-1}=-\frac{\mathrm{x}}{q(\mathrm{x})} \tag{3.7}
\end{equation*}
$$

To construct $C l(\mathcal{V}, q)$ we consider the tensor algebra (over $\mathbb{k}$ ) of $\mathcal{V}, \otimes \mathcal{V}=\oplus_{r \geq 0} \otimes^{r} \mathcal{V}$ and the two-sided ideal $\mathcal{J}_{q}(\mathcal{V})$ generated by all the elements of the form $\mathbf{x} \otimes \mathbf{x}+q(\mathbf{x}) \mathbb{1}, \mathbf{x} \in \mathcal{V}$, and we put:

$$
\begin{equation*}
C l(\mathcal{V}, q)=\frac{\otimes \mathcal{V}}{\mathcal{J}_{q}(\mathcal{V})} \tag{3.8}
\end{equation*}
$$

So we may consider $C l(\mathcal{V}, q)$ as the algebra generated by $\mathbb{1}$ and $\mathcal{V} \hookrightarrow C l(\mathcal{V}, q)$, subject to the relations:

$$
\begin{equation*}
\mathbf{x y}+\mathbf{y x}=-2 \beta(\mathbf{x}, \mathbf{y}) \mathbb{1} \tag{3.9}
\end{equation*}
$$

If $\operatorname{dim} \mathcal{V}=n$ and if $\left\{\mathbf{e}_{1}, \cdots, \mathbf{e}_{n}\right\}$ is a $\mathbb{k}$-basis of $\mathcal{V}$, then the $2^{n}$ elements:

$$
\begin{equation*}
\mathbb{1}, \quad \mathbf{e}_{1}, \cdots, \mathbf{e}_{n}, \quad \mathbf{e}_{1} \mathbf{e}_{2}, \cdots, \mathbf{e}_{i} \mathbf{e}_{j}(i<j), \quad \cdots, \mathbf{e}_{1} \mathbf{e}_{2} \ldots \mathbf{e}_{n} \tag{3.10}
\end{equation*}
$$

form a $\mathbb{k}$-basis of $C l(\mathcal{V}, q)$ and so $\operatorname{dim} C l(\mathcal{V}, q)=2^{n}$.

Example ... If $q=\mathbf{0}$ then $C l(\mathcal{V}, q) \cong \wedge \mathcal{V}$ the exterior algebra of $\mathcal{V}$ over $\mathbb{k}$.
Example ... $C l\left(\mathbf{R}, q(x)=x^{2}\right)=\mathbf{C}$ considered as a real algebra.
Example ... $C l(\mathcal{V}, q)=C l\left(\mathbf{R}^{2}, q(\mathbf{x})=x^{2}+y^{2}\right) \cong \mathbf{H}$, the "real quaternion algebra". In fact, let us consider a $q$-orthonormal real basis $\{\mathbf{i}, \mathbf{j}\}$ for $\mathbf{R}^{2}$. Then:

$$
\begin{array}{llll}
1 & \mathrm{i} & \mathrm{j} & \mathrm{k} \equiv \mathrm{ij}
\end{array}
$$

is a basis for $C l\left(\mathbf{R}^{2}, x^{2}+y^{2}\right)$, which has dimension 4. The relations in $C l\left(\mathbf{R}^{2}, x^{2}+y^{2}\right)$ are:

$$
\begin{align*}
& \mathbf{i}^{2}=\mathbf{j}^{2}=-\mathbf{1} \quad \mathbf{k}^{2}=(\mathbf{i} \mathbf{j})^{2}=\mathbf{i} \mathbf{i} \mathbf{i j}=-\mathbf{i}^{2} \mathbf{j}^{2}=-\mathbf{1} \\
& \mathbf{j} \mathbf{k}=\mathbf{j} \mathbf{i} \mathbf{j}=-\mathbf{j}^{2} \mathbf{i}=\mathbf{i}, \quad \mathrm{ki}=\mathbf{i} \mathbf{i} \mathbf{i}=-\mathbf{i}^{2} \mathbf{j}=\mathbf{j} \tag{3.11}
\end{align*}
$$

and we see that:

$$
\begin{equation*}
C l\left(\mathbf{R}^{2}, x^{2}+y^{2}\right)=\mathbf{H} \tag{3.12}
\end{equation*}
$$

the "real quaternion algebra" nion:

$$
\begin{equation*}
h=a \mathbf{1}+b \mathbf{i}+c \mathbf{j}+d \mathbf{k} \in \mathbf{H} \tag{3.13}
\end{equation*}
$$

we define:
(i). the "conjugate" of $h$ :

$$
h^{*}=a \mathbf{1}-b \mathbf{i}-c \mathbf{j}-d \mathbf{k}
$$

(ii). the "norm" of $h$ :

$$
Q(h)=h h^{*}=a^{2}+b^{2}+c^{2}+d^{2}
$$

It's easy to see that:

$$
\begin{equation*}
Q\left(h h^{\prime}\right)=Q(h) Q\left(h^{\prime}\right) \quad \forall h, h^{\prime} \in \mathbf{H} \tag{3.14}
\end{equation*}
$$

and that $(\mathbf{H}, Q)$ is linear isomorphic to $\left(\mathbf{R}^{4}, q_{e}\right)$, where $q_{e}$ is the usual euclidean norm in $\mathbf{R}^{4}$. Besides, $\mathbf{H}$ is a noncommutative field.

We also use the representation of $\mathbf{H}$ as the real algebra of matrices of the form:

$$
h=\left[\begin{array}{cc}
u & v  \tag{3.15}\\
-\bar{v} & \bar{u}
\end{array}\right] \quad u, v \in \mathbf{C}
$$

In this representation we have that the conjugate of $h$ is $h^{*}=\bar{h}^{t}$, the norm of $h$ is $Q(h)=h h^{*}=$ $h \bar{h}^{t}=(\operatorname{det} h) \mathbb{1}$, and:

$$
\mathbf{1}=\mathbb{1}=\sigma_{0} \quad \mathbf{i}=i \sigma_{1} \quad \mathbf{j}=i \sigma_{2} \quad \mathbf{k}=i \sigma_{3}
$$

where:

$$
\sigma_{1}=\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right], \quad \sigma_{2}=\left[\begin{array}{cc}
0 & -i \\
i & 0
\end{array}\right], \quad \sigma_{3}=\left[\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right]
$$

are the Pauli matrices. Thus the real quaternion (3.13) is written in the form:

$$
\begin{equation*}
h=x^{0} \sigma_{0}+i\left(x^{1} \sigma_{1}+x^{2} \sigma_{2}+x^{3} \sigma_{3}\right) \quad \stackrel{\text { def }}{=} x^{0}+i \overrightarrow{\mathbf{x}} \cdot \vec{\sigma} \tag{3.16}
\end{equation*}
$$

Note also that $\mathbf{i}, \mathbf{j}$ and $\mathbf{k}$ generate the 3 -dimensional space of skew-hermitian matrices of zero trace. We know that the Pauli matrices anticommute and:

$$
\begin{array}{lrl}
\sigma_{i}^{2}=\mathbb{1} & \sigma_{1} \sigma_{2} \sigma_{3}=i \mathbb{1} & \\
\sigma_{1} \sigma_{2}=i \sigma_{3} & \sigma_{2} \sigma_{3}=i \sigma_{1} & \sigma_{3} \sigma_{1}=i \sigma_{2} \tag{3.17}
\end{array}
$$

Moreover if $\overrightarrow{\mathbf{x}}, \overrightarrow{\mathbf{y}} \in \mathbf{R}^{3}$ and $\vec{\sigma}=\left(\sigma_{1}, \sigma_{2}, \sigma_{3}\right)$, then we have in $\mathbf{H}$ :

$$
(\overrightarrow{\mathbf{x}} \cdot \vec{\sigma})(\overrightarrow{\mathbf{y}} \cdot \vec{\sigma})=(\overrightarrow{\mathbf{x}} \cdot \overrightarrow{\mathbf{y}}) \mathbb{1}+i(\overrightarrow{\mathbf{x}} \times \overrightarrow{\mathbf{y}}) \cdot \vec{\sigma}
$$

The real quaternions of unit norm, form the group $S U(2)$ :

$$
S U(2)=\left\{\left[\begin{array}{cc}
u & v \\
-\bar{v} & \bar{u}
\end{array}\right]:|u|^{2}+|v|^{2}=1\right\}
$$

## Involutions in $\mathcal{V}$

Consider the ortoghonal group of $(\mathcal{V}, q)$ :

$$
O(\mathcal{V}, q)=\left\{f: \mathcal{V} \rightarrow \mathcal{V}: f^{*} q=q\right\}
$$

If we take $\mathcal{A}=C l(\mathcal{V}, q)$ and $\varphi=c \circ f$ in definition 1:

$$
\begin{aligned}
& \mathcal{V} \quad \xrightarrow{c} \quad C l(\mathcal{V}, q) \\
& \varphi=c \circ f \quad \downarrow \Phi=\tilde{f} \\
& \mathcal{A}=C l(\mathcal{V}, q)
\end{aligned}
$$

then, since $\varphi=c \circ f$ is a Clifford map $\left(\varphi(\mathbf{x})^{2}=c(f(\mathbf{x}))^{2}=-q(f(\mathbf{x})) \mathbb{1}=-q(x) \mathbb{1}\right)$, we conclude that there exists a unique algebra morphism $\tilde{f} \in \operatorname{Aut}(C l(\mathcal{V}, q))$ that extends $f$, and so it's uniquelly determined by its action on the elements of $\mathcal{V}$. We shall see later that this embedding:

$$
O(\mathcal{V}, q) \hookrightarrow \operatorname{Aut}(C l(\mathcal{V}, q))
$$

actually lies in the subgroup of inner automorphisms.

In particular if $f(\mathbf{x})=-\mathbf{x}, \quad \mathbf{x} \in \mathcal{V}$, then we obtain the so called "main involution" or "degree involution" $\tilde{f}=\alpha$ :

$$
\begin{equation*}
\alpha: C l(\mathcal{V}, q) \rightarrow C l(\mathcal{V}, q) \tag{3.18}
\end{equation*}
$$

which verifies $\alpha^{2}=I d$. So there exists a decomposition:

$$
\begin{equation*}
C l(\mathcal{V}, q)=C l^{0}(\mathcal{V}, q) \oplus C l^{1}(\mathcal{V}, q) \tag{3.19}
\end{equation*}
$$

where $C l^{0}(\mathcal{V}, q)=\{h \in C l(\mathcal{V}, q): \alpha(h)=h\}$ is the "even part", which is a subalgebra, and $C l^{1}(\mathcal{V}, q)=\{h \in C l(\mathcal{V}, q): \alpha(h)=-h\}$ is the "odd part", which is a subspace.

Note that $C l(\mathcal{V}, q)$ endows the structure of "superalgebra" (or $\mathbf{Z}_{2}$-graded algebra), i.e.:

$$
\begin{equation*}
C l^{i}(\mathcal{V}, q) C l^{j}(\mathcal{V}, q) \subseteq C l^{i+j}(\mathcal{V}, q) \tag{3.20}
\end{equation*}
$$

where $(i+j)$ is taken $\bmod 2$. Moreover if $\operatorname{dim} \mathcal{V}=n$, then $\operatorname{dim} C l^{0}(\mathcal{V}, q)=\operatorname{dim} C l^{1}(\mathcal{V}, q)=$ $2^{n-1}$.

Now if we take $\mathcal{A}=C l(\mathcal{V}, q)^{o p}$ and $\varphi=c$ in definition 1, we conclude that there exists a unique algebra morphism in $\operatorname{Aut}(\operatorname{Cl}(\mathcal{V}, q))$ that extends $\varphi=c$, and that we call the "transpose" or "main anti-involution". The image of a product $\mathbf{x}_{1} \mathbf{x}_{2} \ldots \mathrm{x}_{k} \in C l(\mathcal{V}, q)$ under this transpose is:

$$
\left(\mathbf{x}_{1} \mathbf{x}_{2} \ldots \mathbf{x}_{k}\right)^{t}=\mathbf{x}_{k} \mathbf{x}_{k-1} \ldots \mathbf{x}_{1}
$$

and we see that:

$$
\left(h h^{\prime}\right)^{t}=h^{\prime t} h^{t} \quad \forall h, h^{\prime} \in C l(\mathcal{V}, q)
$$

Finall y we define the "conjugation" in $C l(\mathcal{V}, q)$, by:

$$
\begin{equation*}
h^{*} \quad \stackrel{\text { def }}{=} \alpha(h)^{t} \tag{3.21}
\end{equation*}
$$

so that:

$$
\left(\mathbf{x}_{1} \mathbf{x}_{2} \ldots \mathbf{x}_{k}\right)^{*}=(-1)^{k} \mathbf{x}_{k} \mathbf{x}_{k-1} \ldots \mathbf{x}_{1}
$$

## Representations

Definition $2 \ldots$ Let $\mathbf{K} \supseteq \mathbb{k}$ a field containing $\mathbb{k}$. Then a K-representation of the Clifford $\operatorname{algebra} \operatorname{Cl}(\mathcal{V}, q)$ is a $\mathbb{k}$-homomorphism:

$$
\rho: C l(\mathcal{V}, q) \longrightarrow \operatorname{End}_{\mathbf{K}}(W)
$$

into the algebra of linear transformations of a finite dimensional $\mathbf{K}$-vector space $W$.
$W$ is called a $C l(\mathcal{V}, q)$-module over $\mathbf{K}$, and the action:

$$
\rho(h)(\mathbf{w}) \stackrel{\text { def }}{=} h \cdot \mathbf{w} \quad h \in C l(\mathcal{V}, q) \quad \mathbf{w} \in W
$$

is called the Clifford multiplication.

As usual we treat complex representations as the basic objects, viewing real and quaternionic representations as complex representations with additional structure. Thus, if $\mathcal{W}$ is a complex module, a real structure on $\mathcal{W}$ is an anti-linear $C l(\mathcal{V}, q)$-map $\mathcal{R}$ such that $\mathcal{R}^{2}=\operatorname{Id}$, while a quaternionic structure on $\mathcal{W}$ is an anti-linear $G$-map $\mathcal{J}$ such that $\mathcal{J}^{2}=-$ Id. $\mathcal{R}$ or $\mathcal{J}$ are called "structure maps". A complex representation is called of "real type" (resp. "quaternionic type", if it admits a real (resp., quaternionic) structure.

Our main interest are the cases:

- $\mathcal{V}=\mathbf{R}^{n}=\mathbf{R}^{r+s}$ with quadratic form:

$$
\begin{equation*}
q\left(x_{1}, \cdots, x_{n}\right)=\underbrace{x_{1}^{2}+\cdots+x_{r}^{2}}_{r}-\underbrace{x_{r+1}^{2}-\cdots-x_{n}^{2}}_{s=n-r} \tag{3.22}
\end{equation*}
$$

The corresponding Clifford algebra will be denoted by $C l_{r, s}$.

- $\mathcal{V}=\mathrm{C}^{n}$ with quadratic form:

$$
\begin{equation*}
q_{\mathbf{C}}\left(z_{1}, \cdots, z_{n}\right)=z_{1}^{2}+\cdots+z_{n}^{2} \tag{3.23}
\end{equation*}
$$

The corresponding Clifford algebra will be denoted by $\mathrm{C} l_{n}$.
Note that the complexification of $C l_{r, s}$ is just the Clifford algebra (over $\mathbf{C}$ ) corresponding to the complexified quadratic form $q \otimes \mathbf{C}$, where $q$ is given by (3.22), i.e:

$$
C l_{r, s} \otimes_{\mathbf{R}} \mathbf{C} \cong C l\left(\mathbf{C}^{r+s}, q \otimes \mathbf{C}\right)
$$

However, since all non-degenerate quadratic forms on $\mathbf{C}^{n}$ are equivalent, we have that:

$$
\begin{equation*}
\mathbf{C} l_{n} \cong C l_{r, s} \otimes_{\mathbf{R}} \mathbf{C} \tag{3.24}
\end{equation*}
$$

$\forall r, s: r+s=n$.

Theorem $1 \ldots$ Assume that $\mathcal{V}=\mathcal{V}_{1} \oplus \mathcal{V}_{2}$ and that there exists a nondegenerate bilinear pairing between $\mathcal{V}_{1}$ and $\mathcal{V}_{2}$, denoted by $<,>: \mathcal{V}_{1} \times \mathcal{V}_{2} \rightarrow \mathbb{k}$. Consider the nondegenerate bilinear form $\beta$ on $\mathcal{V}$ given by:

$$
\begin{equation*}
\left.\beta\left(\mathbf{v}_{1} \oplus \mathbf{v}_{2}, \mathbf{w}_{1} \oplus \mathbf{w}_{2}\right) \stackrel{\text { def }}{=}-\frac{1}{2}\left[<\mathbf{v}_{1}, \mathbf{w}_{2}\right\rangle+\left\langle\mathbf{w}_{1}, \mathbf{v}_{2}\right\rangle\right] \tag{3.25}
\end{equation*}
$$

and let $q$ be the corresponding quadratic form. Then:

$$
\begin{equation*}
C l(\mathcal{V}, q) \cong E n d_{\mathbb{k}}\left(\wedge \mathcal{V}_{1}\right) \tag{3.26}
\end{equation*}
$$

Proof...
We define for each $\mathbf{v}_{1} \in \mathcal{V}_{1}$ a "creation operator" $\epsilon_{\mathbf{v}_{1}}$, in $\wedge \mathcal{V}_{1}$, by:

$$
\begin{equation*}
\epsilon_{\mathbf{v}_{1}}: \wedge \mathcal{V}_{1} \rightarrow \wedge \mathcal{V}_{1} \quad \epsilon_{\mathbf{v}_{1}} \alpha=\mathbf{v}_{1} \wedge \alpha \quad \forall \alpha \in \wedge \mathcal{V}_{1} \tag{3.27}
\end{equation*}
$$

and for each $\mathbf{v}_{2} \in \mathcal{V}_{2}$, an "anihilation operator" $\iota_{\mathbf{v}_{2}}$, again in $\wedge \mathcal{V}_{1}$, first defining $\iota_{\mathfrak{v}_{2}}: \mathcal{V}_{1} \rightarrow \mathbb{k}$, by $\iota_{\mathbf{v}_{2}}\left(\mathbf{w}_{1}\right)=<\mathbf{w}_{1}, \mathbf{v}_{2}>$, and then extend this to a skew-derivation of $\wedge \mathcal{V}_{1}$, i.e.:

$$
\iota_{\mathbf{v}_{2}}(\alpha \wedge \beta)=\iota_{\mathbf{v}_{2}}(\alpha) \wedge \beta+(-1)^{\operatorname{deg}(\alpha)} \alpha \wedge \iota_{\mathbf{v}_{2}}(\beta) \quad \forall \alpha, \beta \in \wedge \mathcal{V}_{1}
$$

Then $\epsilon_{\mathbf{v}_{1}}$ and $\iota_{\mathbf{v}_{2}}$ are fermionic creation-anihilation operators, i.e.:

$$
\begin{align*}
\epsilon_{\mathbf{v}_{1}}^{2} & =0 \\
\iota_{\mathbf{v}_{2}}^{2} & =0 \\
\left\{\epsilon_{\mathbf{v}_{1}}, \iota_{\mathbf{v}_{2}}\right\} & =<\mathbf{v}_{1}, \mathbf{v}_{2}>\mathrm{Id} \tag{3.28}
\end{align*}
$$

By the universal property of definition 1 , to define the Clifford action on $\wedge \mathcal{V}_{1}$ we need only specify it on $\mathcal{V}$. We define it by:

$$
\begin{equation*}
\mathbf{v} \cdot \alpha=\left(\mathbf{v}_{1} \oplus \mathbf{v}_{2}\right) \cdot \alpha \stackrel{\text { def }}{=} \quad\left(\epsilon_{\mathbf{v}_{1}}-\iota_{\mathbf{v}_{2}}\right) \alpha \quad \mathbf{v}=\mathbf{v}_{1} \oplus \mathbf{v}_{2} \in \mathcal{V}=\mathcal{V}_{1} \oplus \mathcal{V}_{2}, \alpha \in \wedge \mathcal{V}_{1} \tag{3.29}
\end{equation*}
$$

We only need to verify if $\mathbf{v} \cdot(\mathbf{v} \cdot)=-q(\mathbf{v}) \mathbb{1}$, which it's true since:

$$
\begin{align*}
\mathbf{v} \cdot(\mathbf{v} \cdot \alpha) & =\left(\mathbf{v}_{1} \oplus \mathbf{v}_{2}\right) \cdot\left(\mathbf{v}_{1} \oplus \mathbf{v}_{2}\right) \cdot \alpha \\
& =\left(\mathbf{v}_{1} \oplus \mathbf{v}_{2}\right) \cdot\left(\epsilon_{\mathbf{v}_{1}}-\iota_{\mathbf{v}_{2}}\right) \alpha \\
& =\left(\epsilon_{\mathbf{v}_{1}}^{2}+\epsilon_{\mathbf{v}_{1}} \iota_{\mathbf{v}_{2}}+\iota_{\mathbf{v}_{2}} \epsilon_{\mathbf{v}_{1}}+\iota_{\mathbf{v}_{2}}^{2}\right) \alpha \\
& =<\mathbf{v}_{1}, \mathbf{v}_{2}>\mathbb{1} \alpha \\
& =-q(\mathbf{v}) \mathbb{1} \alpha \tag{3.30}
\end{align*}
$$

Thus this Clifford action extends to a homomorphism:

$$
\begin{equation*}
C l(\mathcal{V}, q) \rightarrow \operatorname{End}_{\mathfrak{k}}\left(\wedge \mathcal{V}_{1}\right) \tag{3.31}
\end{equation*}
$$

Since $\operatorname{dim} \operatorname{End}_{\mathfrak{k}}\left(\wedge \mathcal{V}_{1}\right)=\left(2^{n}\right)^{2}=2^{2 n}=\operatorname{dim} C l(\mathcal{V}, q)$, to show that this is an isomorphism it suffices to show that this is surjective. In fact this follows from the fact that the algebra $E n d_{\mathbb{k}}\left(\wedge \mathcal{V}_{1}\right)$ is generated by the above fermionic creation-anihilation operators, CQD.

With the same hypothesis of the previous theorem, sometimes it's useful to use another isomorphic representation, constructed as follows:

Let $\left\{\mathbf{e}_{1}, \cdots, \mathbf{e}_{n}\right\}$ be a $\mathbb{1}_{k}$-basis for $\mathcal{V}_{1}$, and let $\left\{\mathbf{f}_{1}, \cdots, \mathbf{f}_{n}\right\}$ be the dual basis, with respect to the duality $<.>$, so that:

$$
<\mathbf{e}_{i}, \mathbf{f}_{j}>=\delta_{i j}
$$

Relativelly to the bilinear form $\beta$ on $\mathcal{V}$ given by (3.25), and the corresponding quadratic form $q$, we have:

$$
q\left(\mathbf{e}_{i}\right)=0=q\left(\mathbf{f}_{j}\right) \quad \beta\left(\mathbf{e}_{i}, \mathbf{f}_{j}\right)=-\frac{1}{2} \delta_{i j}
$$

and in $C l(\mathcal{V}, q)$ :

$$
\mathbf{e}_{i}^{2}=0=\mathbf{f}_{j}^{2} \quad\left\{\mathbf{e}_{i}, \mathbf{f}_{j}\right\}=\mathbf{e}_{i} \mathbf{f}_{j}+\mathbf{f}_{j} \mathbf{e}_{i}=\frac{1}{2} \delta_{i j} \mathbb{1}
$$

Now we define the "Clifford vacuum":

$$
\Omega=\mathbf{f}_{1} \mathbf{f}_{2} \ldots \mathbf{f}_{n}
$$

and consider the left ideal $\mathcal{S}$ in $C l(\mathcal{V}, q)$ :

$$
\begin{equation*}
\mathcal{S} \stackrel{\text { def }}{=} C l(\mathcal{V}, q) \Omega \tag{3.32}
\end{equation*}
$$

It's easy to see that $\mathcal{S}$ is in fact the subspace of $C l(\mathcal{V}, q)$ linearlly generated by all the elements of the form $\mathbf{e}_{I} \Omega$, i.e:

$$
\mathcal{S}=\mathbb{k}\left\langle\mathbf{e}_{I} \Omega: \forall I=\left\{1 \leq i_{1}<i_{2}<\cdots i_{r} \leq n, 1 \leq r \leq n\right\}, \emptyset\right\rangle
$$

(we put $\mathbf{e}_{\emptyset}=\mathbb{1}$ ). In fact the set of all $\mathbf{e}_{I} \mathbf{f}_{J}$ is basis for $C l(\mathcal{V}, q)$, and $\mathbf{f}_{J} \Omega=0, \forall J \neq \emptyset$. Now we consider the left action of $C l(\mathcal{V}, q)$ on $\mathcal{S}=C l(\mathcal{V}, q) \Omega$ :

$$
\begin{equation*}
h \cdot\left(h^{\prime} \Omega\right) \stackrel{\text { def }}{=}\left(h h^{\prime}\right) \Omega \tag{3.33}
\end{equation*}
$$

which endows $\mathcal{S}$ with the structure of $C l(\mathcal{V}, q)$-module. Of course $\mathcal{S}$ is linearlly isomorphic to $\wedge \mathcal{V}_{1} \Omega \cong \wedge \mathcal{V}_{1}$, and the map $\alpha \mapsto \alpha \cdot \Omega$ gives an isomorphism:

$$
\wedge \mathcal{V}_{1} \longrightarrow \mathcal{S}=\wedge \mathcal{V}_{1} \cdot \Omega=C l(\mathcal{V}, q) \cdot \Omega
$$

of left $C l(\mathcal{V}, q)$-modules. So we have the following:
Theorem $2 \ldots$ Assume the same hypothesis of the previous theorem. Then the (left) $C l(\mathcal{V}, q)$-module $\wedge \mathcal{V}_{1}$ is isomorphic to a left ideal in $C l(\mathcal{V}, q)$. In fact, let $\Omega$ be a generator of the top exterior power $\wedge^{n} \mathcal{V}_{2}$ (the "Clifford vacuum"). Then:

$$
\begin{equation*}
\mathcal{S} \stackrel{\text { def }}{=} C l(\mathcal{V}, q) \cdot \Omega \cong \wedge \mathcal{V}_{1} \cdot \Omega \tag{3.34}
\end{equation*}
$$

and the map $\alpha \mapsto \alpha \cdot \Omega$ gives an isomorphism:

$$
\wedge \mathcal{V}_{1} \longrightarrow \mathcal{S}=\wedge \mathcal{V}_{1} \cdot \Omega=C l(\mathcal{V}, q) \cdot \Omega
$$

of left $C l(\mathcal{V}, q)$-modules.

Theorem $3 \ldots$ Let $\mathcal{V}$ be a $2 n$-dimensional vector space with a nondegenerate quadratic form. Assume that there exists an involution $\Phi: \mathcal{V} \rightarrow \mathcal{V}: \Phi^{2}=I d$, which is skew-symmetric with respect to $\beta$, i.e., $\beta(\Phi \mathbf{v}, \mathbf{w})=-\beta(\mathbf{v}, \Phi \mathbf{w}), \forall \mathbf{v}, \mathbf{w} \in \mathcal{V}$. Then $C l(\mathcal{V}, q)$ is isomorphic to $\operatorname{End}_{\mathfrak{l} \mathfrak{k}}\left(\mathcal{V}_{1}\right)$ where $\mathcal{V}_{1}=\operatorname{ker}(\Phi-I d)$.

Proof...
Consider the ( $\pm 1$ )-eigenspaces of $\Phi$ :

$$
\begin{aligned}
& \mathcal{V}_{1}=\{\mathbf{v} \in \mathcal{V}: \Phi \mathbf{v}=\mathbf{v}\} \\
& \mathcal{V}_{2}=\{\mathbf{v} \in \mathcal{V}: \Phi \mathbf{v}=-\mathbf{v}\}
\end{aligned}
$$

Then $\mathcal{V}=\mathcal{V}_{1} \oplus \mathcal{V}_{2}$, with:

$$
\mathbf{v}=\mathbf{v}_{1} \oplus \mathbf{v}_{2}=\frac{1}{2}(\mathbf{v}+\Phi \mathbf{v})+\frac{1}{2}(\mathbf{v}-\Phi \mathbf{v}) \in \mathcal{V}_{1} \oplus \mathcal{V}_{2}
$$

$\mathcal{V}_{1}$ and $\mathcal{V}_{2}$ are totally isotropic with respect to $q$. In fact, if $\mathbf{v}_{1}, \mathbf{w}_{1} \in \mathcal{V}_{1}$, then, since $\Phi$ is skew:

$$
\beta\left(\mathbf{v}_{1}, \mathbf{w}_{1}\right)=\beta\left(\Phi \mathbf{v}_{1}, \Phi \mathbf{w}_{1}\right)=-\beta\left(\Phi^{2} \mathbf{v}_{1}, \mathbf{w}_{1}\right)=-\beta\left(\mathbf{v}_{1}, \mathbf{w}_{1}\right)
$$

whence $\beta\left(\mathbf{v}_{1}, \mathbf{w}_{1}\right)=0$. Similarly $\beta\left(\mathbf{v}_{2}, \mathbf{w}_{2}\right)=0, \forall \mathbf{v}_{2}, \mathbf{w}_{2} \in \mathcal{V}_{2}$. Now we define a bilinear pairing between $\mathcal{V}_{1}$ and $\mathcal{V}_{2}$, by:

$$
<\mathbf{v}_{1}, \mathbf{v}_{2}>\stackrel{\text { def }}{=}-2 \beta\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right) \quad \mathbf{v}_{1} \in \mathcal{V}_{1}, \mathbf{v}_{2} \in \mathcal{V}_{2}
$$

It is nondegenerate, since $\beta$ is so, and with respect to the direct sum decomposition $\mathcal{V}=\mathcal{V}_{1} \oplus \mathcal{V}_{2}$, $\beta$ verifies:

$$
\begin{aligned}
\beta\left(\mathbf{v}_{1} \oplus \mathbf{v}_{2}, \mathbf{w}_{1} \oplus \mathbf{w}_{2}\right) & =\beta\left(\mathbf{v}_{1}, \mathbf{w}_{2}\right)+\beta\left(\mathbf{w}_{1}, \mathbf{v}_{2}\right) \\
& =-\frac{1}{2}\left[\left\langle\mathbf{v}_{1}, \mathbf{w}_{2}\right\rangle+\left\langle\mathbf{w}_{1}, \mathbf{v}_{2}\right\rangle\right]
\end{aligned}
$$

and we can apply the previous theorem to conclude that $C l(\mathcal{V}, q) \cong \operatorname{End}_{\mathfrak{l}_{\mathbf{k}}}\left(\wedge \mathcal{V}_{1}\right), \mathrm{CQD}$.

## Corollary 1 ...

$$
\mathbf{C} l_{2 n} \cong \operatorname{End}_{\mathbf{C}}\left(\wedge \mathbf{C}^{n}\right)
$$

## Corollary $2 \ldots$

$$
C l_{r, r} \cong E n d_{\mathbf{R}}\left(\wedge \mathbf{R}^{r}\right)
$$

Theorem $4 \ldots$ Consider the Clifford algebra $C l(\mathcal{V}, q)$, and let $\mathbf{e} \in \mathcal{V}$ be a nonzero vector with $q(\mathbf{e})=a \neq 0$. Consider the orthogonal $\mathcal{W}=\mathbf{e}^{\perp}$ and the quadratic form $q^{\perp}(\mathbf{y})=$ $a q(\mathbf{y}), \quad \mathbf{y} \in \mathcal{W}$.

Then, the even subalgebra $C l^{(0)}(\mathcal{V}, q)$ is the Clifford algebra of $\left(\mathcal{W}, q^{\perp}\right)$ :

$$
\begin{equation*}
C l^{(0)}(\mathcal{V}, q)=C l\left(\mathcal{W}, q^{\perp}\right) \tag{3.35}
\end{equation*}
$$

Proof...

Consider the diagram of definition 1:

$$
\begin{array}{cc}
\mathcal{W} \xrightarrow{c} & C l\left(\mathcal{W}, q^{\perp}\right) \\
\varphi & \downarrow \Phi \\
& \\
& \mathcal{A}=C l^{(0)}(\mathcal{V}, q)
\end{array}
$$

with $\varphi(\mathbf{y})=$ ye. Then $\varphi$ is Clifford map. In fact, since $\mathbf{y}$ and $\mathbf{e}$ are $q$-orthogonal, they anticommute in $C l(\mathcal{V}, q)$, and so $\forall \mathbf{y} \in \mathbf{e}^{\perp}=\mathcal{W}$ :

$$
\varphi(\mathbf{y})^{2}=\text { yeye }=-\mathbf{y}^{2} \mathbf{e}^{2}=-q(\mathbf{e}) q(\mathbf{y})=-a q(\mathbf{y})=-q^{\perp}(\mathbf{y}) \mathbb{1}
$$

So $\varphi$ extends to a unique algebra morphism $\Phi: C l\left(\mathcal{W}, q^{\perp}\right) \rightarrow C l^{(0)}(\mathcal{V}, q)$ which it's an isomorphism, CQD.

$$
\begin{array}{|l|l}
\text { Example } & \ldots
\end{array} C l_{0,3}=\mathbf{C}(2)
$$

Let $(\mathcal{V}, q)=\left(\mathbf{R}^{3},-q_{e}\right)$, where $q_{e}(\mathbf{x})=x^{2}+y^{2}+z^{2}$ is the euclidean quadratic form. We know that $C l\left(\mathbf{R}^{3},-q_{e}\right)$ has real dimension $8=2^{3}$. Let us apply the previous theorem, fixing an unit vector $\mathbf{e} \in \mathbf{R}^{3}$, with $\mathbf{q}(\mathbf{e})=a=-1$, and considering $\left(\mathcal{W}=\mathbf{e}^{\perp}, q^{\perp}\right) \cong\left(\mathbf{R}^{2}, q^{\perp}=\left.q_{e}\right|_{\mathcal{W}}\right)$.

The theorem says that the even subalgebra $C l^{(0)}\left(\mathbf{R}^{3},-q_{e}\right)$ is the Clifford algebra of $\left(\mathbf{R}^{2}, q(\mathbf{x})=\right.$ $x^{2}+y^{2}$ ), which is $\mathbf{H}$, as we have seen in a previous example, i.e.:

$$
C l_{0,3}^{(0)}=C l_{2,0}=\mathbf{H}
$$

Let us consider now an orthonormal basis $\mathcal{B}=\left\{\mathbf{e}_{1}, \mathbf{e}_{2}, \mathbf{e}_{3}\right\}$ of $\mathbf{R}^{3}$, and the element:

$$
\begin{equation*}
\omega=\mathbf{e}_{1} \mathbf{e}_{2} \mathbf{e}_{3} \in C l_{0,3} \tag{3.36}
\end{equation*}
$$

which is called the "chirality operator". Note that if we choose another orthonormal basis $\hat{\mathcal{B}}=$ $\left\{\hat{\mathbf{e}}_{1}, \hat{\mathbf{e}}_{2}, \hat{\mathbf{e}}_{3}\right\}$, then $\hat{\mathbf{e}}_{i}=g_{i}^{j} \mathbf{e}_{j}$ with $g=\left(g_{i}^{j}\right) \in O(3)$. Besides it's easy to see that:

$$
\hat{\mathbf{e}}_{1} \hat{\mathbf{e}}_{2} \hat{\mathbf{e}}_{3}=(\operatorname{det} g) \mathbf{e}_{1} \mathbf{e}_{2} \mathbf{e}_{3}
$$

and so if we choose an orientation for $\mathbf{R}^{3}$ we see that we can define the chirality operator by (3.36), and this definition is independent of the choice of the orthonormal basis belonging to that orientation.

Now we compute that:

$$
\omega^{2}=-\mathbb{1} \quad \omega \mathbf{e}_{i}=\mathbf{e}_{i} \omega \quad i=1,2,3
$$

and that the center of $C l_{0,3}$ is the subalgebra of the elements of the form $a \mathbb{1}+b \omega$, thus isomorphic to $\mathbf{C}$ since $\omega^{2}=-\mathbb{1}$. So we see that $C l_{0,3}$ is a complex algebra, and since $\omega C l_{0,3}^{(0)}=C l_{0,3}^{(1)}$, then:

$$
\begin{align*}
C l_{0,3} & =C l_{0,3}^{(0)} \oplus C l_{0,3}^{(1)} \\
& =C l_{0,3}^{(0)} \oplus \omega C l_{0,3}^{(0)} \\
& =\mathbf{H} \oplus \omega \mathbf{H} \\
& =\mathbf{H}^{\mathbf{C}} \\
& =\mathbf{C}(2) \tag{3.37}
\end{align*}
$$

The usual representation of $C l_{0,3}$ by matrices of $\mathbf{C}(2)$, is the following: if $c: \mathbf{R}^{3} \hookrightarrow C l_{0,3}$ is the canonical injection, and if $\left\{\mathbf{e}_{1}, \mathbf{e}_{2}, \mathbf{e}_{3}\right\}$ is an orthonormal basis of $\mathbf{R}^{3}$, we put:

$$
\begin{align*}
c\left(x \mathbf{e}_{1}+y \mathbf{e}_{2}+z \mathbf{e}_{3}\right) & =\left[\begin{array}{cc}
z & x-i y \\
x+i y & -z
\end{array}\right] \\
& =x \sigma_{1}+y \sigma_{2}+z \sigma_{3} \tag{3.38}
\end{align*}
$$

where:

$$
\sigma_{1}=\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right], \quad \sigma_{2}=\left[\begin{array}{cc}
0 & -i \\
i & 0
\end{array}\right], \quad \sigma_{3}=\left[\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right]
$$

are the Pauli matrices. So $c\left(\mathbf{R}^{3}\right) \hookrightarrow C l\left(\mathbf{R}^{3},-q_{e}\right)=\mathbf{C}(2)$ is the real subspace of hermitian matrices with zero trace. We know that the Pauli matrices anticommute, and that:

$$
\begin{array}{lll}
\sigma_{i}^{2}=\mathbb{1} & \sigma_{1} \sigma_{2} \sigma_{3}=i \mathbb{1} \\
\sigma_{1} \sigma_{2}=i \sigma_{3} & \sigma_{2} \sigma_{3}=i \sigma_{1} & \sigma_{3} \sigma_{1}=i \sigma_{2} \tag{3.39}
\end{array}
$$

and we see that $\left\{\mathbb{1}, i \sigma_{1}, i \sigma_{2}, i \sigma_{3}\right\}$ is a basis for the even subalgebra $C l_{0,3}^{(0)}$, while $\left\{\mathbb{1}, i \sigma_{1}, i \sigma_{2}, i \sigma_{3}, i \mathbb{1}\right.$,-$\left.\sigma_{1},-\sigma_{2},-\sigma_{3}\right\}$ is a real basis for $C l_{0,3}$.

$$
\text { Example } \ldots \quad C l_{3,0}=C l\left(\mathbf{R}^{3}, q_{e}\right)=\mathbf{H} \oplus \mathbf{H}
$$

In fact, now the chirality operator $\omega=\mathbf{e}_{1} \mathbf{e}_{2} \mathbf{e}_{3}$ verifies: $\omega^{2}=\mathbb{1}$ and $\mathbf{v} \omega=\omega \mathbf{v} \forall \mathbf{v} \in \mathbf{R}^{3}$, i.e., $\omega$ is a central element in $C l_{3,0}$.

We can consider now the direct sum decomposition:

$$
C l_{3,0}=C l_{3,0}^{+} \oplus C l_{3,0}^{-}
$$

where:

$$
C l_{3,0}^{+} \stackrel{\text { def }}{=} \frac{\mathbb{1}+\omega}{2} C l_{3,0} \quad \text { and } \quad C l_{3,0}^{+} \stackrel{\text { def }}{=} \frac{\mathbb{1}-\omega}{2} C l_{3,0}
$$

are isomorphic subalgebras such that $\alpha\left(C l_{3,0}^{ \pm}\right)=C l_{3,0}^{\mp}$.
For the next theorem, assume that $\left(\mathcal{V}, q_{\mathcal{V}}\right)$ and $\left(\mathcal{W}, q_{\mathcal{W}}\right)$ are two vector spaces with quadratic forms. Define in $\mathcal{V} \oplus \mathcal{W}$ a quadratic form $q=q_{\mathcal{V}} \oplus q_{\mathcal{W}}$ by:

$$
q(\mathbf{v} \oplus \mathbf{w})=q_{\mathcal{V}}(\mathbf{v})+q_{\mathcal{W}}(\mathbf{w})
$$

Recall also that if $\mathcal{V}=\mathcal{V}^{0} \oplus \mathcal{V}^{1}$ and $\mathcal{W}=\mathcal{W}^{0} \oplus \mathcal{W}^{1}$ are two superalgebras then we define its tensor product $\mathcal{V} \hat{\otimes} \mathcal{W}$ as the superspace:

$$
\begin{align*}
& \mathcal{V} \otimes \mathcal{W}= \\
& \stackrel{(\mathcal{V} \otimes \mathcal{W})^{0} \oplus(\mathcal{V} \otimes \mathcal{W})^{1}}{=}  \tag{3.40}\\
&\left(\mathcal{V}^{0} \otimes \mathcal{W}^{0} \oplus \mathcal{V}^{1} \otimes \mathcal{W}^{1}\right) \oplus\left(\mathcal{V}^{0} \otimes \mathcal{W}^{1} \oplus \mathcal{V}^{1} \otimes \mathcal{W}^{0}\right)
\end{align*}
$$

together with a multiplication defined by:

$$
\left(\mathbf{v}_{1} \oplus \mathbf{w}_{1}\right)\left(\mathbf{v}_{2} \oplus \mathbf{w}_{2}\right)=(-1)^{\left(\operatorname{deg} \mathbf{w}_{1}\right)\left(\operatorname{deg} \mathbf{v}_{2}\right)} \mathbf{v}_{1} \mathbf{v}_{2} \otimes \mathbf{w}_{1} \mathbf{w}_{2}
$$

Theorem 5 ... There exists an isomorphism of superalgebras:

$$
\begin{equation*}
C l\left(\mathcal{V} \oplus \mathcal{W}, q_{\mathcal{V}} \oplus q_{\mathcal{W}}\right) \cong C l\left(\mathcal{V}, q_{\mathcal{V}}\right) \hat{\otimes} C l\left(\mathcal{W}, q_{\mathcal{W}}\right) \tag{3.41}
\end{equation*}
$$

Proof...
Consider the linear map $\varphi: \mathcal{V} \oplus \mathcal{W} \rightarrow C l\left(\mathcal{V}, q_{\mathcal{V}}\right) \hat{\otimes} C l\left(\mathcal{W}, q_{\mathcal{W}}\right)$ defined by:

$$
\varphi(\mathbf{v} \oplus \mathbf{w})=\mathbf{v} \otimes \mathbb{1}_{\mathcal{W}}+\mathbb{1}_{\mathcal{V}} \otimes \mathbf{w}
$$

Then:

$$
\begin{align*}
\varphi(\mathbf{v} \oplus \mathbf{w})^{2} & =\left(\mathbf{v} \otimes \mathbb{1}_{\mathcal{W}}+\mathbb{1}_{\mathcal{V}} \otimes \mathbf{w}\right)^{2} \\
& =\mathbf{v}^{2} \otimes \mathbb{1}_{\mathcal{W}}+\mathbf{v} \otimes \mathbf{w}-\mathbf{v} \otimes \mathbf{w}+\mathbb{1}_{\mathcal{V}} \otimes \mathbf{w}^{2} \\
& =-\left[q_{\mathcal{V}}(\mathbf{v})+q_{\mathcal{W}}(\mathbf{w})\right] \mathbb{1}_{\mathcal{V}} \otimes \mathbb{1}_{\mathcal{W}} \\
& =-\left(q_{\mathcal{V}} \oplus q_{\mathcal{W}}\right)(\mathbf{v} \oplus \mathbf{w}) \mathbb{1}_{\mathcal{V}} \otimes \mathbb{1}_{\mathcal{W}} \tag{3.42}
\end{align*}
$$

i.e., $\varphi$ is a Clifford map and so extends to an algebra morphism:

$$
\tilde{\varphi}: C l\left(\mathcal{V} \oplus \mathcal{W}, q_{\mathcal{V}} \oplus q_{\mathcal{W}}\right) \rightarrow C l\left(\mathcal{V}, q_{\mathcal{V}}\right) \hat{\otimes} C l\left(\mathcal{W}, q_{\mathcal{W}}\right)
$$

Now consider $\eta: C l\left(\mathcal{V}, q_{\mathcal{V}}\right) \hat{\otimes} C l\left(\mathcal{W}, q_{\mathcal{W}}\right) \rightarrow C l\left(\mathcal{V} \oplus \mathcal{W}, q_{\mathcal{V}} \oplus q_{\mathcal{W}}\right)$, defined by:

$$
\eta(\mathbf{v} \otimes \mathbf{w})=\mathbf{v w}
$$

Then it's easy to prove that $\eta$ is an algebra morphism such that $\eta=\varphi^{-1}$, CQD.

Now we want to compute the Clifford algebras of $\left(\mathcal{V}=\mathbf{R}^{k}, \pm q_{e}\right)$, where $q_{e}(\mathbf{x})=\sum_{i=1}^{k} x_{i}^{2}$ is the euclidean quadratic form. But before, two useful theorems:

### 3.2 Pin and Spin groups

Consider again a non-degenerate quadratic space $(\mathcal{V}, q)$, and let $\mathbf{a} \in \mathcal{V}$ be a nonisotropic vector $(q(\mathbf{a}) \neq 0)$. Then the reflection $s_{\mathbf{a}}$ with respect to $\mathbf{a}^{\perp}$ is the orthogonal map given by:

$$
\begin{equation*}
s_{\mathbf{a}}(\mathbf{x})=\mathbf{x}-2 \frac{\beta(\mathbf{x}, \mathbf{a})}{q(\mathbf{a})} \mathbf{a} \tag{3.43}
\end{equation*}
$$

Let us write this equality in $C l(\mathcal{V}, q)$ :

$$
\begin{align*}
s_{\mathbf{a}}(\mathbf{x}) & =\mathbf{x}-2 \frac{\beta(\mathbf{x}, \mathbf{a})}{q(\mathbf{a})} \mathbf{a} \\
& =\mathbf{x}-(\mathbf{a x}+\mathbf{x a}) \frac{-\mathbf{a}}{q(\mathbf{a})} \\
& =\mathbf{x}-(\mathbf{a x}+\mathbf{x a}) a^{-1} \\
& =-\mathbf{a x a}^{-1} \tag{3.44}
\end{align*}
$$

By the theorem of Cartan-Dieudonné, every $f \in O(\mathcal{V}, q)$ can be written as a product of those reflections:
(i). in even number if $\operatorname{det} f=1$, say $g=s_{\mathbf{a}_{1}} s_{\mathbf{a}_{2}} \cdots s_{\mathbf{a}_{2 p}}$, so that in $C l(\mathcal{V}, q)$ :

$$
\begin{equation*}
f(\mathbf{x})=\left(\mathbf{a}_{1} \mathbf{a}_{2} \cdots \mathbf{a}_{2 p}\right) \mathbf{x}\left(\mathbf{a}_{1} \mathbf{a}_{2} \cdots \mathbf{a}_{2 p}\right)^{-1} \tag{3.45}
\end{equation*}
$$

(i). in odd number if $\operatorname{det} f=-1$, say $g=s_{\mathbf{a}_{1}} s_{\mathbf{a}_{2}} \cdots s_{\mathbf{a}_{2 p+1}}$, so that in $C l(\mathcal{V}, q)$ :

$$
\begin{equation*}
f(\mathbf{x})=-\left(\mathbf{a}_{1} \mathbf{a}_{2} \cdots \mathbf{a}_{2 p+1}\right) \mathbf{x}\left(\mathbf{a}_{1} \mathbf{a}_{2} \cdots \mathbf{a}_{2 p+1}\right)^{-1} \tag{3.46}
\end{equation*}
$$

As we know every $f \in O(\mathcal{V}, q)$ extends uniquely to an algebra morphism $\tilde{f}: C l(\mathcal{V}, q) \rightarrow$ $C l(\mathcal{V}, q)$. If $\operatorname{det} f=1$ then $\tilde{f}$ is an inner automorphism: $\tilde{f}(\mathbf{x})=h \mathbf{x} h^{-1}$, where $h$ is a product of an even number of nonisotropic vectors in $\mathcal{V}$, while if $\operatorname{det} f=-1$ then $\tilde{f}$ is the compose of the main involution $\alpha$ with an inner automorphism.

This lead us to consider the so called "Clifford group" $\Gamma(\mathcal{V}, q)$, of $(\mathcal{V}, q)$, as the group of the invertible elements $h \in C l(\mathcal{V}, q)$ such that:

$$
\alpha(h) \mathcal{V} h^{-1} \subseteq \mathcal{V}
$$

By the above discussion, $\Gamma(\mathcal{V}, q)$ contains all nonisotropic vectors in $\mathcal{V}$ as well all the elements of $C l(\mathcal{V}, q)$ that are products of nonisotropic vectors of $\mathcal{V}$.

Note that $\Gamma(\mathcal{V}, q)$ come with a ready-made homomorphism:

$$
\begin{equation*}
\widetilde{A d}: \Gamma(\mathcal{V}, q) \longrightarrow A u t(\mathcal{V}) \tag{3.47}
\end{equation*}
$$

defined by:

$$
\begin{equation*}
\widetilde{A d}: g \mapsto \widetilde{A d}_{g}(\mathbf{x}) \quad \stackrel{\text { def }}{=} \alpha(g) \mathbf{x} g^{-1} \quad g \in \Gamma(\mathcal{V}, q) \quad \mathbf{x} \in \mathcal{V} \tag{3.48}
\end{equation*}
$$

which is called the "Twisted Adjoint Representation" of $\Gamma(\mathcal{V}, q)$ on $\mathcal{V}$. This representation is nearly faithful:

Proposition 1 ([LM, prop. 2.4])... The kernel of $\widetilde{A d}: \Gamma(\mathcal{V}, q) \longrightarrow A u t(\mathcal{V})$ is $\mathbb{k}^{\times}$, the multiplicative group of nonzero scalar multiples of $\mathbb{1} \in C l_{k}$.

Consider now the "Norm mapping" $N: C l_{k} \rightarrow C l_{k}$ defined by:

$$
N(h)=h h^{*}
$$

where $h^{*}=\alpha\left(h^{t}\right)$ is the conjugate of $h$. Note that $N(\mathbf{x})=\mathbf{x}(-\mathbf{x})=-\mathbf{x}^{2}=q(\mathbf{x}) \mathbb{1}, \quad \forall \mathbf{x} \in \mathcal{V}$. Moreover we can prove (see ([LM, prop. 2.5])) that if $g \in \Gamma(\mathcal{V}, q)$ then $N(g) \in \mathbb{k}^{\times}$, and that:

$$
N: \Gamma(\mathcal{V}, q) \rightarrow \mathbb{k}^{\times}
$$

is an algebra homomorphism.
Proposition $2 \ldots$ For all $g \in \Gamma(\mathcal{V}, q)$, the transformations $\widetilde{A d}_{g}$ preserve the quadratic form q. So there is an homomorphism:

$$
\widetilde{A d}: \Gamma(\mathcal{V}, q) \longrightarrow O(\mathcal{V}, q)
$$

Proof...
Note that $N(\alpha(g))=N(g), \forall g \in \Gamma(\mathcal{V}, q)$, since $N(\alpha(g))=\alpha(g)(\alpha(g))^{*}=\alpha(g) g^{t}=\alpha(N(g))=$ $N(g)$. So if we consider the subset of all the nonisotropic vectors in $\mathcal{V}$ :

$$
\mathcal{V}^{\times}=\{\mathbf{x} \in \mathcal{V}: q(\mathbf{x}) \neq \mathbf{0}\}
$$

then for each $\mathbf{x} \in \mathcal{V}^{\times} \subset \Gamma(\mathcal{V}, q)$, we have that $N\left(\widetilde{\operatorname{Ad}}{ }_{g}(\mathbf{x})\right)=N\left(\alpha(g) \mathbf{x} g^{-1}\right)=N(\alpha(g)) N(\mathbf{x}) N\left(g^{-1}\right)=$ $N(g) N(g)^{-1} N(\mathbf{x})=N(\mathbf{x})$, and since $N(\mathbf{v})=q(\mathbf{v}), \forall \mathbf{v} \in \mathcal{V}$, we see that $\widetilde{A} d_{g}$ preserves all non-zero $q$-lengths. Applying $\widetilde{A d}_{g^{-1}}$ now shows that $\widetilde{A d}_{g}\left(\mathcal{V}^{\times}\right)=\mathcal{V}^{\times}$, and so $\widetilde{A d} d_{g}$ leaves also invariant the set of vectors with zero $q$-length. Thus $\widetilde{A d}_{g}$ is $q$-orthogonal, CQD.

Definition 3 ... We define the $\mathbf{P i n} \operatorname{group} \operatorname{Pin}(\mathcal{V}, q)$ of $(\mathcal{V}, q)$, as the subgroup of $\Gamma(\mathcal{V}, q)$ generated by all elements $\mathbf{v} \in \mathcal{V}$ such that $q(\mathbf{v})= \pm 1$ :

$$
\begin{equation*}
\operatorname{Pin}(\mathcal{V}, q) \stackrel{\text { def }}{=}\left\{\mathbf{v}_{1} \mathbf{v}_{2} \cdots \mathbf{v}_{r} \in \Gamma(\mathcal{V}, q): q\left(\mathbf{v}_{j}\right)= \pm 1 \quad \forall j\right\} \tag{3.49}
\end{equation*}
$$

The associated $\underline{\text { Spin group }}$ of $(\mathcal{V}, q)$ is defined by:

$$
\begin{equation*}
\operatorname{Spin}(\mathcal{V}, q) \stackrel{\text { def }}{=} \operatorname{Pin}(\mathcal{V}, q) \cap C l^{(0)}(\mathcal{V}, q) \tag{3.50}
\end{equation*}
$$

## Example ... $\operatorname{Spin}(4), S O(4)$

Recall that we can identify the euclidean space $\left(\mathbf{R}^{4}, q_{e}\right)$, where $q_{e}(\mathbf{x})=\|\mathbf{x}\|^{2}$ is the euclidean quadratic form, with the linear space $\mathbf{H}$ of real quaternions through the linear map:

$$
\begin{align*}
\mathbf{x}=\left(x^{0}, x^{1}, x^{2}, x^{3}\right)=\left(x^{0}, \overrightarrow{\mathbf{x}}\right) \in \mathbf{R}^{4} \mapsto \mathbf{X} & =x^{0} \mathbf{1}-i \overrightarrow{\mathbf{x}} \cdot \vec{\sigma} \\
& =x^{0} \mathbf{1}+x^{1} \mathbf{i}+x^{2} \mathbf{j}+x^{3} \mathbf{k} \\
& =\left[\begin{array}{cc}
x^{0}-i x^{3} & -x^{2}-i x^{1} \\
x^{2}-i x^{1} & x^{0}+i x^{3}
\end{array}\right] \\
& =\left[\begin{array}{cc}
u & v \\
-\bar{v} & \bar{u}
\end{array}\right] \tag{3.51}
\end{align*}
$$

with $u=x^{0}-i x^{3}, v=-\left(x^{2}+i x^{1}\right) \in \mathbf{C}$. In this form, the conjugate of $\mathbf{X} \in \mathbf{H}$ is $\mathbf{X}^{*}=\overline{\mathbf{X}}^{t}$, the norm of $\mathbf{X}$ is $Q(\mathbf{X})=\mathbf{X} \mathbf{X}^{*}=\mathbf{X} \overline{\mathbf{X}}^{t}=(\operatorname{det} \mathbf{X}) \mathbb{1}=\left(\left(x^{0}\right)^{2}+\left(x^{1}\right)^{2}+\left(x^{2}\right)^{2}+\left(x^{3}\right)^{2}\right) \mathbb{1}=\|\mathbf{x}\|^{2} \mathbb{1}$, and the real quaternions of unit norm form the group $S U(2)$.

Consider now the Clifford algebra $C l_{4,0} \equiv C l\left(\mathbf{R}^{4}, q_{e}\right)$. We know that $C l_{4,0}$ has real dimension $16=2^{4}$. Recall that $\left(\mathbf{R}^{4}, q_{e}\right)$ is linear isomorphic to $(\mathbf{H}, Q)$. The map $c: \mathbf{H} \rightarrow \mathbf{H}(2)$ defined by:

$$
c(h)=\left[\begin{array}{cc}
0 & h \\
-h^{*} & 0
\end{array}\right] \quad h \in \mathbf{H}
$$

where $\mathbf{H}(2)$ is the real algebra of quaternionic $(2 \times 2)$-matrices, is a Clifford map, since:

$$
c(h)^{2}=\left[\begin{array}{cc}
0 & h  \tag{3.52}\\
-h^{*} & 0
\end{array}\right]^{2}=\left[\begin{array}{cc}
-h h^{*} & 0 \\
0 & -h^{*} h
\end{array}\right]=-Q(h) \mathbb{1}
$$

Moreover since $\mathbf{H}(2)$ is generated as a real algebra of dimension 16 by the above matrices we see that:

$$
C l_{4,0}=\mathbf{H}(2)
$$

$\mathbf{R}^{4} \cong \mathbf{H}$ sits inside $C l_{4,0}=\mathbf{H}(2)$ through the canonical injection $c$ given by (3.52), and we identify $\mathbf{R}^{4}$ with $c\left(\mathbf{R}^{4}\right)$. In particular the images in $C l_{4,0}=\mathbf{H}(2)$, under $c$, of the elements $\mathbf{e}_{i}, i=$ $0,1,2,3$ of the canonical basis of $\mathbf{R}^{4}$ are the so called "Dirac $\gamma$-matrices":

$$
\gamma_{0}=c\left(\mathbf{e}_{0}\right)=\left[\begin{array}{cc}
0 & \mathbb{1}  \tag{3.53}\\
-\mathbb{1} & 0
\end{array}\right], \quad \gamma_{k}=c\left(\mathbf{e}_{k}\right)=\left[\begin{array}{cc}
0 & -i \sigma_{k} \\
i \sigma_{k} & 0
\end{array}\right] \quad k=1,2,3
$$

Now we know that the even subalgebra $C l_{4,0}^{(0)}$ is isomorphic to $C l_{3,0}=C l\left(\mathbf{R}^{3}, q_{e}\right)$ where $\mathbf{R}^{3}$ is the subspace of $\mathbf{R}^{4}$ orthogonal to $\mathbf{e}_{0}$. But $C l_{3,0}=\mathbf{H} \oplus \mathbf{H}$, as we have seen previously, and so $C l_{4,0}^{(0)}=\mathbf{H} \oplus \mathbf{H} \hookrightarrow \mathbf{H}(2)$ through the map:

$$
h \oplus h^{\prime} \rightarrow\left[\begin{array}{cc}
h & 0 \\
0 & h^{\prime}
\end{array}\right]
$$

Such an element $h \oplus h^{\prime} \in C l_{4,0}^{(0)}$ is invertible iff both $h$ and $h^{\prime} \in \mathbf{H}$ are. Moreover an invertible $h \oplus h^{\prime}$ is such that:

$$
A d_{h \oplus h^{\prime}} \mathbf{X} \in \mathbf{R}^{4} \quad \forall \mathbf{X} \in \mathbf{R}^{4} \cong c(\mathbf{H}) \hookrightarrow C L_{4,0}=\mathbf{H}(2)
$$

iff:

$$
\left[\begin{array}{cc}
h & 0 \\
0 & h^{\prime}
\end{array}\right]\left[\begin{array}{cc}
0 & \mathbf{X} \\
-\mathbf{X}^{*} & 0
\end{array}\right]\left[\begin{array}{cc}
h^{-1} & 0 \\
0 & h^{\prime-1}
\end{array}\right]=\left[\begin{array}{cc}
0 & h \mathbf{X} h^{\prime-1} \\
-h^{\prime} \mathbf{X}^{*} h^{-1} & 0
\end{array}\right] \in \mathbf{R}^{4}
$$

i.e.:

$$
-h^{\prime} \mathbf{X}^{*} h^{-1}=-\left(h \mathbf{X} h^{\prime-1}\right)^{*}
$$

which is equivalent to $h^{\prime} h^{\prime *} \mathbf{X}^{*}=\mathbf{X}^{*} h^{*} h$, i.e., $\left(\operatorname{det} h^{\prime}\right) \mathbf{X}^{*}=(\operatorname{det} h) \mathbf{X}^{*}, \forall \mathbf{X} \in \mathbf{R}^{4} . \operatorname{Thus} \operatorname{det} h^{\prime}=\operatorname{det} h$, and in particular we conclude that:

$$
\operatorname{Spin}(4)=\left\{h \oplus h^{\prime} \in C l_{4}^{0}=\mathbf{H} \oplus \mathbf{H}: \operatorname{det} h^{\prime}=\operatorname{det} h=1\right\} \cong S U(2) \times S U(2)
$$

The above computations show also that the adjoint representation is completelly determined by the action $\phi$ of $\operatorname{Spin}(4)=S U(2) \times S U(2)$ on $\mathbf{H} \cong \mathbf{R}^{4}$, given by:

$$
\phi\left(h_{1}, h_{2}\right) \mathbf{X}=h_{1} \mathbf{X} h_{2}^{-1} \quad h_{1}, h_{2} \in S U(2), \mathbf{X} \in \mathbf{H}
$$

Then $h_{1} \mathbf{X} h_{2}^{-1} \in \mathbf{H}$ and $\operatorname{det}\left(\phi\left(h_{1}, h_{2}\right) \mathbf{X}\right)=\operatorname{det}\left(h_{1} \mathbf{X} h_{2}^{-1}\right)=\operatorname{det} \mathbf{X}$ which give us a homomorphism:

$$
\varphi: S U(2) \times S U(2) \rightarrow S O(4)
$$

with kernel consists of the pairs $\left(h_{1}, h_{2}\right)$ such that:

$$
h_{1} \mathbf{X} h_{2}^{-1}=\mathbf{X} \quad \forall \mathbf{X} \in \mathbf{H}
$$

This implies that $h_{1}=h_{2}=\lambda \mathbb{1}$ and since $\lambda \mathbb{1} \in S U(2)$ we see that $\lambda^{2}=1$ and so $\operatorname{Ker} \varphi=$ $\{(\mathbb{1}, \mathbb{1}),(-\mathbb{1},-\mathbb{1})\}=\mathbf{Z}_{2}$.

Thus we have the identifications:

$$
\begin{equation*}
\operatorname{Spin}(4)=S U(2) \times S U(2) \tag{3.54}
\end{equation*}
$$

and:

$$
\begin{equation*}
S O(4)=S U(2) \times S U(2) / \mathbf{Z}_{2} \tag{3.55}
\end{equation*}
$$

### 3.3 Spin Representations

We will distinguish the two copies of $S U(2)$ in $\operatorname{Spin}(4)$, by writing:

$$
\operatorname{Spin}(4)=S U^{+}(2) \times S U^{-}(2)
$$

The representations of $\operatorname{Spin}(4)$ can be determined using this isomorphism. But first let us recall the representations of $S U(2)$ : the fundamental representation $D_{1 / 2}$, is $S U(2)$ acting on $\mathbf{C}^{2}$ in the usual way, and all the others irreducible representations are symmetric powers:

$$
D_{k / 2}=\operatorname{Sym}^{k} D_{1 / 2}
$$

with $k \in \mathbf{Z}^{+}$. We have that $\operatorname{dim}_{\mathbf{C}} D_{k / 2}=\operatorname{dim}_{\mathbf{C}} S y m^{k} D_{1 / 2}=k+1$, since we can identify this space with the space of homogeneous polynomials of degree $k$ in 2 variables.

Tensor products of this representations decompose according to Clebsh-Gordon formula:

$$
D_{k / 2} \otimes D_{l / 2}=D_{k+l / 2} \oplus D_{k+l-2 / 2} \oplus \cdots \oplus D_{|k-l| / 2}
$$

The spin representations $D_{1 / 2}^{ \pm}$of $\operatorname{Spin}(4)=S U^{+}(2) \times S U^{-}(2)$ are the representations obtained by projecting onto $S U^{ \pm}(2)$ and then applying $D_{1 / 2}$. So any irreducible $\operatorname{Spin}(4)$-module has the form:

$$
\begin{align*}
S^{k, l} & \equiv D_{k / 2}^{+} \otimes D_{l / 2}^{-} \\
& =\text {Sym }^{k} D_{1 / 2}^{+} \otimes \text { Sym }^{l} D_{1 / 2}^{-} \quad k, l \geq 0 \tag{3.56}
\end{align*}
$$

which has complex dimension $(k+1)(l+1)$ and factors through $S O(4)$ iff $k+l$ is even. In particular the basic $S O(4)$-module which is $\mathbf{R}^{4}$, must be equal to $S^{1,1}$, i.e.:

$$
\begin{align*}
\left(\mathbf{R}^{4}\right)^{\mathbf{C}} \cong S^{1,1} & =\mathbf{C}^{2}+\otimes \mathbf{C}^{2}{ }_{-} \\
& \equiv \mathcal{S}^{+} \oplus \mathcal{S}^{-} \tag{3.57}
\end{align*}
$$

The spin representations $D_{1 / 2}^{ \pm}$generate the representation ring of $\operatorname{Spin}(4)$.
We know that $\mathbf{C} l(4)=C l_{4} \otimes_{\mathbf{R}} \mathbf{C}=\mathbf{H}(2) \otimes_{\mathbf{R}} \mathbf{C}=\mathbf{C}(4)=\operatorname{End}\left(\mathbf{C}^{4}\right)$, the algebra of complex $(4 \times 4)$-matrices. The inclusion:

$$
\operatorname{Spin}(4) \subset \mathbf{C} l(4)=\operatorname{End}\left(\mathbf{C}^{4}\right)
$$

makes $\mathcal{S}=\mathbf{C}^{4}$ into a $\operatorname{Spin}(4)$-representation. Since the chirallity operator:

$$
\omega=\mathbf{e}_{1} \mathbf{e}_{2} \mathbf{e}_{3} \mathbf{e}_{4} \in C l(4)
$$

satisfies in this case:

$$
\omega^{2}=\mathbb{1}
$$

we see that $\mathcal{S}$ decomposes into the $\pm 1$ eigenspaces of $\omega$ :

$$
\begin{align*}
\mathcal{S}=\mathbf{C}^{4} & =\mathbf{C}^{2} \oplus \mathbf{C}^{2} \\
& =\mathcal{S}^{+} \oplus \mathcal{S}^{-} \tag{3.58}
\end{align*}
$$

with $\mathcal{S}^{ \pm}=(\mathbb{1}+\omega) \mathcal{S}$, called the spaces of $\pm$ Majorana spinors (see [LM], prop.5.10). Moreover, since $\omega$ commutes with all the elements in the even subalgebra $C l_{4}^{0}$, each of the subspaces $\mathcal{S}^{+}$and $\mathcal{S}^{-}$are invariant under $C l_{4}^{0}$, i.e.:

$$
C l_{4}^{0}=\operatorname{End}\left(\mathcal{S}^{+}\right) \oplus \operatorname{End}\left(\mathcal{S}^{-}\right)
$$

as $\operatorname{Spin}(4)$-modules. Moreover each $\mathbf{x} \in \mathbf{R}^{4} \subset \mathbf{C} l_{4}$ gives isomorphisms through Clifford multiplication:

$$
\begin{equation*}
\mathrm{x}: \mathcal{S}^{-} \rightarrow \mathcal{S}^{+} \quad \mathrm{x}: \mathcal{S}_{+} \rightarrow \mathcal{S}^{-} \tag{3.59}
\end{equation*}
$$

which we denote by $\mathbf{x}: \psi \mapsto \mathbf{x} \cdot \psi, \quad \mathbf{x} \in \mathbf{R}^{4}, \psi \in \mathcal{S}^{ \pm}$.
In fact, the representations $\mathcal{S}^{ \pm}$are exactly the 2-dimensional complex spin representations $D_{1 / 2}^{ \pm}$ mentioned above.

Now let us see what happens at the Lie algebra level. We know that $\operatorname{spin}(4)=\operatorname{Lie}(\operatorname{Spin}(4))$ is the Lie subalgebra of $\left(C l_{4},[],\right)$ generated by $\gamma_{i} \gamma_{j}, i<j$, which is of course isomorphic to $\wedge^{2} \mathbf{R}^{4}$ (see [LM], prop.6.1):

$$
\operatorname{spin}(4)=\wedge^{2} \mathbf{R}^{4}=\operatorname{span}_{\mathbf{R}}\left\{\gamma_{i} \gamma_{j}\right\}_{i<j}
$$

through the (non canonical) linear map defined by:

$$
\begin{equation*}
\mathbf{e}_{i} \wedge \mathbf{e}_{j} \mapsto \iota\left(\mathbf{e}_{i}\right) \iota\left(\mathbf{e}_{j}\right)=\gamma_{i} \gamma_{j} \quad i<j \tag{3.60}
\end{equation*}
$$

Meanwhile, the Lie algebra so(4) is:

$$
\text { so }(4)=\left\{A: \mathbf{R}^{4} \rightarrow \mathbf{R}^{4}: \mathrm{A} \text { is linear and skew symmetric }\right\}
$$

and there exists a natural isomorphism $\wedge^{2} \mathbf{R}^{4} \cong s o(4)$, induced by associating to a pair of vectors $\mathbf{v}, \mathbf{w} \in \mathbf{R}^{4}$ the skew symmetric endomorphism " $\mathbf{v} \wedge \mathbf{w}$ " defined by:

$$
\begin{equation*}
(\mathbf{v} \wedge \mathbf{w})(\mathrm{x})=<\mathbf{v}, \mathbf{x}>\mathbf{w}-<\mathbf{w}, \mathbf{x}>\mathbf{v} \tag{3.61}
\end{equation*}
$$

In particular $\mathbf{e}_{i} \wedge \mathbf{e}_{j}$, for $i<j$, corresponds to the elementary skew-symmetric matrix $E_{i j}$, with -1 in $(i, j)$-entry, 1 in ( $j, i$-entry and all others 0 . These matrices form the standard basis of so(4). These together with (3.60) shows that:

$$
\begin{equation*}
\operatorname{spin}(4)=\wedge^{2} \mathbf{R}^{4}=\operatorname{so}(4) \tag{3.62}
\end{equation*}
$$

Note however that the Lie algebra isomorphism:

$$
\Psi: \operatorname{spin}(4) \longrightarrow \operatorname{so}(4)
$$

induced by the adjoint representation $A d: \operatorname{Spin}(4) \rightarrow S O(4)$ is given explicitly on the basis elements $\left\{\gamma_{i} \gamma_{j}\right\}_{i<j}$ by (see [LM], prop. 6.2):

$$
\begin{equation*}
\Psi\left(\gamma_{i} \gamma_{j}\right)=2 \mathbf{e}_{i} \wedge \mathbf{e}_{j} \tag{3.63}
\end{equation*}
$$

and consequently for $\mathbf{v}, \mathbf{w} \in \mathbf{R}^{4}$ :

$$
\begin{equation*}
\Psi^{-1}(\mathbf{v} \wedge \mathbf{w})=\frac{1}{4}[\mathbf{v}, \mathbf{w}] \tag{3.64}
\end{equation*}
$$

Now recall that the Hodge star operator $*: \wedge^{2}=\wedge^{2} \mathbf{R}^{4} \rightarrow \wedge^{2}$ defined by:

$$
\alpha \wedge * \beta=(\alpha, \beta) \omega \quad \alpha, \beta \in \mathbf{R}^{4}
$$

verifies $*^{2}=1$ and so we can decompose $\wedge^{2}=\wedge^{2} \mathbf{R}^{4}$ in self dual and anti-self-dual bivectors:

$$
\wedge^{2}=\wedge_{+}^{2} \oplus \wedge_{-}^{2}
$$

with each of the subspaces $\wedge_{ \pm}^{2}=\frac{1}{2}(1 \pm *) \wedge^{2}$ being (through (3.61)) a 3-dimensional space of skew symmetric matrices which we identify to $s o(3)=s u(2)$. The basis for $\wedge_{ \pm}^{2}$ are respectivelly:

$$
\left\{\mathbf{e}_{1} \wedge \mathbf{e}_{2}+\mathbf{e}_{3} \wedge \mathbf{e}_{4}, \mathbf{e}_{1} \wedge \mathbf{e}_{3}+\mathbf{e}_{4} \wedge \mathbf{e}_{2}, \mathbf{e}_{1} \wedge \mathbf{e}_{4}-\mathbf{e}_{2} \wedge \mathbf{e}_{3}\right\}
$$

and:

$$
\left\{\mathbf{e}_{1} \wedge \mathbf{e}_{2}-\mathbf{e}_{3} \wedge \mathbf{e}_{4}, \mathbf{e}_{1} \wedge \mathbf{e}_{3}-\mathbf{e}_{4} \wedge \mathbf{e}_{2}, \mathbf{e}_{1} \wedge \mathbf{e}_{4}-\mathbf{e}_{2} \wedge \mathbf{e}_{3}\right\}
$$

So we have the following identifications:

$$
\begin{align*}
\operatorname{spin}(4) & =\operatorname{so}(4) \\
& =\wedge^{2} \\
& =\wedge_{+}^{2} \oplus \wedge_{-}^{2} \\
& =s u(2) \oplus \operatorname{su}(2) \tag{3.65}
\end{align*}
$$

Through (3.64) the action of an elementary transformation $\mathbf{v} \wedge \mathbf{w} \in \operatorname{so}(4)=\wedge^{2}$ on the spinor space $\mathcal{S}$ is given by $\frac{1}{4}[\mathbf{v}, \mathbf{w}]$. where $\cdot$ is Clifford module multiplication on $\mathcal{S}$. In particular we can prove that:

$$
\left(\wedge_{ \pm}^{2}\right)^{\mathbf{C}}=\left[\operatorname{Hom}\left(\mathcal{S}^{ \pm}, \mathcal{S}^{ \pm}\right)\right]^{o}
$$

where.${ }^{o}$ denotes the component of traceless matrices. The real parts $\wedge_{ \pm}^{2}$ consists of traceless skew-hermitian of $\mathcal{S}^{ \pm} \cong \mathbf{C}^{2}$.

Moreover, since $\mathcal{S}^{+} \cong\left(\mathcal{S}^{+}\right)^{*}$ symplectically, we also have that:

$$
\begin{equation*}
\left(\wedge_{+}^{2}\right)^{\mathbf{C}}=\text { Sym }^{2} \mathcal{S}^{+} \tag{3.66}
\end{equation*}
$$

## 3.4 $U(2)$, spinors and almost complex structures

If we fix a nonzero spinor $\phi \in \mathcal{S}^{+}$, then this gives rise to a real isomorphism $\mathbf{R}^{4} \cong \mathcal{S}^{-}=\mathbf{C}^{2}$, given by Clifford multiplication: $\mathbf{x} \mapsto \mathbf{x} \cdot \phi$, and so identifies $\mathbf{R}^{4}$ with a complex vector space, i.e., furnishes $\mathbf{R}^{4}$ with a (almost) complex structure $J_{\phi} \in \operatorname{End}\left(\mathbf{R}^{4}\right)$ wich corresponds with the multiplication by $i$ in the cited identification $\mathbf{R}^{4} \cong \mathbf{C}^{2}$ :

$$
J_{\phi} \mathbf{x} \cdot \phi=i(\mathbf{x} \cdot \phi) \quad \mathbf{x} \in \mathbf{R}^{4}
$$

This $J_{\phi}$ is compatible with the metric (is ortoghonal) and orientation. Moreover, multiplying $\phi \in \mathcal{S}^{+}=\mathbf{C}^{2}$ by a nonzero scalar $\lambda \in \mathbf{C}^{*}$ defines the same complex structure: $J_{\lambda \phi}=J_{\phi}$. Thus the projective space:

$$
P\left(\mathcal{S}^{+}\right) \cong \mathbf{C} P(1)
$$

parametrizes a set of compatible complex structures in $\mathbf{R}^{4}$.

The subgroup of $\operatorname{Spin}(4)=S U(2) \times S U(2)$ which leaves fixed $\phi$ up to a scalar multiple, is $S^{1} \times S U(2)$, the double covering of $U(2) \subset S O(4)$. Hence the projective space $P\left(\mathcal{S}^{+}\right) \cong \mathbf{C} P(1)$ is naturally isomorphic to $S O(4) / U(2)$, the space of all complex structures compatible with the metric and orientation.

There exists a dual way of looking at this, where we take not the Clifford multiplication map $\mathbf{R}^{4} \times \mathcal{S}^{+} \rightarrow \mathcal{S}^{-}$but its adjoint:

$$
\begin{equation*}
\Pi: \mathcal{S}^{-} \longrightarrow \mathbf{R}^{4} \times \mathcal{S}^{+} \tag{3.67}
\end{equation*}
$$

defined by:

$$
\begin{equation*}
\Pi: \psi \mapsto \sum_{i} \mathbf{e}_{i} \cdot \psi \otimes \mathbf{e}_{i} \tag{3.68}
\end{equation*}
$$

Now, if we are given any $\phi \in \mathcal{S}^{+}$, we get a map $\Pi_{\phi}: \mathcal{S}^{-} \rightarrow\left(\mathbf{R}^{4}\right)^{\mathbf{C}}=\mathbf{C}^{4}$ given by:

$$
\begin{equation*}
\Pi_{\phi}: \psi \mapsto \sum_{i} \epsilon\left(\mathbf{e}_{i} \cdot \psi, \phi\right) \mathbf{e}_{i} \tag{3.69}
\end{equation*}
$$

where $\epsilon$ is the sympletic form on $\mathcal{S}^{+}=\mathbf{C}^{2}$. The image $\Pi_{\phi}\left(\mathcal{S}^{-}\right)$in $\mathbf{C}^{4}$ is the subspace of holomorphic vectors $T^{(1,0)}$ which equivalently defines the complex structure.

## $3.5 \operatorname{Spin}^{c}(4)$

All the preceding discussion can be extended to the complex case. We define the main involution $\alpha$ and the transposition ()$^{t}$ on $C l_{4} \otimes_{\mathbf{R}} \mathbf{C}=\mathbf{H}(2) \otimes_{\mathbf{R}} \mathbf{C}=\mathbf{C}(4)$, the algebra of complex (4×4)-matrices, by:

$$
\begin{align*}
\alpha(\varphi \otimes z) & =\alpha(\varphi) \otimes z \\
(\varphi \otimes z)^{t} & =\varphi^{t} \otimes \bar{z} \quad \varphi \otimes z \in C l_{4} \otimes \mathbf{C} \tag{3.70}
\end{align*}
$$

and we define $N^{c}(\varphi \otimes z)=N(\varphi)|z|^{2}, \quad \Phi \in C l_{k} \otimes_{\mathbf{R}} \mathbf{C}$.

## Definition $4 \ldots$

We define $\Gamma_{4}^{c}$ as the subgroup of all invertible elements $\Phi=\varphi \otimes z \in C l_{4} \otimes_{\mathbf{R}} \mathbf{C}$, for which:

$$
\mathbf{x} \in \mathbf{R}^{4} \Longrightarrow \widetilde{A} d_{\Phi}(\mathbf{x}) \equiv \alpha(\Phi) \mathbf{x} \Phi^{-1} \in \mathbf{R}^{4}
$$

Theorem $6 \ldots$ ([ABS], prop. 3.17)
Let Pin $^{c}(4)$ be the kernel of $N^{c}: \Gamma_{4}^{c} \rightarrow \mathbf{C}^{*}$. Then we have an exact sequence:

$$
\mathbb{1} \rightarrow U(1) \rightarrow \operatorname{Pin}^{c}(4) \xrightarrow{\widetilde{A d}} O(4) \rightarrow \mathbb{1}
$$

where $U(1)=\left\{\mathbb{1} \otimes z \in C l_{4} \otimes \mathbf{C}:|z|=1\right\}$. In particular we have a natural isomorphism:

$$
\begin{equation*}
\operatorname{Pin}^{c}(4) \cong \operatorname{Pin}(4) \times_{\mathbf{Z}_{2}} U(1) \cong \operatorname{Pin}^{c}(4) \tag{3.71}
\end{equation*}
$$

where $\mathbf{Z}_{2}$ acts on $\operatorname{Pin}(4)$ and $U(1)$ as $\pm 1$.

## Definition 5 ...

We define the group $\operatorname{Spin}^{c}(4)$ as the inverse image of $S O(4)$ under the homomorphism $\operatorname{Pin}^{c}(4) \rightarrow$ $O(4)$ of the previous theorem. It follows that:

$$
\begin{align*}
\operatorname{Spin}^{c}(4) & \cong \operatorname{Spin}(4) \times \mathbf{Z}_{2} U(1) \\
& =(S U(2) \times S U(2)) \times_{\mathbf{Z}_{2}} U(1) \tag{3.72}
\end{align*}
$$

The group $\operatorname{Spin}^{c}(4)$ is usefull to understand the relation between spinors and complex structures. In fact a given $U(2)$-PFbundle over a 4 -manifold is an $S O(4)$-PFbundle under the natural embedding:

$$
\iota: U(2) \hookrightarrow S O(4)
$$

However, this mapping may not lift to $\operatorname{Spin}(4)$. Thus the existence of a complex structure on a bundle of rank 4 does not necessarily yield a Spin-bundle. However it does yield a $S^{\text {Sin }}{ }^{c}$-structure, a less restrictive requirement!

In fact the homomorphism:

$$
l: U(2) \rightarrow S O(4) \times U(1)
$$

defined by:

$$
l(T)=\iota(T) \times \operatorname{det} T
$$

does lift to $\operatorname{Spin}^{c}(4)$ : explicitly, the lifted map $\tilde{l}: U(2) \rightarrow \operatorname{Spin}^{c}(4)$ is given as follows. Let $T \in U(2)$ be expressed relative to an orthonormal basis $\left\{\mathbf{e}_{1}, \mathbf{e}_{2}\right\}$ of $\mathbf{C}^{2}$ by the diagonal matrix:

$$
T=\left[\begin{array}{cc}
e^{i \theta_{1}} & 0 \\
0 & e^{i \theta_{2}}
\end{array}\right]
$$

Let $\left\{\mathbf{e}_{1}, i \mathbf{e}_{1}, \mathbf{e}_{2}, i \mathbf{e}_{2}\right\}$ the corresponding basis of $\mathbf{R}^{4}$. Then:

$$
\tilde{l}(T)=\left(\cos \frac{\theta_{1}}{2}+\sin \frac{\theta_{1}}{2} \cdot \mathbf{e}_{1} i \mathbf{e}_{1}\right)\left(\cos \frac{\theta_{2}}{2}+\sin \frac{\theta_{2}}{2} \cdot \mathbf{e}_{2} \mathbf{e}_{2}\right) \times e^{\frac{i\left(\theta_{1}+\theta_{2}\right)}{2}}
$$

Thus any $U(2)$-frame bundle on a 4 -manifold $M$ induces a $\operatorname{Spin}^{c}(4)$-structure on $M$. In certain cases we shall be able to see that this $\operatorname{Spin}^{c}(4)$-structure reduces to a $\operatorname{Spin}(4)$-structure on certain real submanifolds of $M$. We can prove that:

## Theorem 7 ...

If $H^{2}(M, \mathbf{Z})=0$ then any $\operatorname{Spin}^{c}(4)$-bundle can be reduced to Spin(4)-bundle over $M$.

## Chiral Operator. Self Duality

Definition $6 \ldots$ Choose an orientation for $\mathbf{R}_{r, s}$ and let $\left\{\mathbf{e}_{1}, \cdots, \mathbf{e}_{n}\right\}$ a positively oriented $q$ orthonormal basis $(n=r+s)$. We define the associated "Volume element" by:

$$
\begin{equation*}
\omega \stackrel{\text { def }}{=} \mathbf{e}_{1} \ldots \mathbf{e}_{n} \in C l_{r, s} \tag{3.73}
\end{equation*}
$$

It's easy to see that $\omega$ doesn't depend of the choice of the positively oriented $q$-orthonormal basis. Moreover, we have that:

$$
\omega^{2}=\left\{\begin{array}{lll}
(-1)^{s} \mathbb{1} & \text { if } & n \equiv 0,3(\bmod 4)  \tag{3.74}\\
(-1)^{s+1} \mathbb{1} & \text { if } & n \equiv 1,2(\bmod 4)
\end{array}\right.
$$

and:

$$
\begin{equation*}
\mathbf{x} \omega=(-1)^{n-1} \omega \mathbf{x} \quad \forall \mathbf{x} \in \mathbf{R}^{n} \tag{3.75}
\end{equation*}
$$

In particular, if $n$ is odd, then $\omega$ is central, while if $n$ is even, then:

$$
\begin{equation*}
h \omega=\omega \alpha(h) \quad \forall h \in C l_{r, s} \tag{3.76}
\end{equation*}
$$

i.e., $\omega$ super-commutes with $h$. If $\rho: C l_{r, s} \rightarrow E n d_{\mathbf{K}}(\mathcal{W})$ is a $\mathbf{K}$-representation, then $\Omega \stackrel{\text { def }}{=} \rho(\omega)$ is called the associated "Chiral operator".

Definition $7 \ldots$ Assume that $\omega^{2}=\mathbb{1}$, in $C l_{r, s}$. Then an element $h \in C l_{r, s}$ is called "self-dual" if $\omega h=h$, and it's called "anti-self-dual" if $\omega h=-h$

If we assume that $\omega^{2}=\mathbb{1}$ and $n$ odd, then $\omega$ is central, and we have a decomposition of $C l_{r, s}$ in a direct sum:

$$
\begin{equation*}
C l_{r, s}=C l_{r, s}^{+} \oplus C l_{r, s}^{-} \tag{3.77}
\end{equation*}
$$

of isomorphic (self-dual and anti-self-dual) subalgebras:

$$
C l_{r, s}^{ \pm} \stackrel{\text { def }}{=}\left\{h \in C l_{r, s}: \omega h= \pm h\right\}=\frac{\mathbb{1} \pm \omega}{2} C l_{r, s}
$$

Moreover $\alpha\left(C l_{r, s}^{ \pm}\right)=C l_{r, s}^{\mp}$.
Table 1... Clifford Algebras $C L_{r, s}$. In each case $N$ is computed knowing that $r+s=n$ and the real dimension of $C L_{r, s}$ is $2^{n}$ :

| $r-s(\bmod 8)$ | $C l_{r, s}$ |
| :--- | :--- |
| 0,6 | $\mathbf{R}(N)$ |
| 2,4 | $\mathbf{H}(N)$ |
| 1,5 | $\mathbf{C}(N)$ |
| 3 | $\mathbf{H}(N) \oplus \mathbf{H}(N)$ |
| 7 | $\mathbf{R}(N) \oplus \mathbf{R}(N)$ |

Table 2... The even part $C L_{r, s}^{(0)}$ of the Clifford Algebras $C L_{r, s}$. In each case $N$ is computed knowing that $r+s=n$ and the real dimension of $C L_{r, s}^{(0)}$ is $2^{n-1}$ :

| $r-s(\bmod 8)$ | $C l_{r, s}^{(0)}$ |
| :--- | :--- |
| 0 | $\mathbf{R}(N) \oplus \mathbf{R}(N)$ |
| 1,7 | $\mathbf{R}(N)$ |
| 3,5 | $\mathbf{H}(N)$ |
| 2,6 | $\mathbf{C}(N)$ |
| 4 | $\mathbf{H}(N) \oplus \mathbf{H}(N)$ |

## Example ... ...

$$
\begin{array}{ll}
C l_{2,0}^{(0)}=C l_{0,2}^{(0)}=\mathbf{C} & C l_{1,1}^{(0)}=\mathbf{R} \oplus \mathbf{R} \\
C l_{3,1}^{(0)}=C l_{1,3}^{(0)}=\mathbf{C}(2) & C l_{4,0}^{(0)}=C l_{0,4}^{(0)}=\mathbf{H} \oplus \mathbf{H} \quad C l_{2,2}^{(0)}=\mathbf{R}(2) \oplus \mathbf{R}(2)
\end{array}
$$

Table 3... Decomposition in self-dual, anti-self-dual parts

| $r-s \quad(\bmod 8)$ | $C l_{r, s}^{(0)}$ |
| :--- | :--- |
| 0 | $\mathbf{R}(N) \oplus \mathbf{R}(N)$ |
| 1,7 | $\mathbf{R}(N)$ |
| 3,5 | $\mathbf{H}(N)$ |
| 2,6 | $\mathbf{C}(N)$ |
| 4 | $\mathbf{H}(N) \oplus \mathbf{H}(N)$ |

Definition $8 \ldots A$ "Pinnor inner product" $\epsilon$ is an inner product on the pinor space $\mathcal{P}_{r, s}$ with the property that the adjoint with respect to $\epsilon$ is the conjugation involution on $C l_{r, s}$, i.e.:

$$
\begin{equation*}
\epsilon(h \cdot \phi, \psi)=\epsilon\left(\phi, h^{*} \cdot \psi\right) \quad h \in C l_{r, s} \quad \phi, \psi \in \mathcal{P}_{r, s} \tag{3.78}
\end{equation*}
$$

In particular $\epsilon(\mathbf{x} \cdot \phi, \psi)=\epsilon(\phi,-\mathbf{x} \cdot \psi), \forall \mathbf{x} \in \mathcal{V}$. We can prove that there always exists such a inner product which is unique up to a change of scale.

Now we define a symmetric bilinear $\mathcal{V}$-valued mapping on $\mathcal{S}_{r, s}$ :

$$
\{,\}: \mathcal{S}_{r, s} \otimes \mathcal{S}_{r, s} \longrightarrow \mathcal{V}
$$

by defining $\{\phi, \psi\} \in \mathcal{V}$ as the unique vector in $\mathcal{V}$ such that its inner product with any $\mathbf{x} \in \mathcal{V}$ is equal to $\epsilon(\mathbf{x} \cdot \phi, \psi)$ :

$$
\begin{equation*}
<\{\phi, \psi\}, \mathbf{x}>\stackrel{\text { def }}{=} \epsilon(\mathbf{x} \cdot \phi, \psi) \quad \forall \mathbf{x} \in \mathcal{V} \tag{3.79}
\end{equation*}
$$

We can prove that $\{$,$\} is in fact symmetric:$

$$
\begin{array}{rlr}
<\{\phi, \psi\}, \mathbf{x}> & =\epsilon(\mathbf{x} \cdot \phi, \psi) & \\
& =\epsilon(\phi,-\mathbf{x} \cdot \psi) & \\
& =\epsilon(\mathbf{x} \cdot \psi, \phi) & \text { since } \epsilon \text { is skew } \\
& =<\{\psi, \phi\}, \mathbf{x}> & \forall \mathbf{x} \in \mathcal{V}
\end{array}
$$

To construct Lie superalgebras $\mathfrak{G}=\mathfrak{g}_{0} \oplus \mathfrak{g}_{1}$, wih the even part $\mathfrak{g}_{0}=\mathfrak{s p i n}_{r, s} \oslash \mathcal{V}$, the semi-direct sum of the Lie algebra of $S p i n_{r, s}$ with its fundamental representation $\mathcal{V} \cong \mathbf{R}^{r+s}$, we choose a spinor space which is the carrier of a representation of $\mathfrak{s p i n}_{r, s}$ and define the anticommutator of two pinors by the bove formula. It remains to prove that:

$$
\begin{equation*}
\Lambda \cdot\{\phi, \psi\}=\{\Lambda \cdot \phi, \psi\}+\{\phi, \Lambda \cdot \psi\} \quad \forall \Lambda \in \mathfrak{s p i n}_{r, s}, \quad \forall \phi, \psi \in \mathcal{S} \tag{3.80}
\end{equation*}
$$


[^0]:    ${ }^{1}$ Esta é uma versão provisória, incompleta, para uso exclusivo nas sessões de trabalho do TQFT club

